

Precise Scheduling of Mixed-Criticality Tasks by Varying Processor Speed

Ashikahmed Bhuiyan^{1*}, **Zhishan Guo**¹, Sai Sruti², and Kecheng Yang³

¹University of Central Florida, ²Missouri University of Science & Technology,
³Texas Tech University,

* Alphabetically ordered by last names

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Problem and Motivation

- Traditional MC task model

LO-criticality task

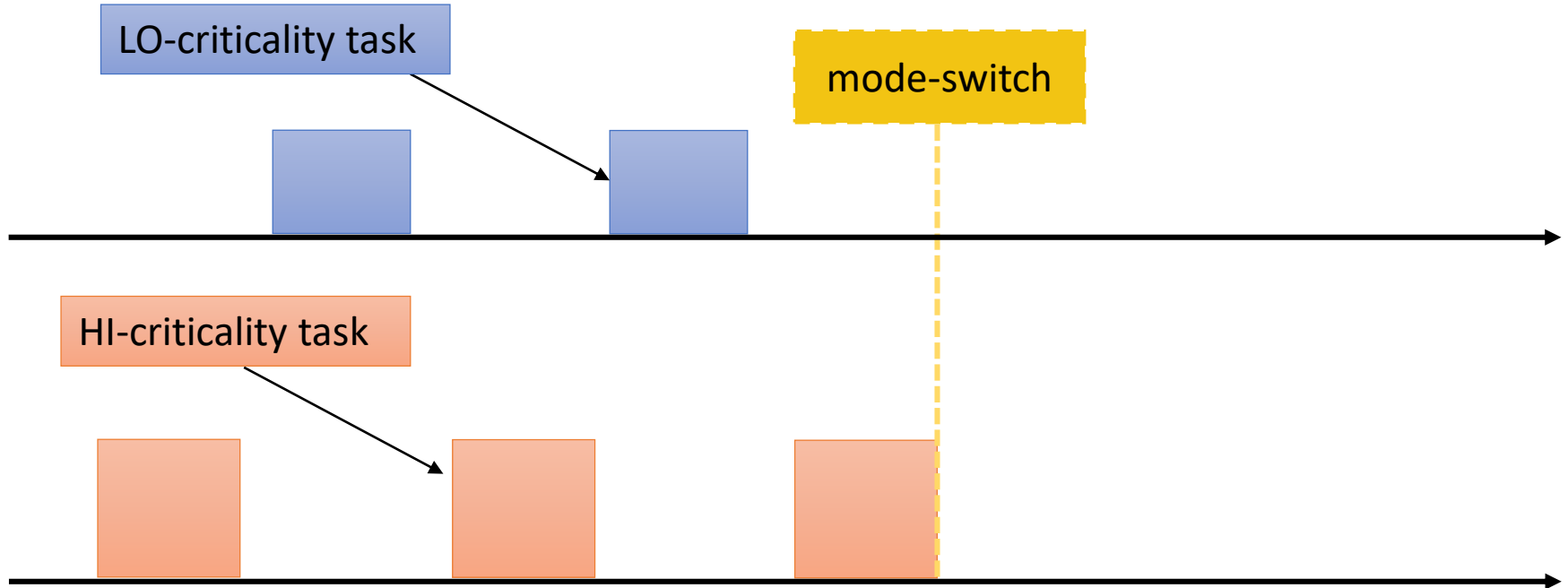


HI-criticality task



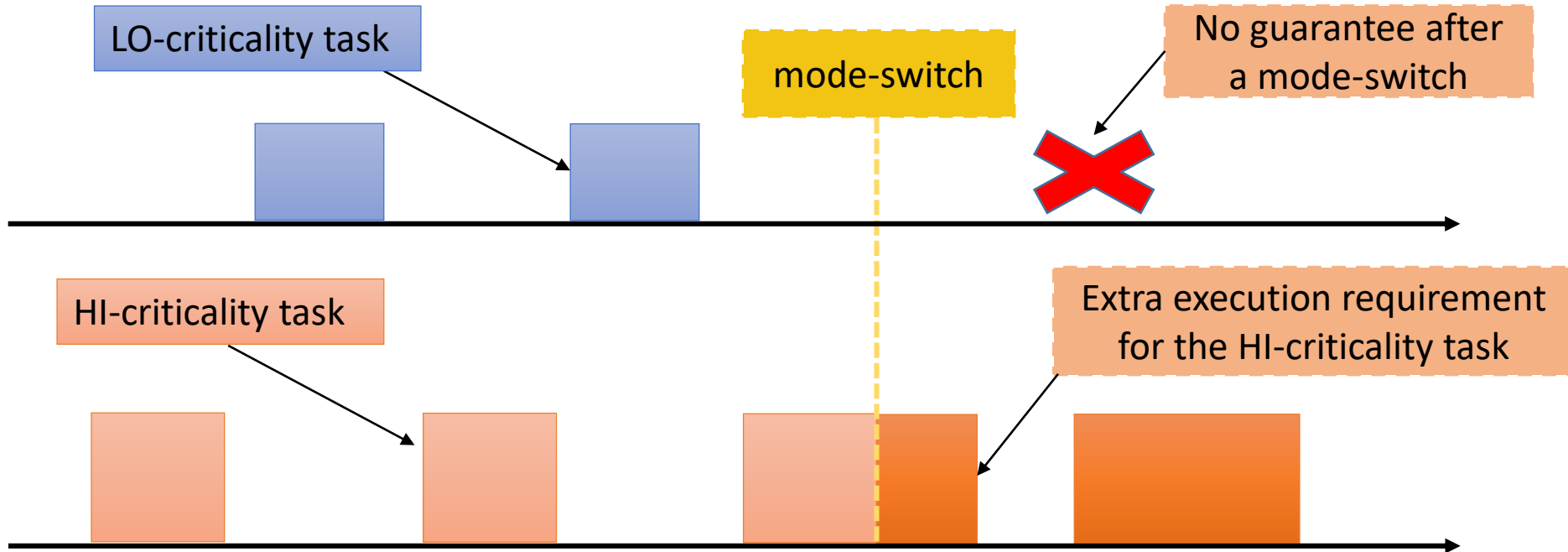
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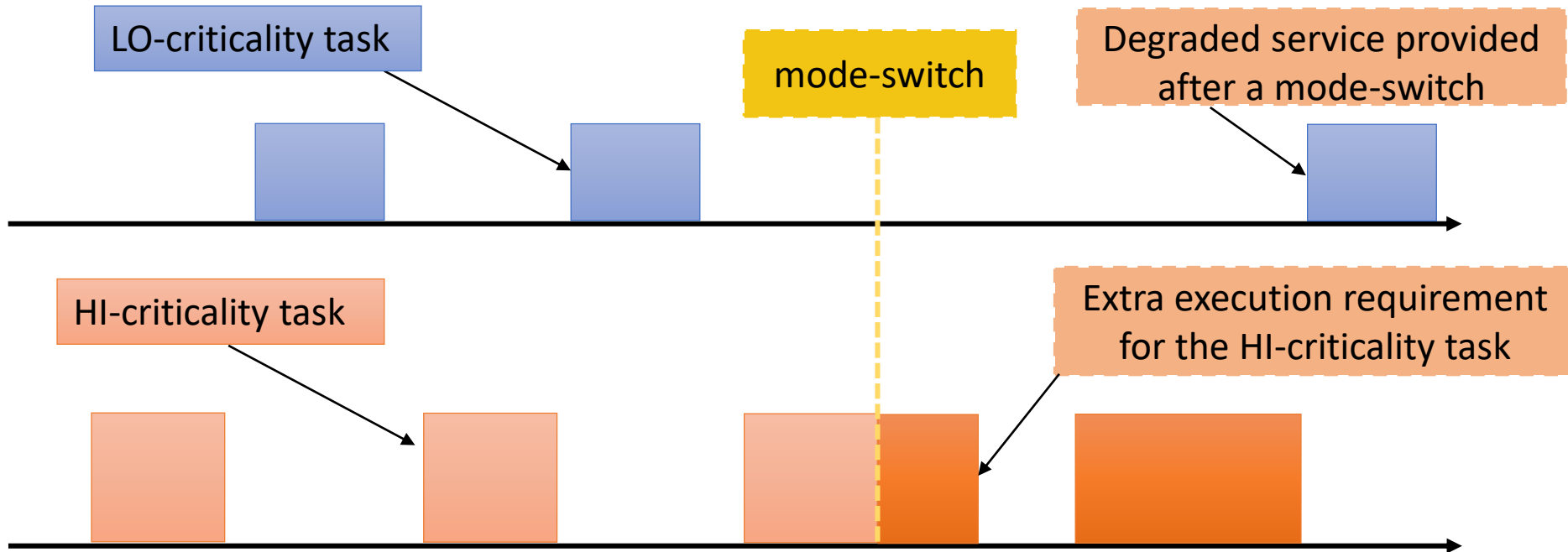
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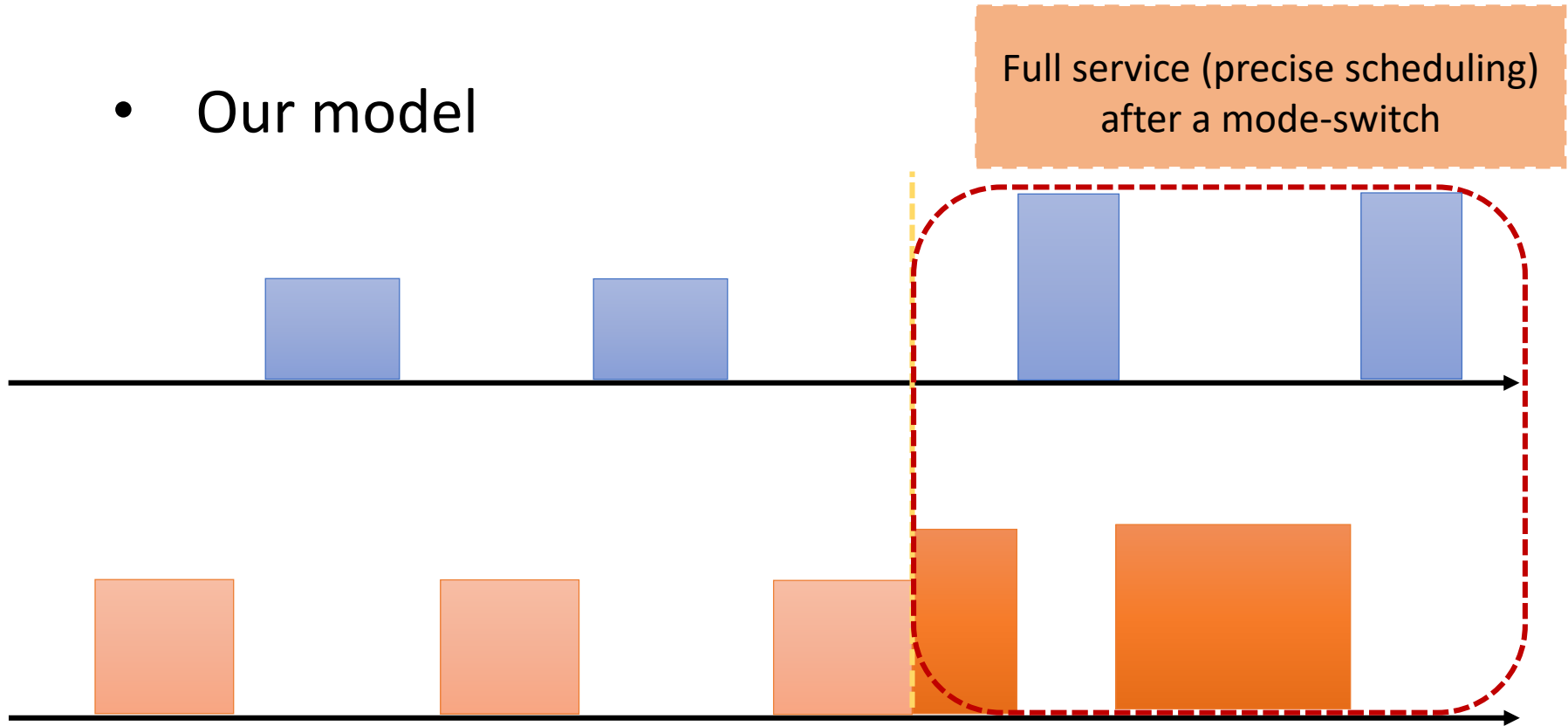
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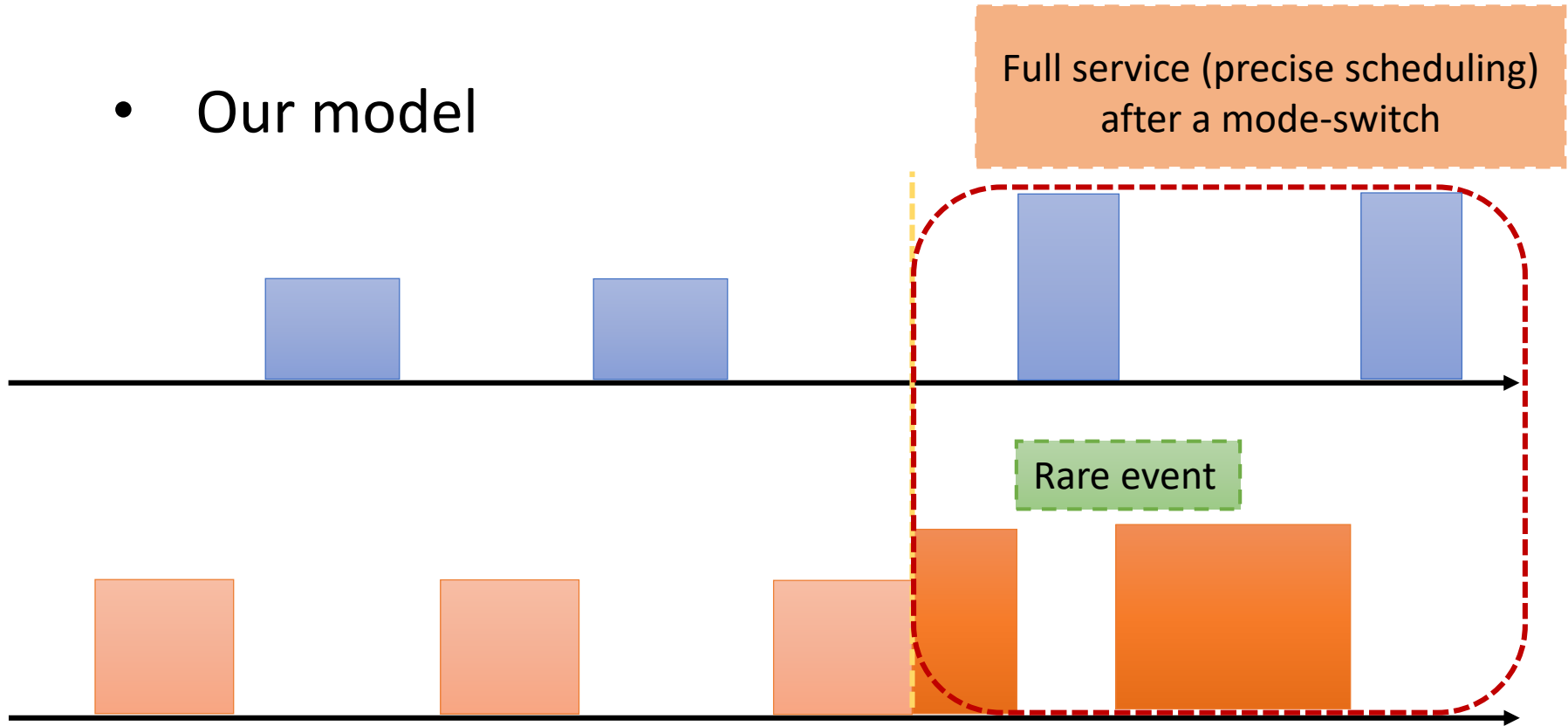
Problem and Motivation

- Our model



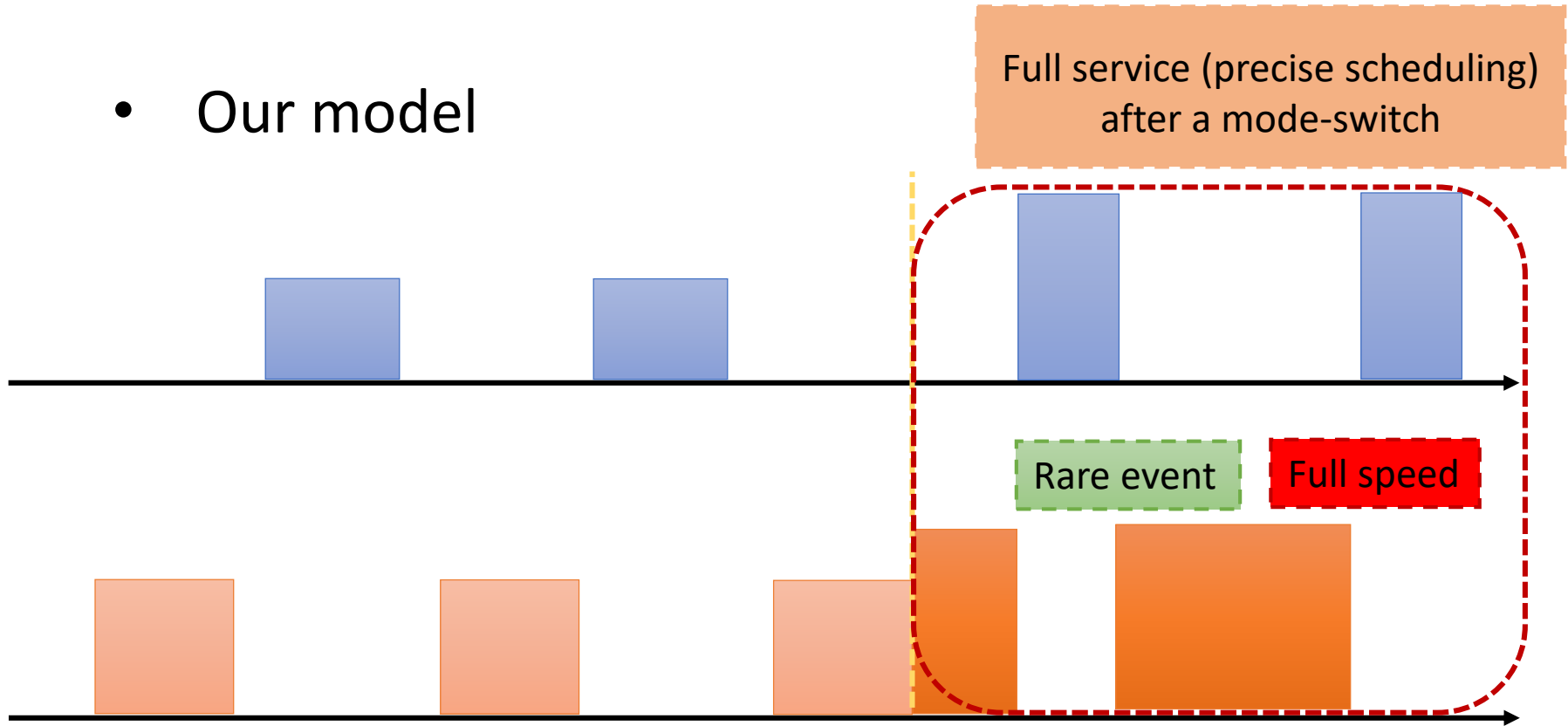
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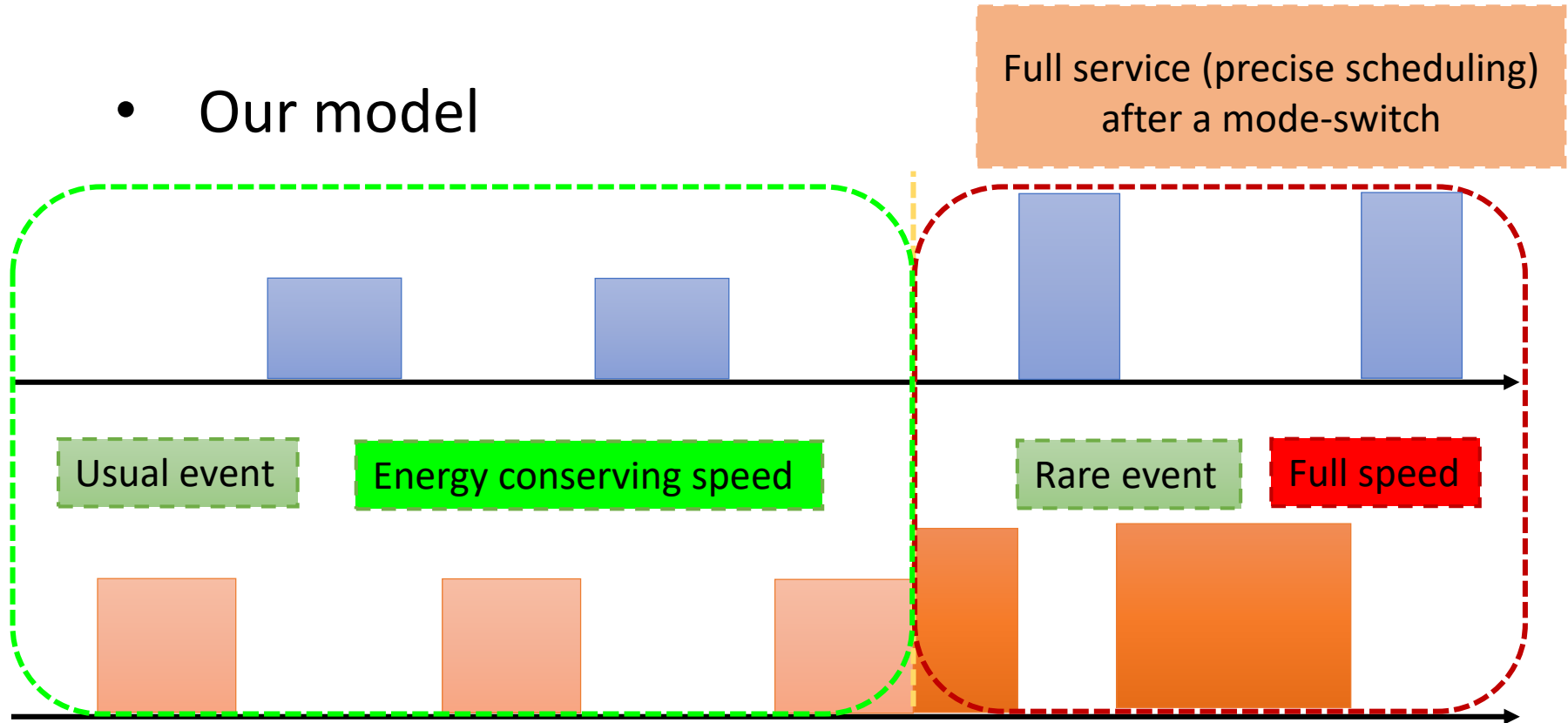
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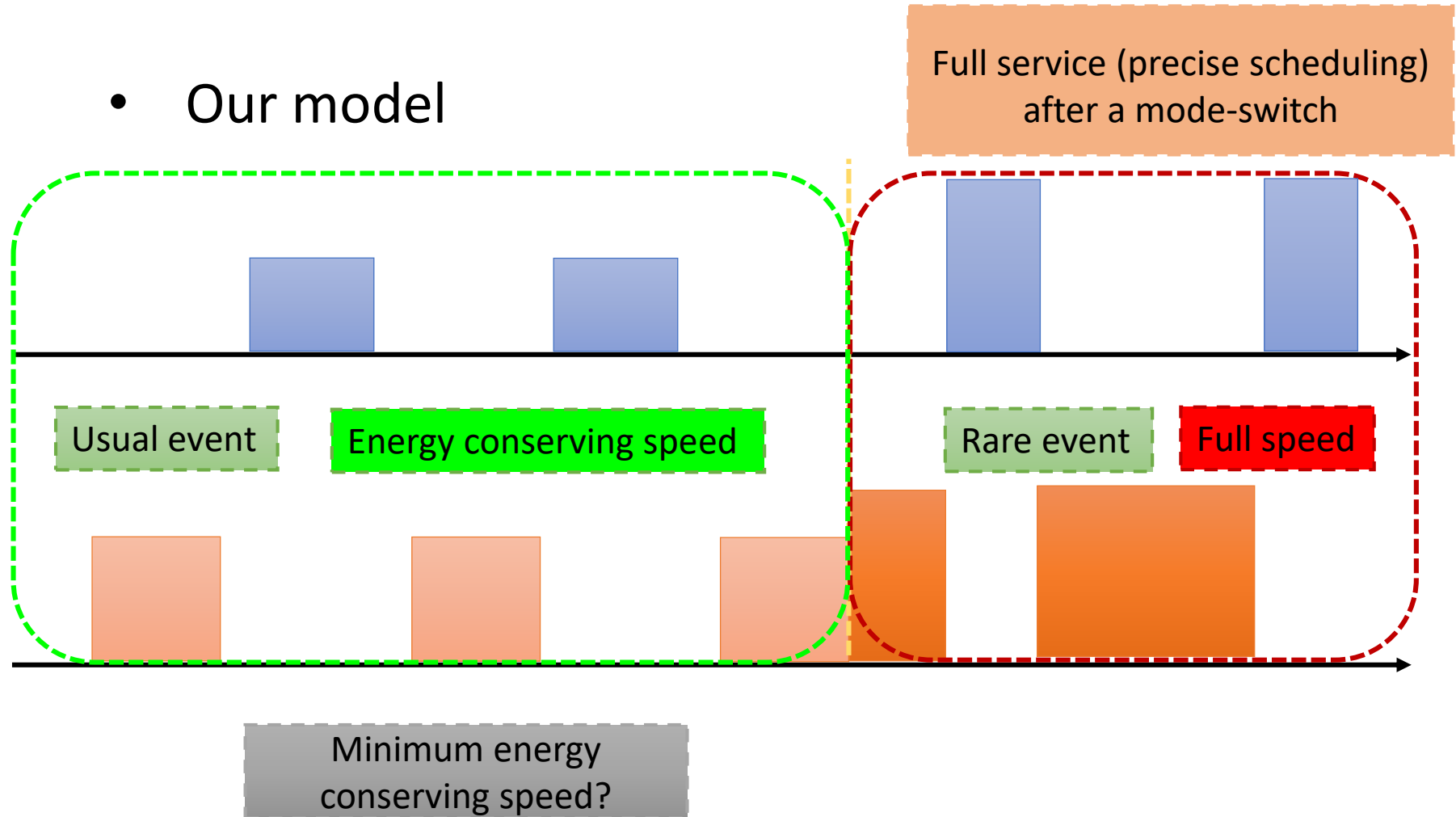
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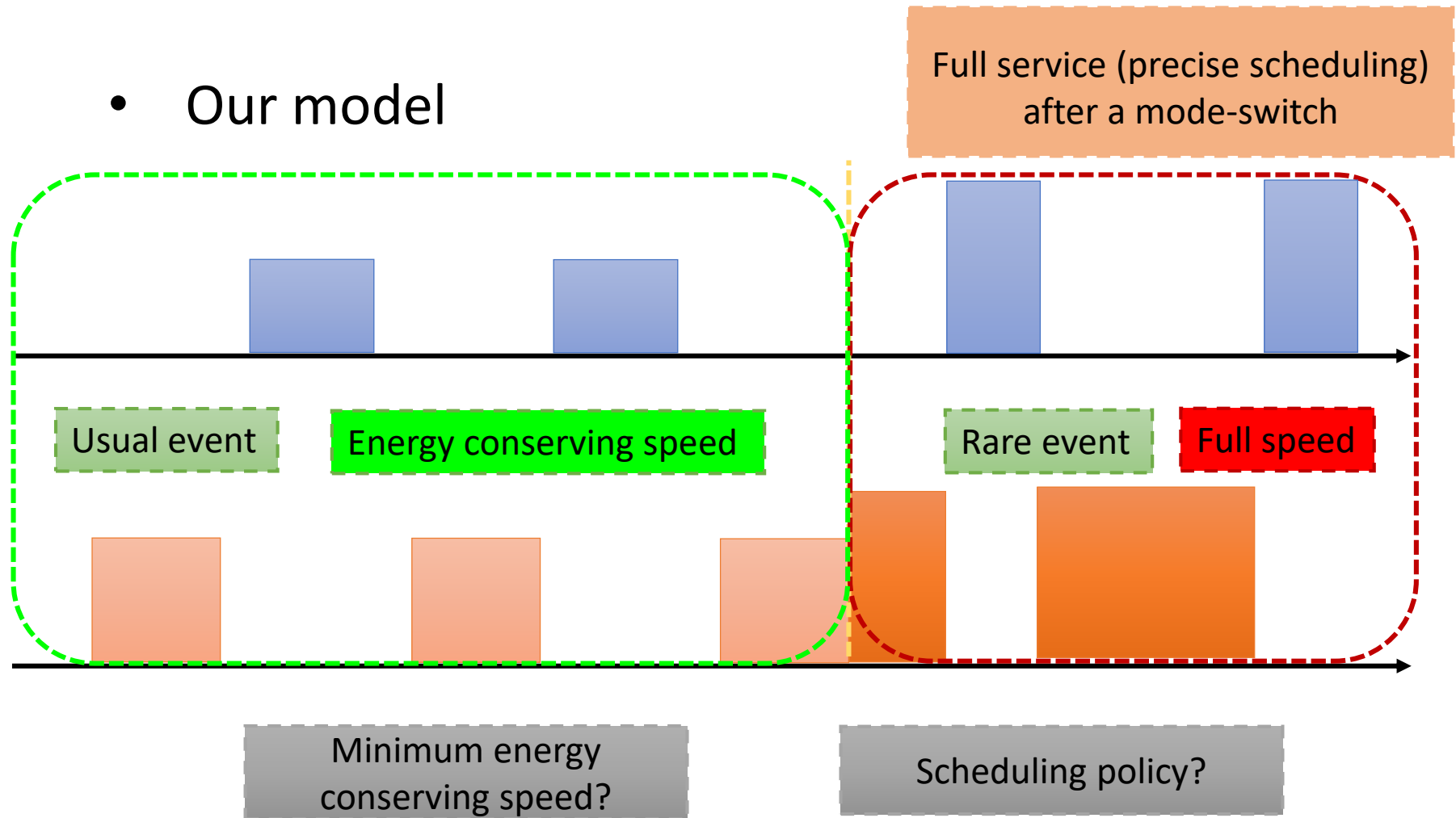
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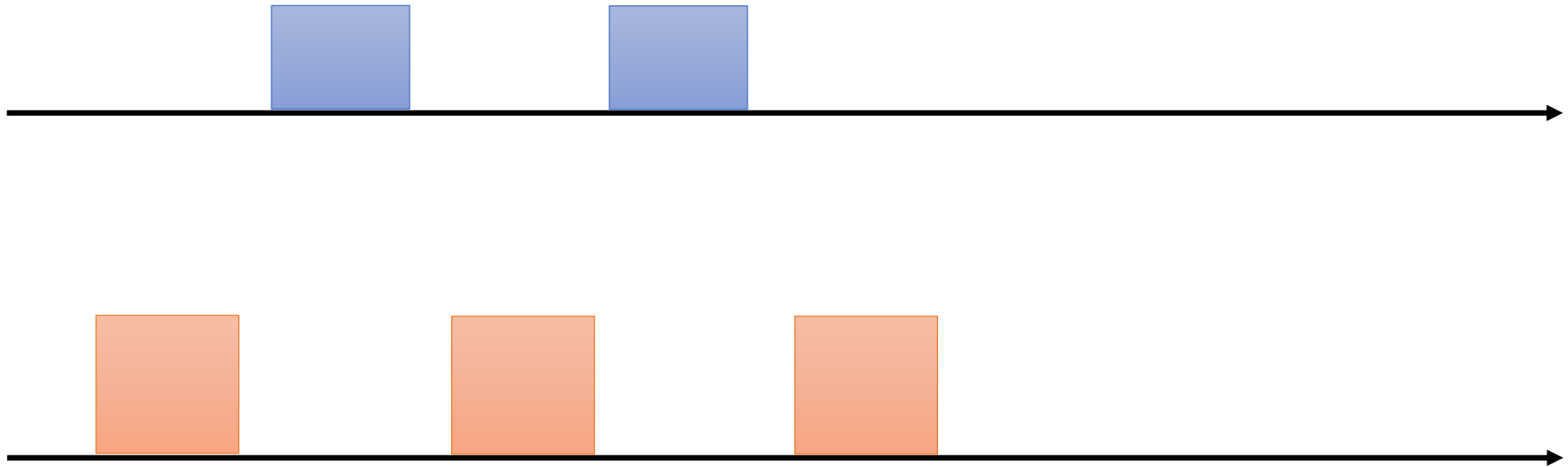


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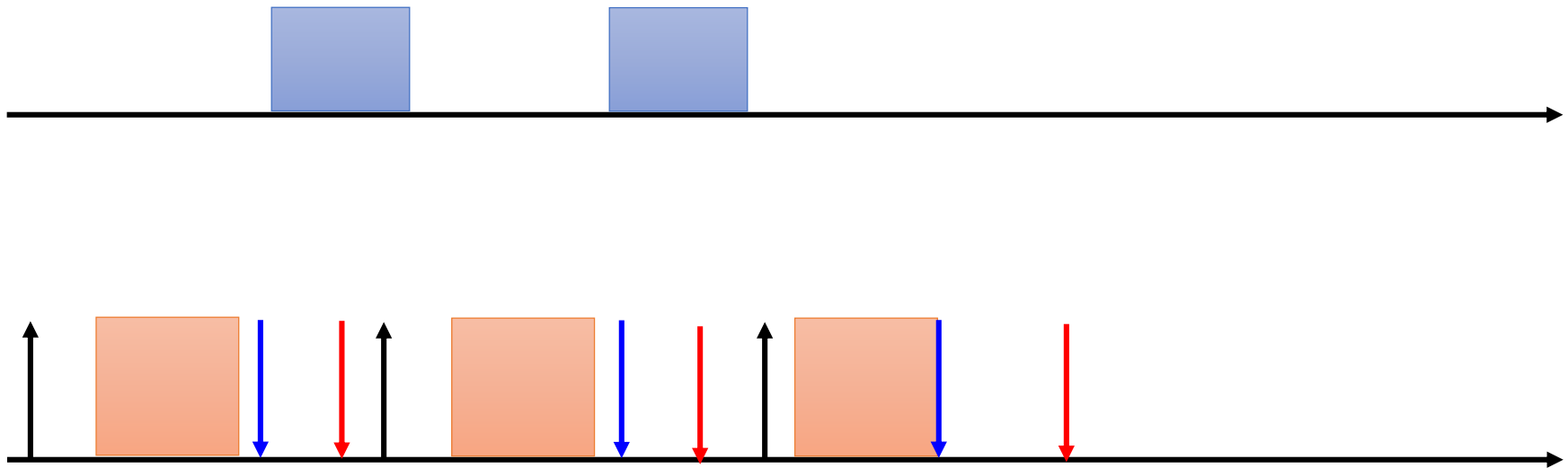
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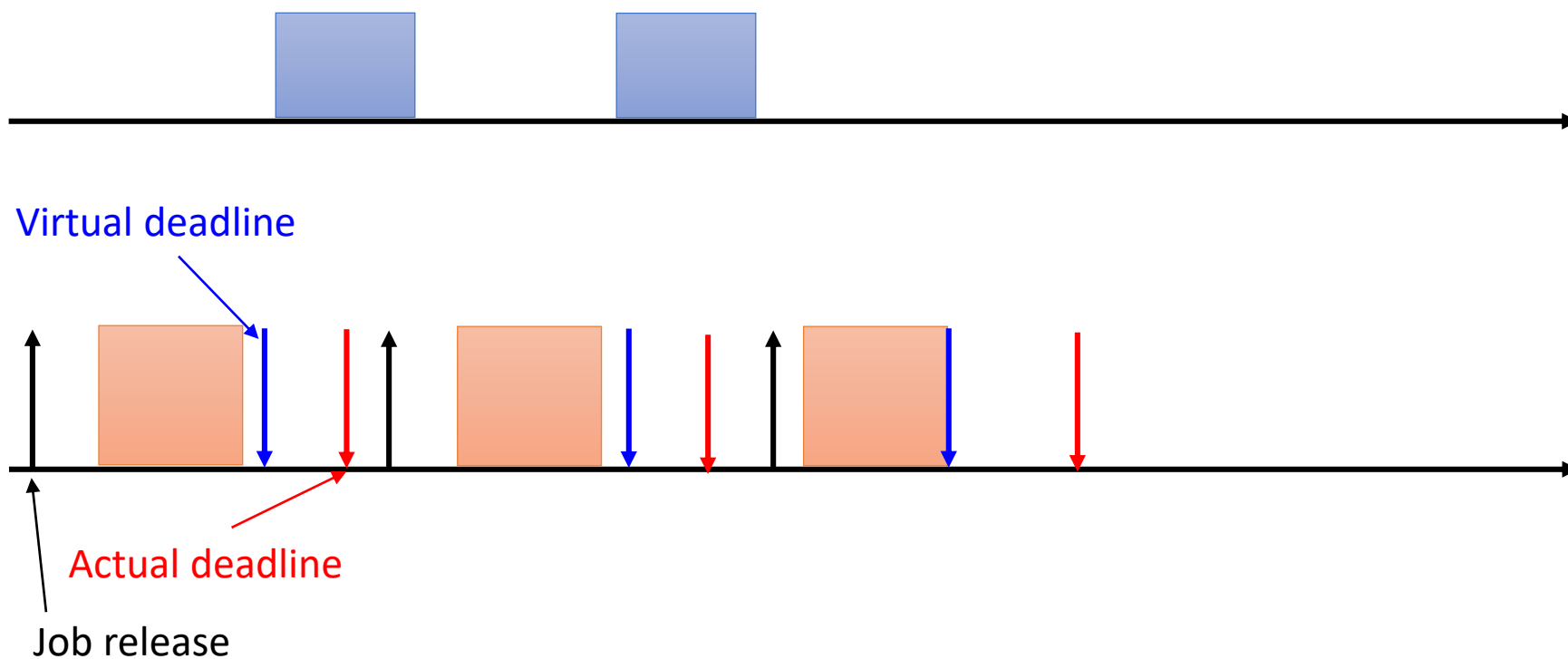
- Setting a virtual deadline (**VD**) to all the HI-criticality tasks at LO-criticality mode.



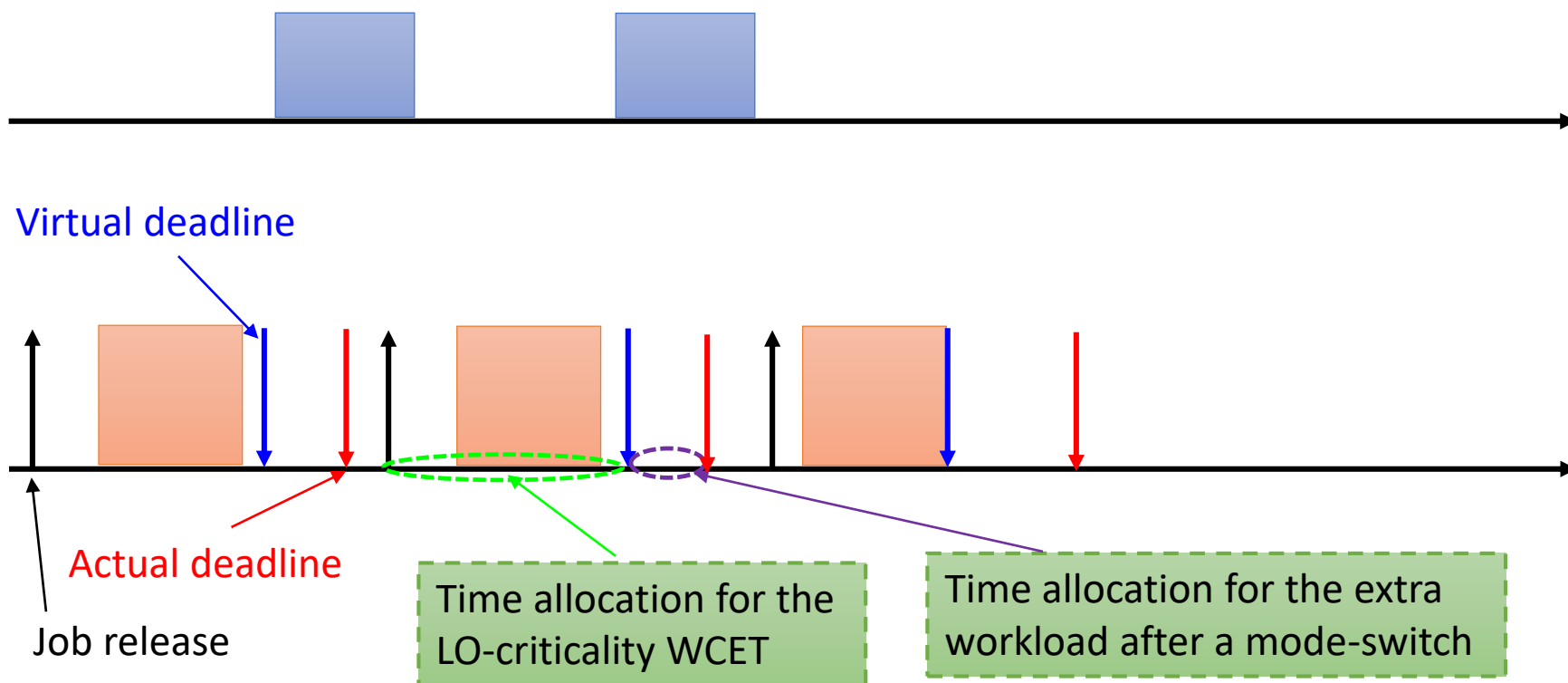
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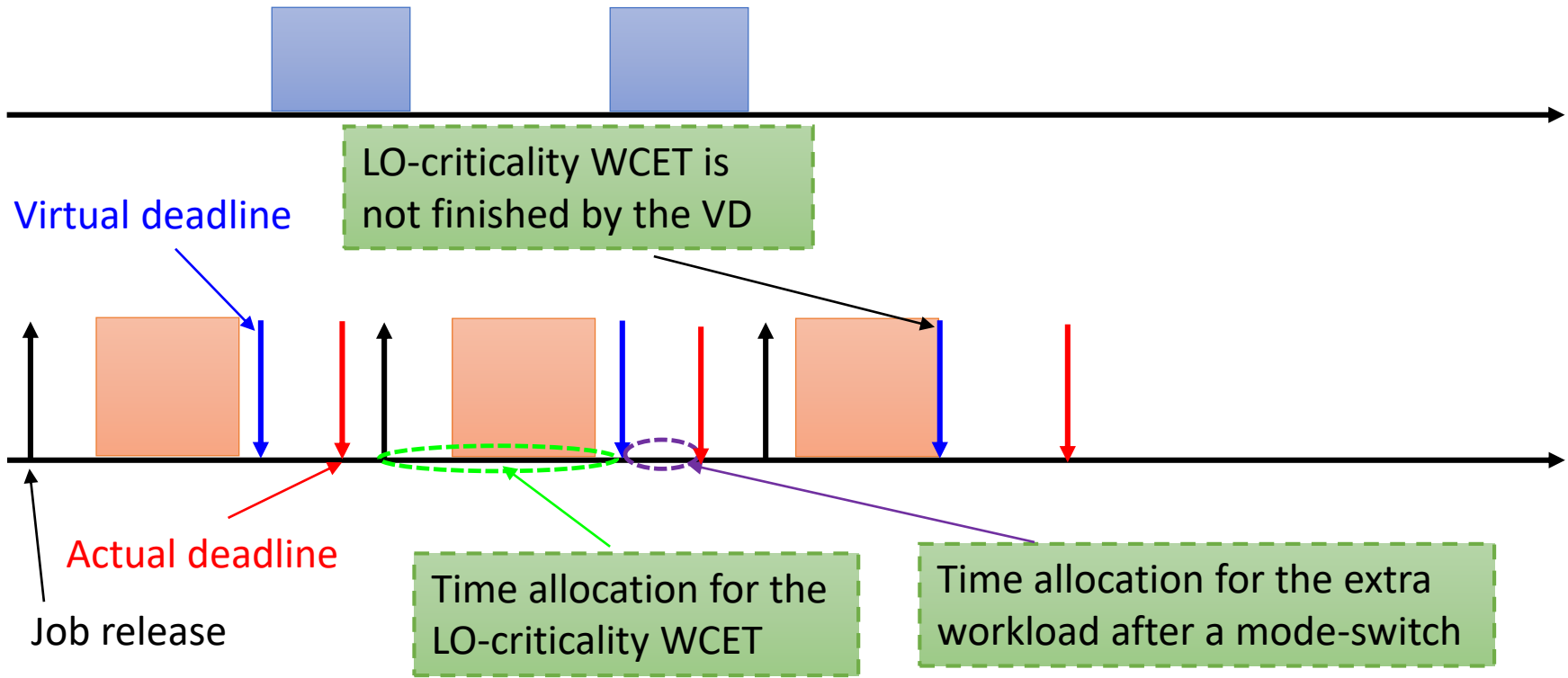
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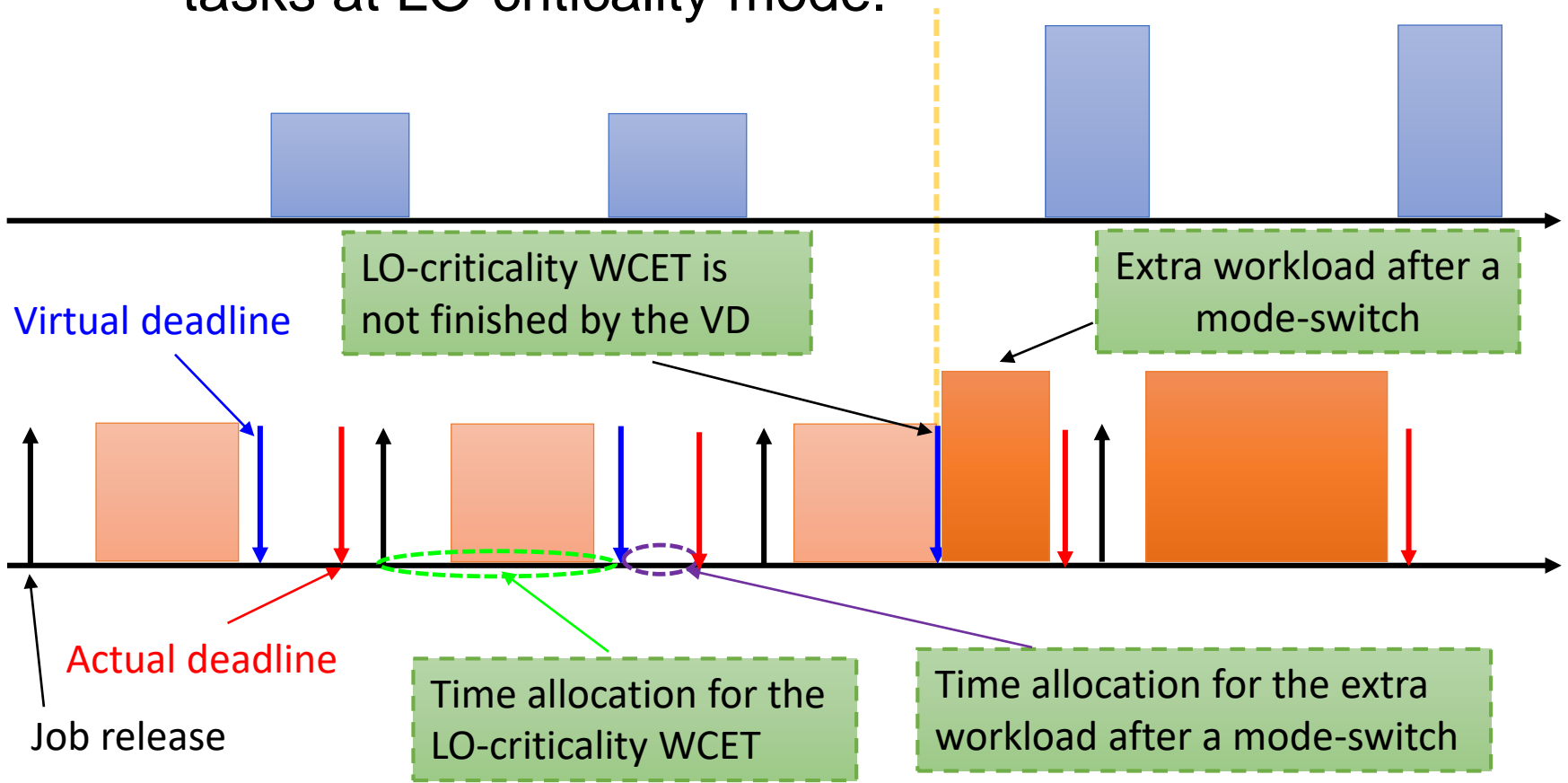
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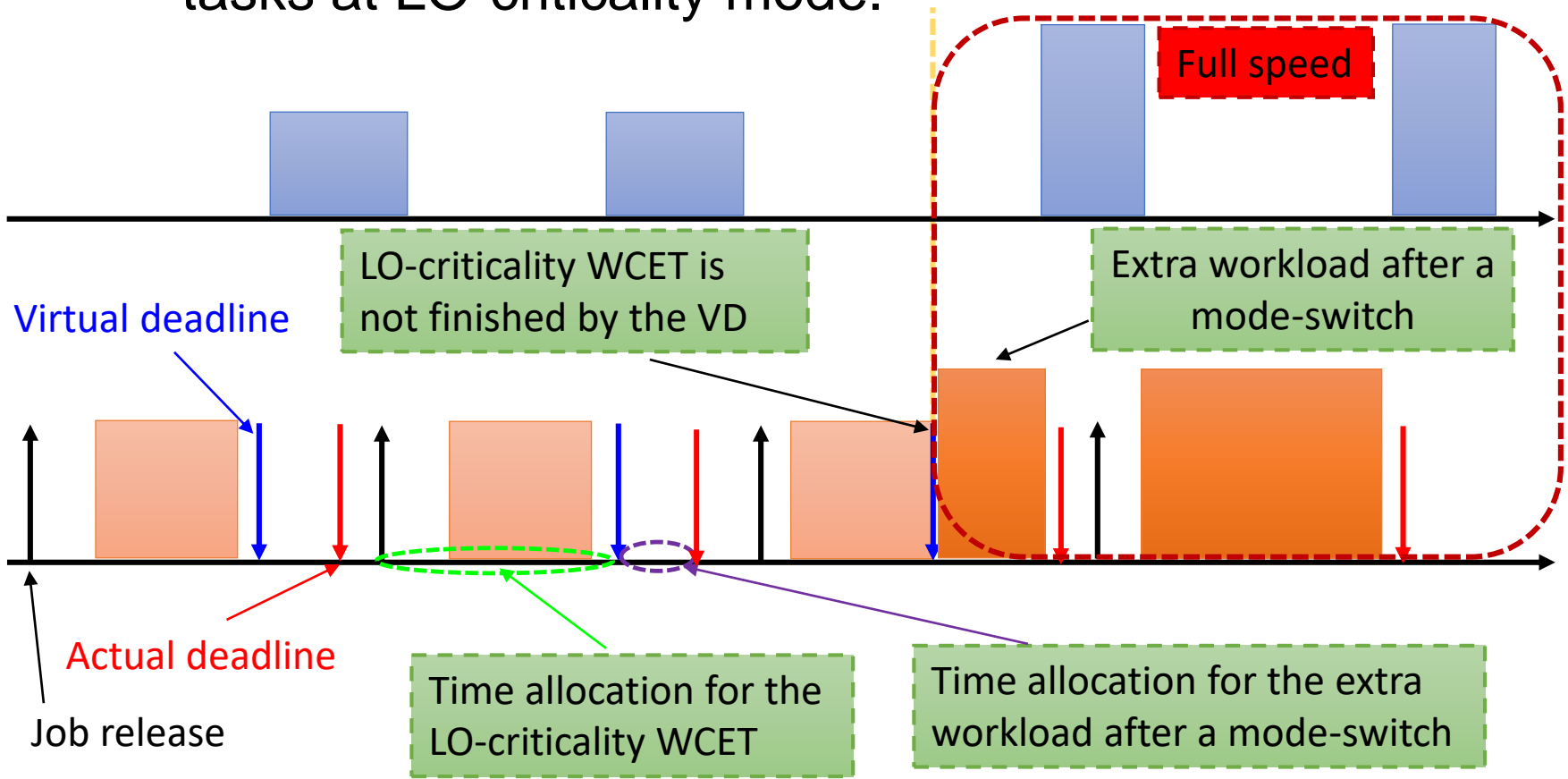
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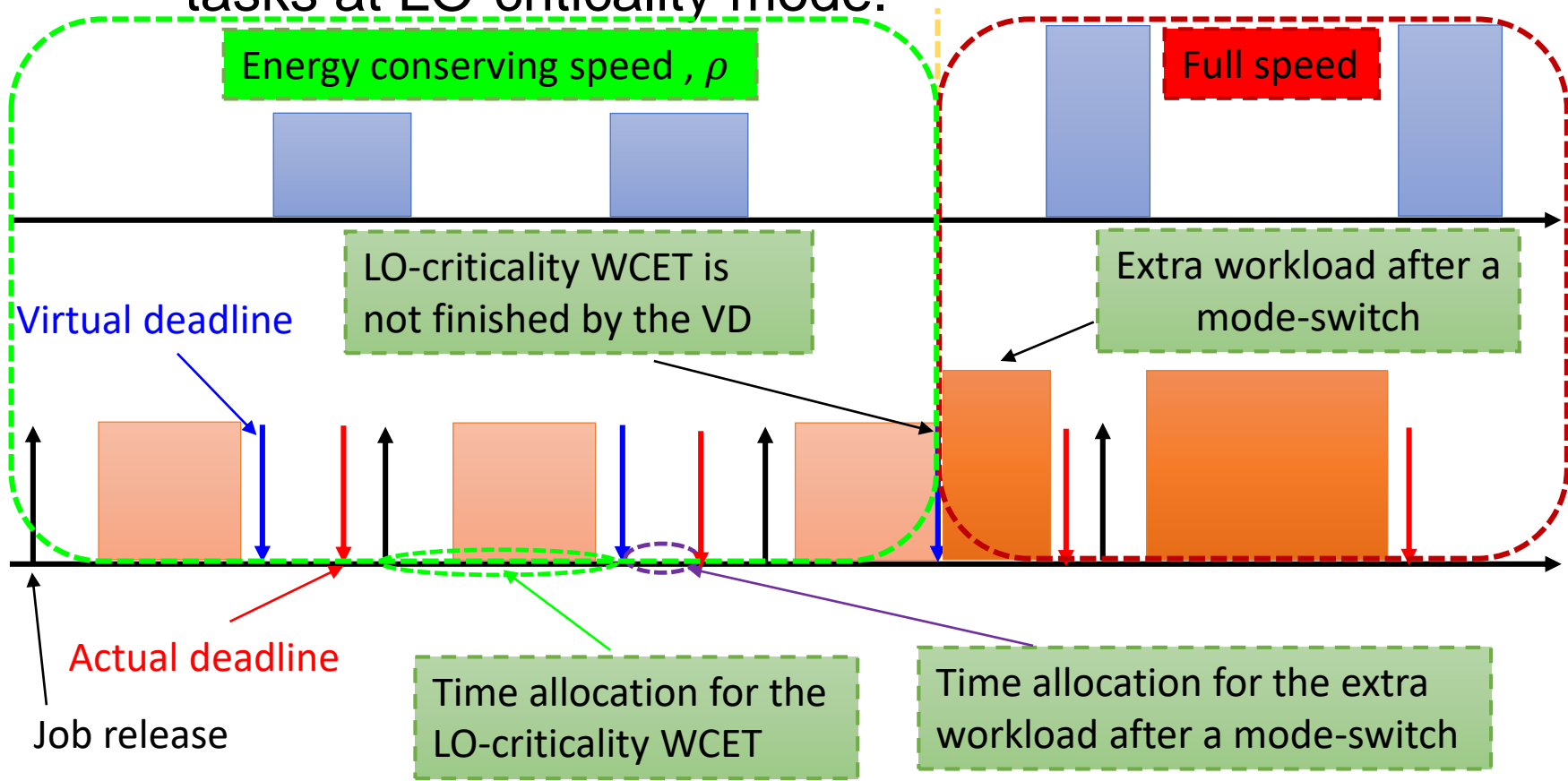
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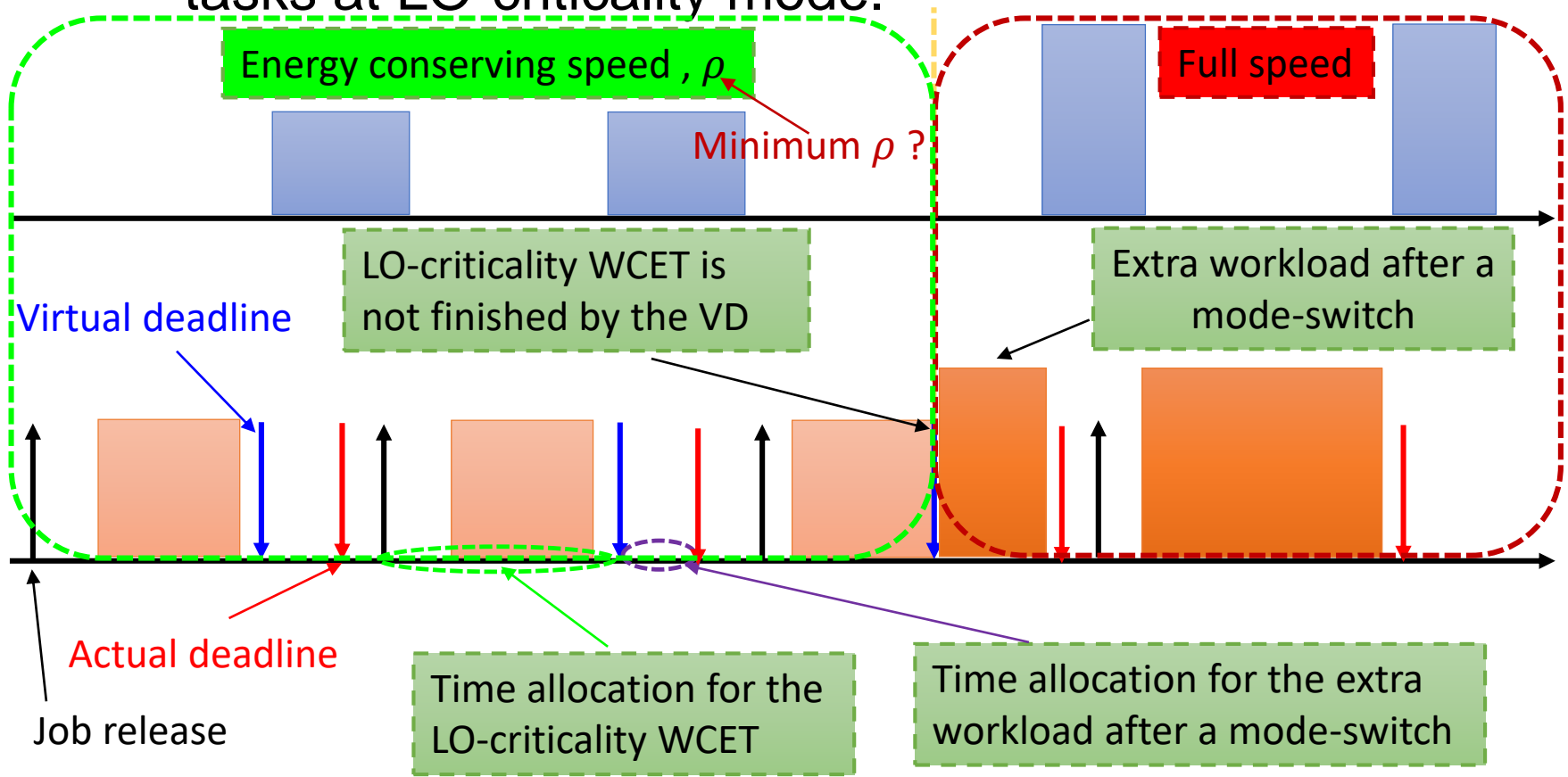
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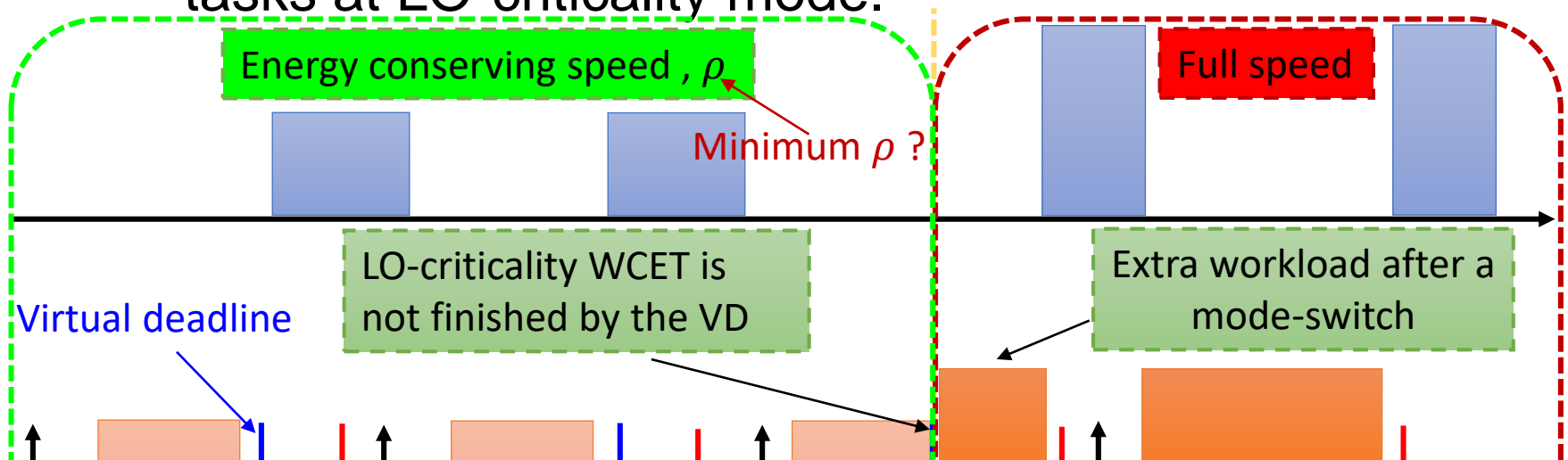
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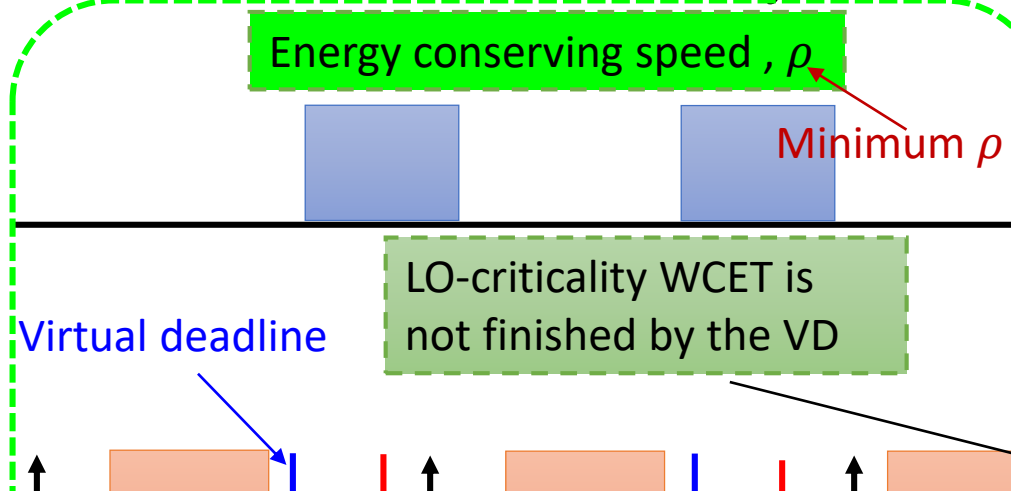
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Theorem 3.4. Given a precise mixed-criticality model task set, the minimum value of ρ for the task set to be schedulable by EDF-VD is

$$\rho = \min\left(U_L^L + U_H^H, U_L^L + \frac{(1 - U_L^L)U_H^L}{(1 - U_H^H - U_L^L)}\right)$$

- Setting a virtual deadline (VD) to all the HI-criticality tasks at LO-criticality mode.



Virtual Deadline
 $= x \cdot \text{Actual Deadline}$

$$x \leq \frac{1 - (U_H^H + U_L^L)}{(1 - U_L^L)}$$

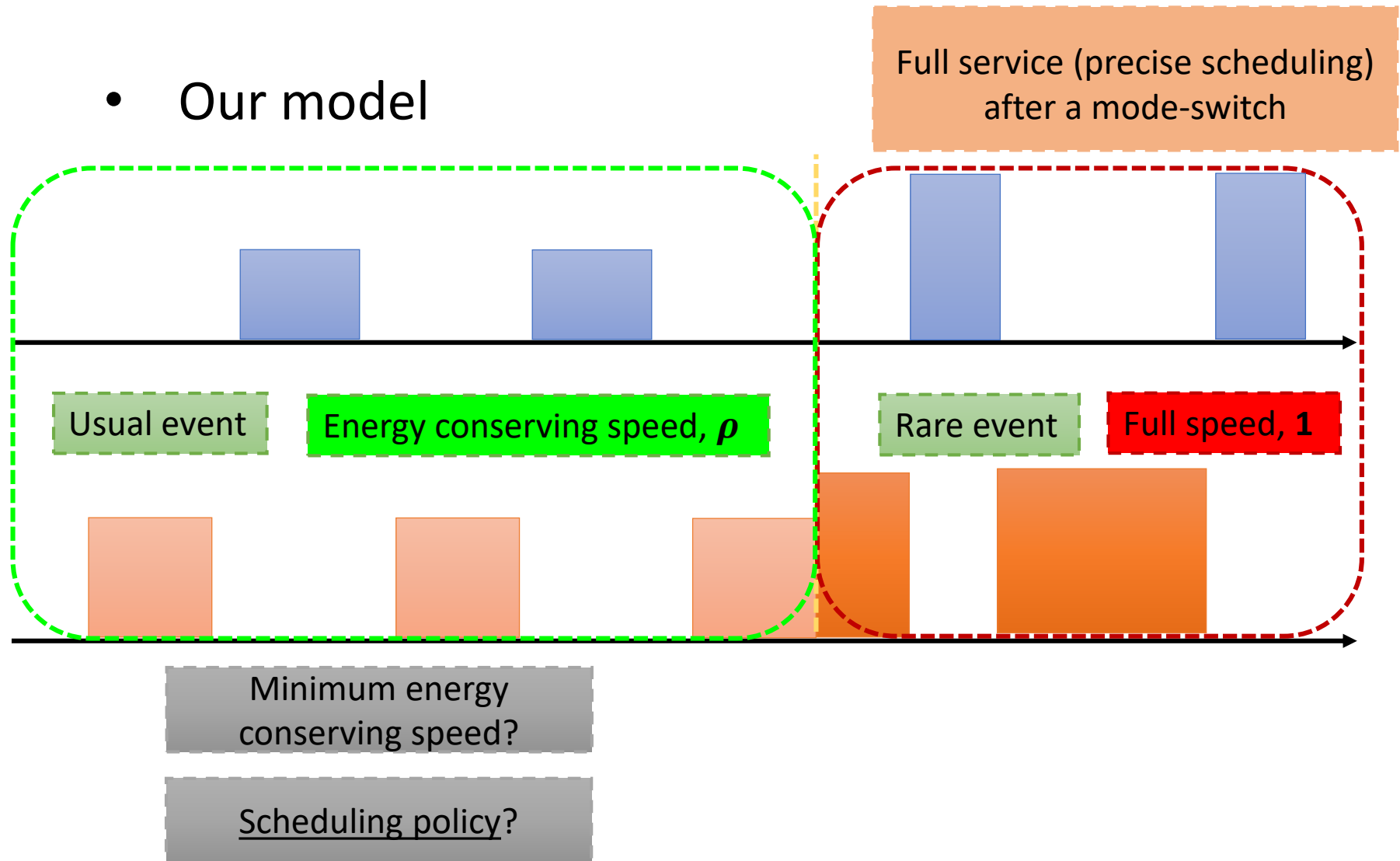
$$x \geq \frac{U_H^L}{(\rho - U_L^L)}$$

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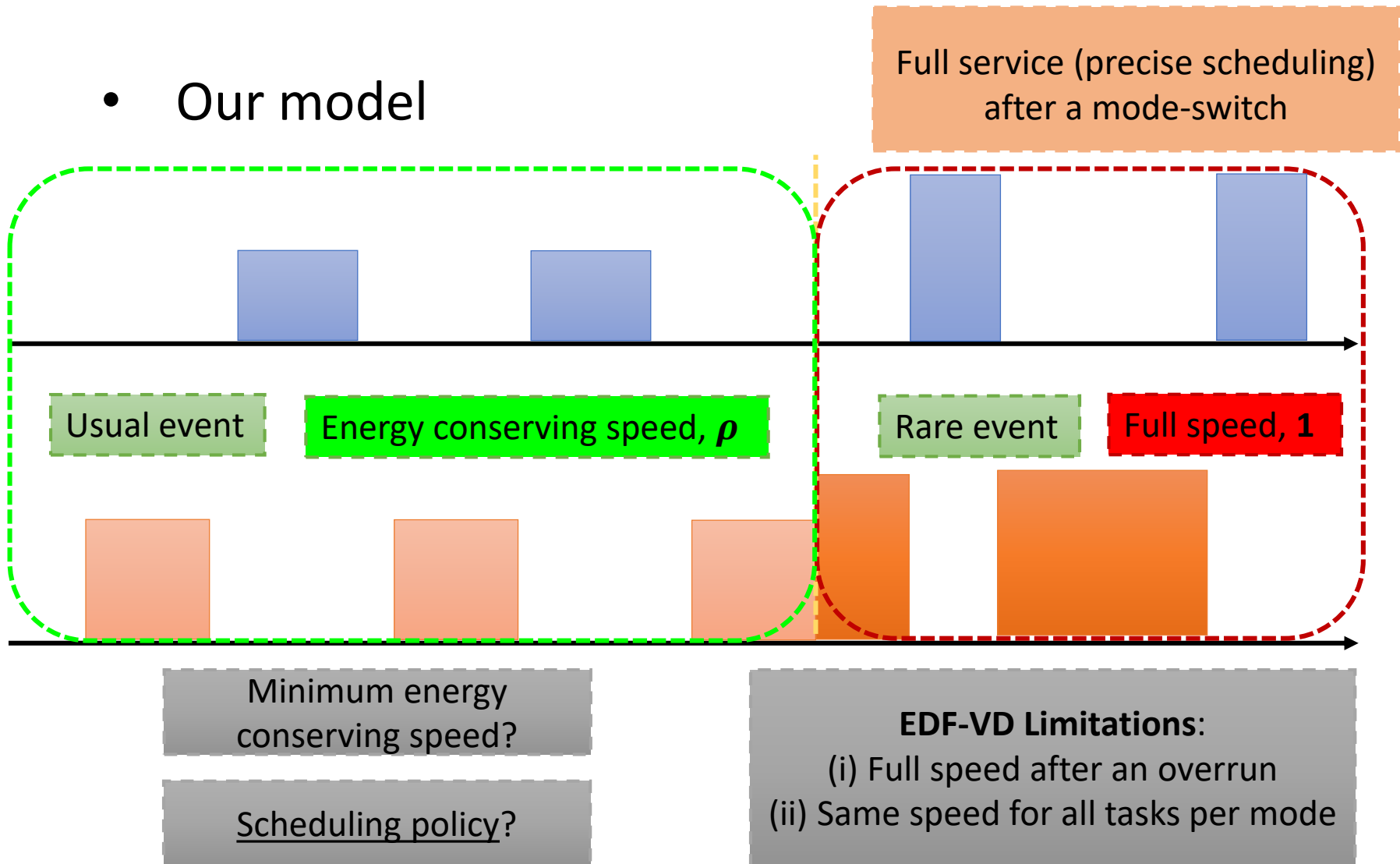
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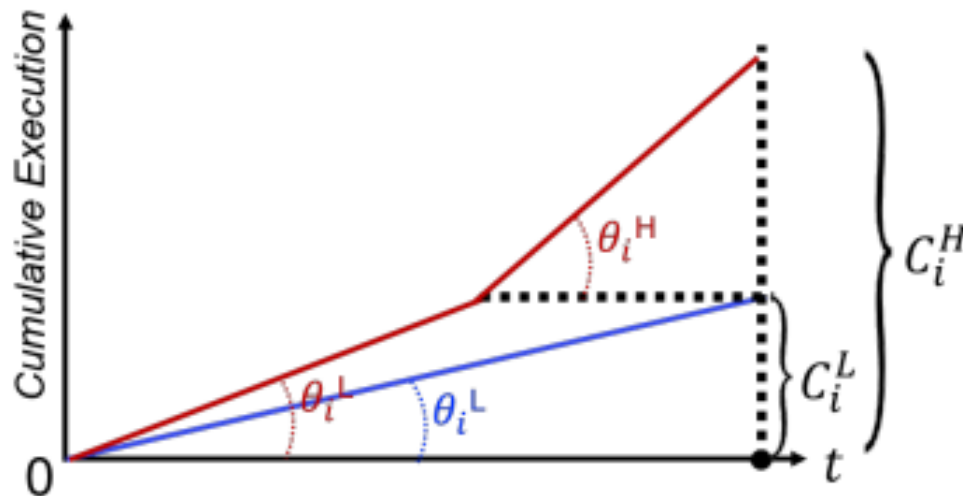


Problem and Motivation

- Our model



- All the tasks receive processor-share and have a constant execution rate from their release to the deadline.

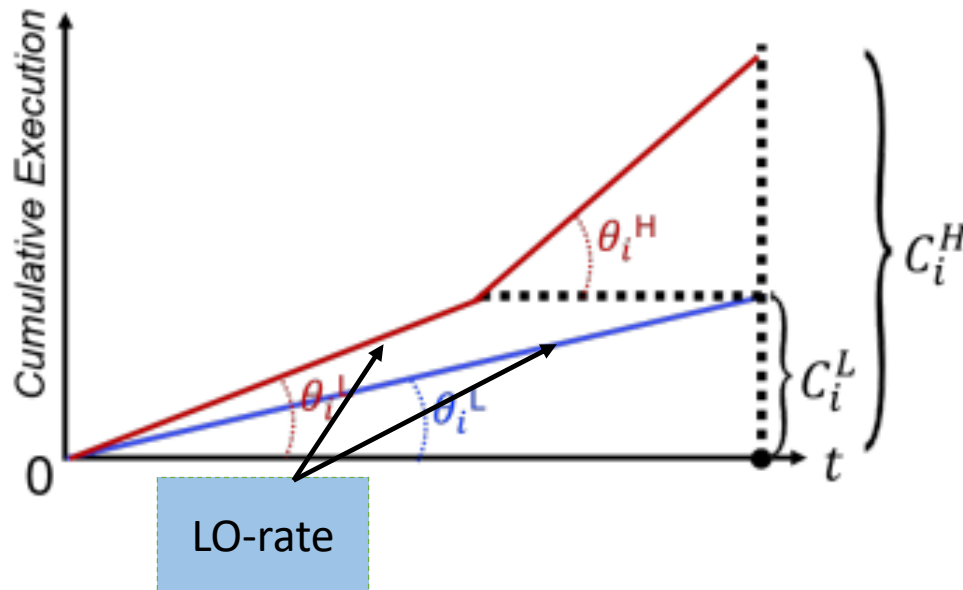


Acknowledgment: Sanjoy Baruah

J. Lee, K. Phan, X. Gu, J. Lee, A. Easwaran, I. Shin, and I. Lee. MC-Fluid: Fluid model-based mixed-criticality scheduling on multiprocessors. In RTSS 2014.

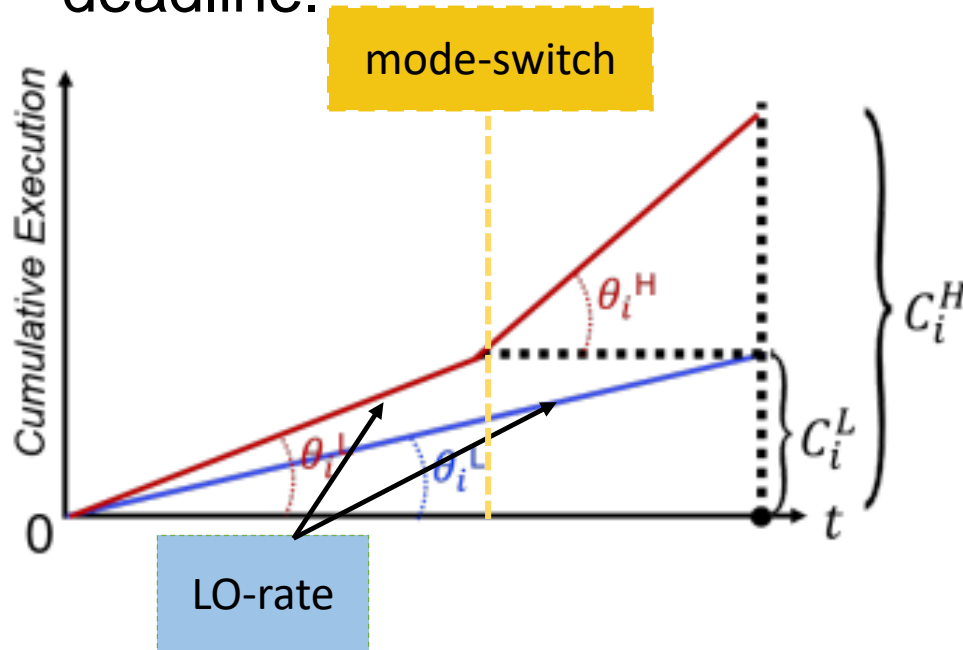
MC-Fluid (MCF)

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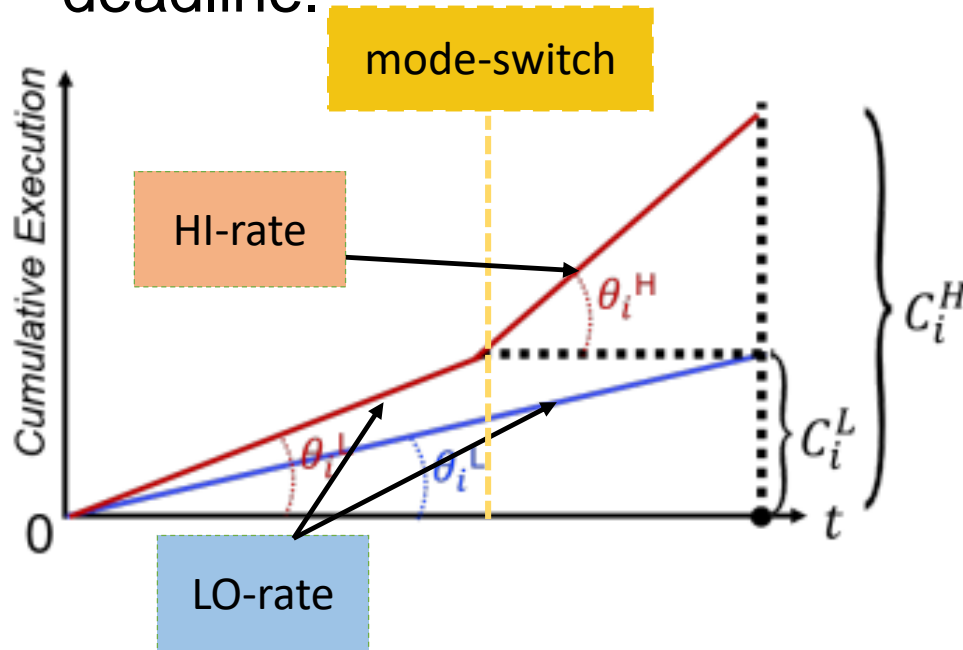
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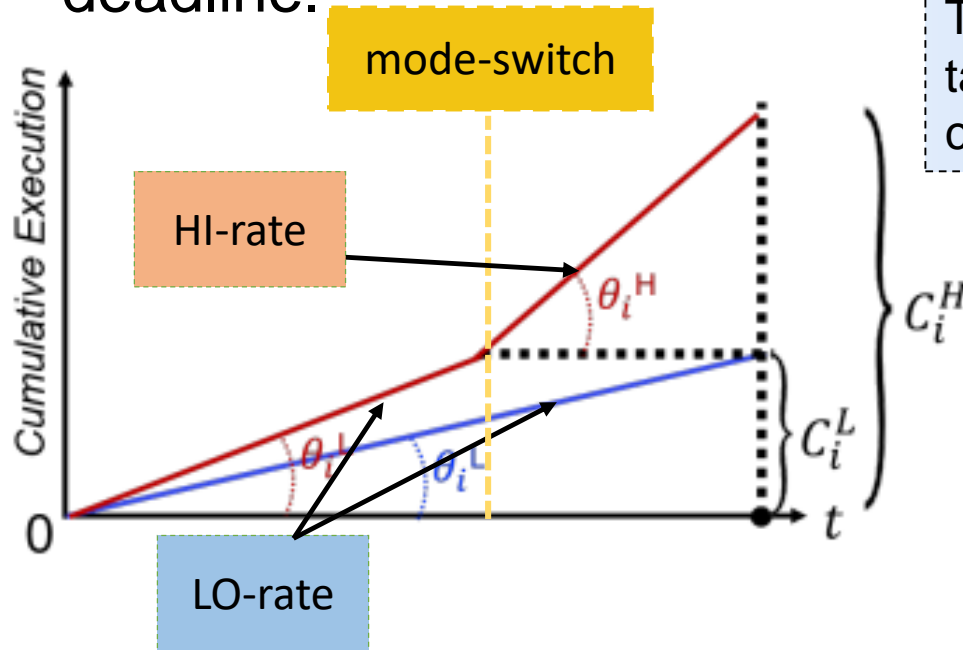


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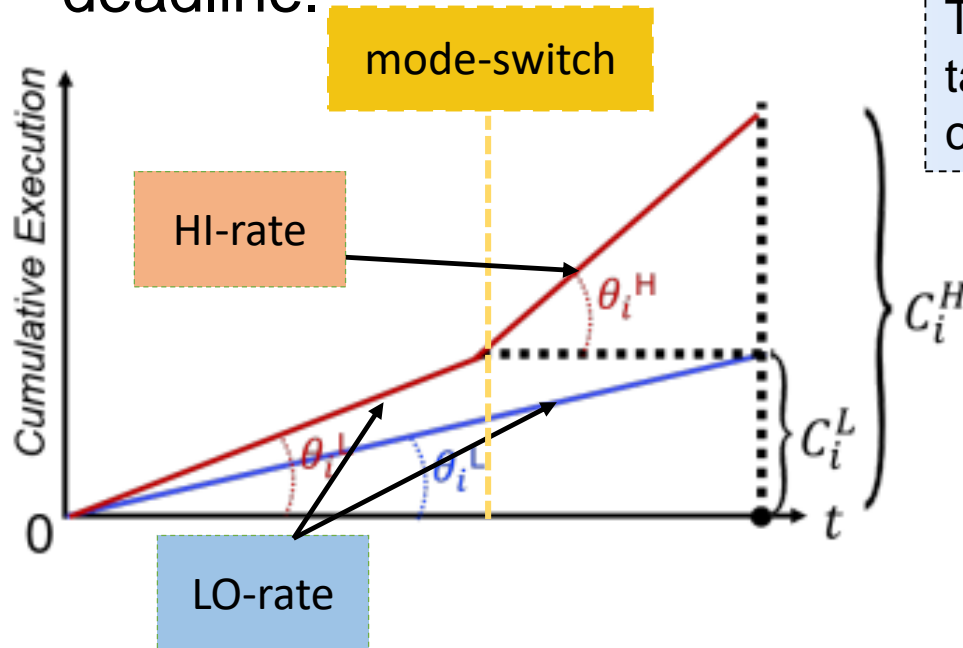


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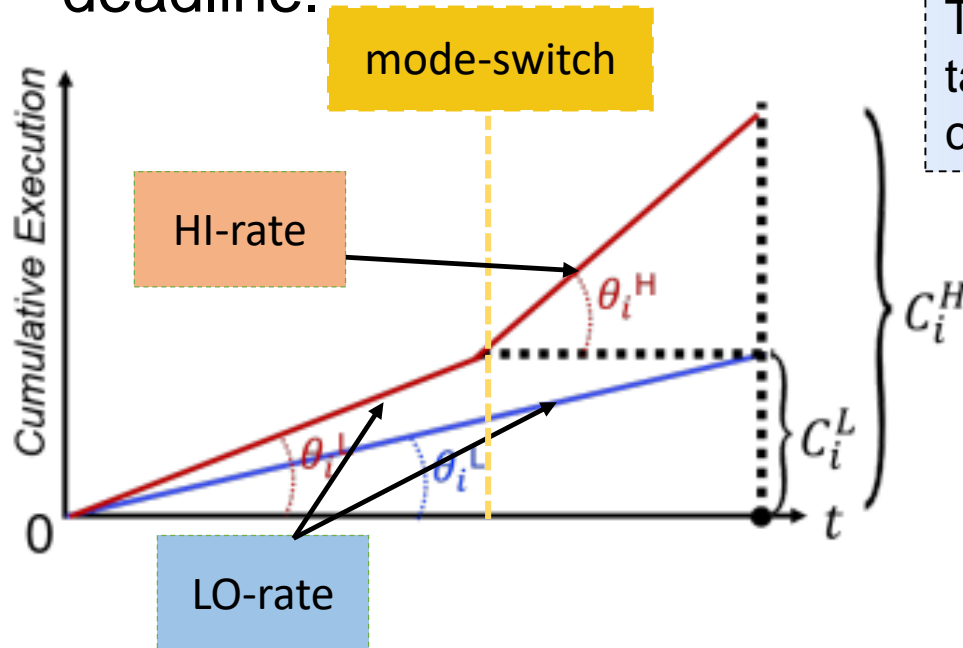
Total processor-share (of each task) is less or equal to the capacity (speed) of the processor.

$$\sum_{\tau_i \in \tau} \theta_i^l < 1$$

$$\sum_{\tau_i \in \tau_H} \theta_i^H \leq 1$$

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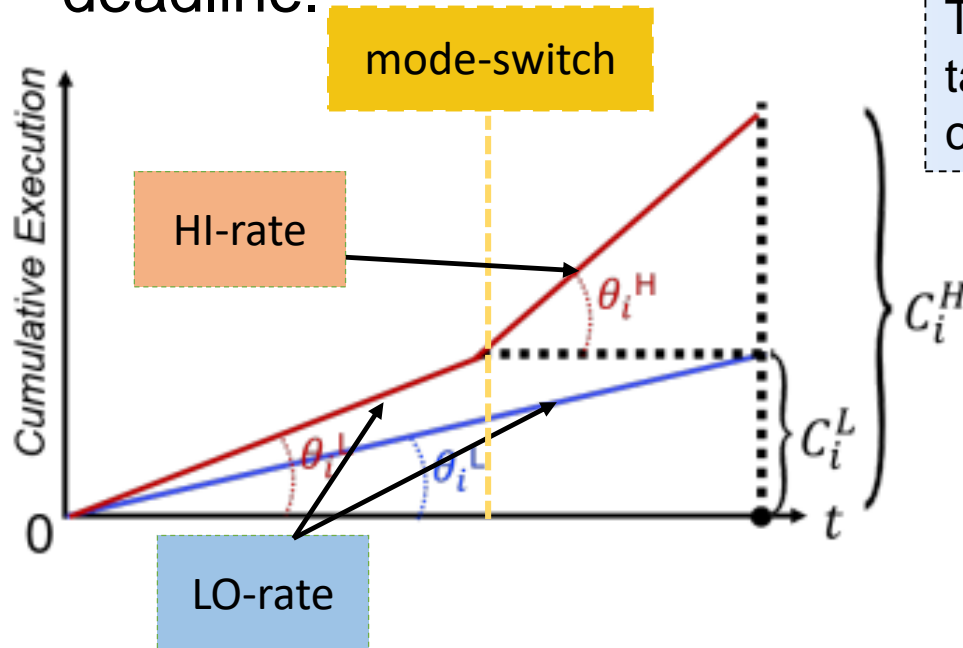


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$$\theta_i^H = \theta_i \quad \theta_i^l = \lambda \theta_i$$

$$\lambda = \frac{U^L}{1 + U^L - U^H}$$

$$\forall i, \theta_i = \frac{u_i^L}{\lambda} - u_i^L + u_i^H$$

Performance Evaluation

- **Speedup Bound, s .** How much faster processors are required for an algorithm to schedule the same taskset, scheduled by an optimal algorithm.
- **Approximation Ratio, α .** The ratio of energy conserving speed determined by an algorithm vs the optimal algorithm.

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	LO-criticality (Speedup Bound)	HI-criticality (Speedup Bound)	LO-criticality (Approximat ion Ratio)	HI-criticality (Approximation Ratio)
Optimal algorithm	P	1	P	1
An algorithm	sP	s	αP	1

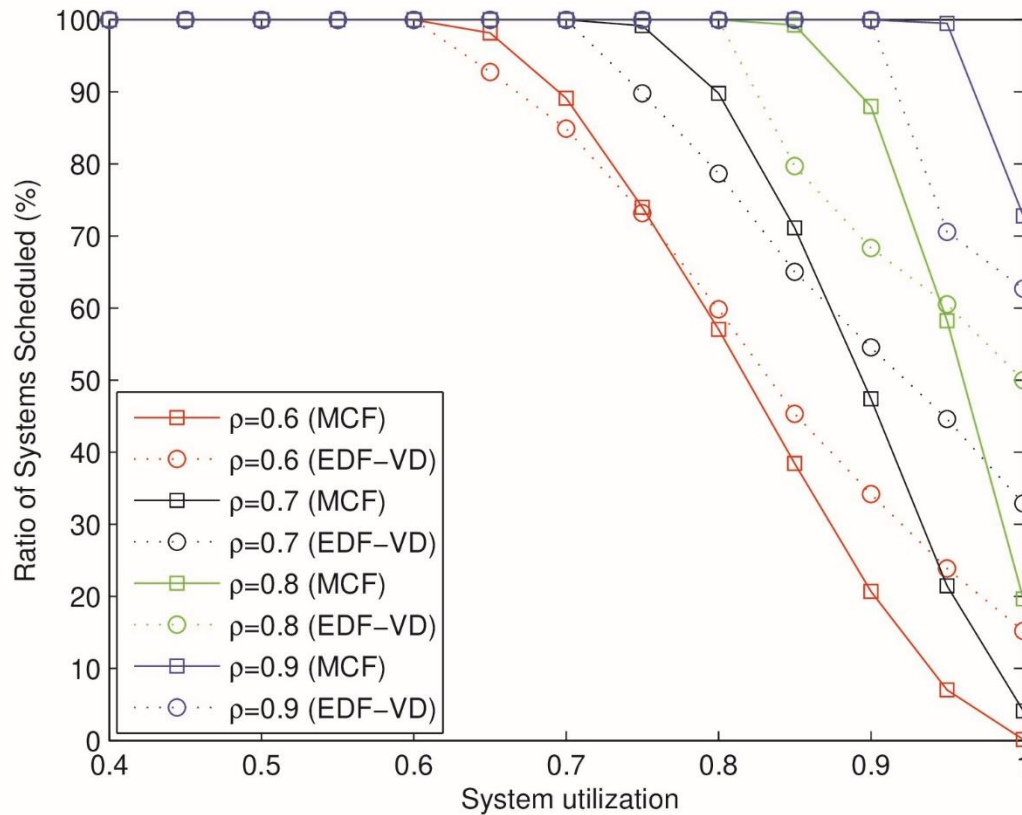
- **Speedup Bound, s .** How much faster processors are required for an algorithm to schedule the same taskset, scheduled by an optimal algorithm.
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$$\textit{Theorem 3.4. (EDF - VD), } s \leq (1/\min(U_L^L + U_H^H, U_L^L + \frac{(1-U_L^L)U_H^L}{(1-U_H^H-U_L^L)}))$$

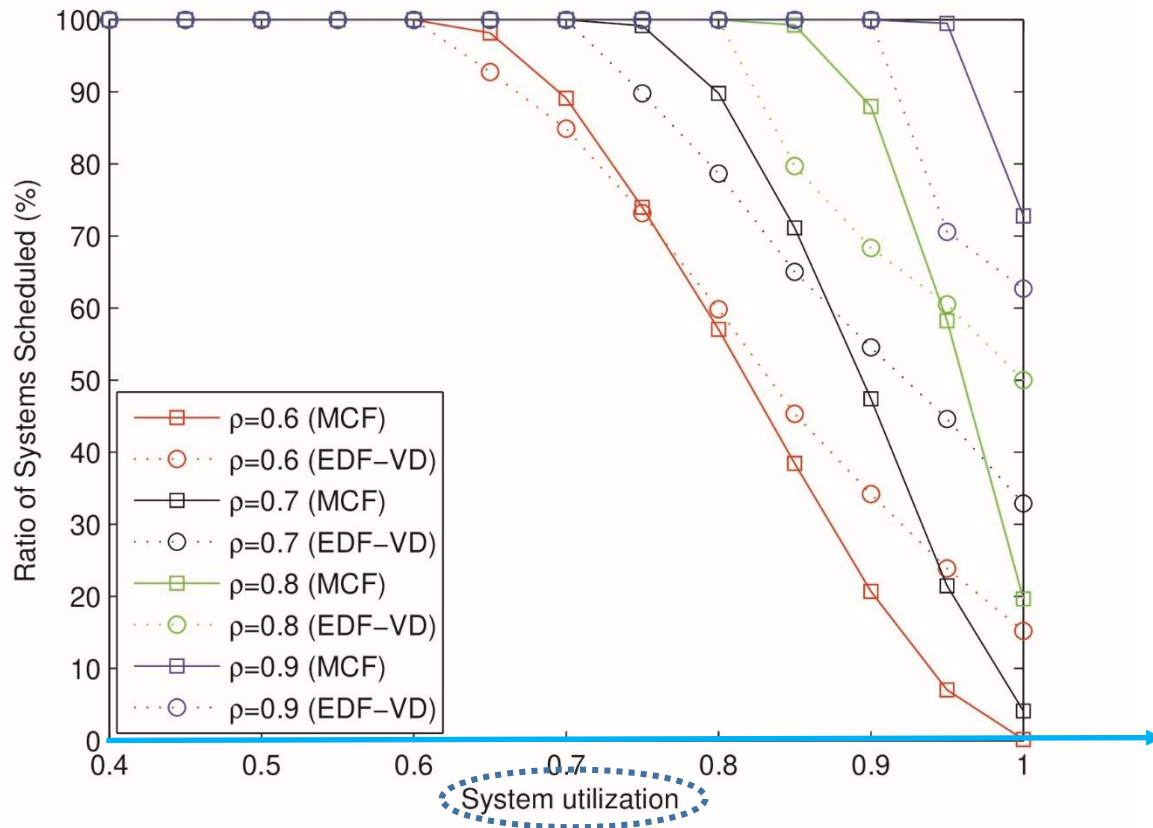
$$\textit{Theorem 3.6. (EDF - VD), } \alpha \leq 1 + \frac{U_H^L(1-U_L^L)}{U_L^L(1-U_L^L-U_H^H)}$$

$$\textit{Theorem 4.3. (MCF), } \alpha \leq \frac{1}{1 + U^L - U^H}$$

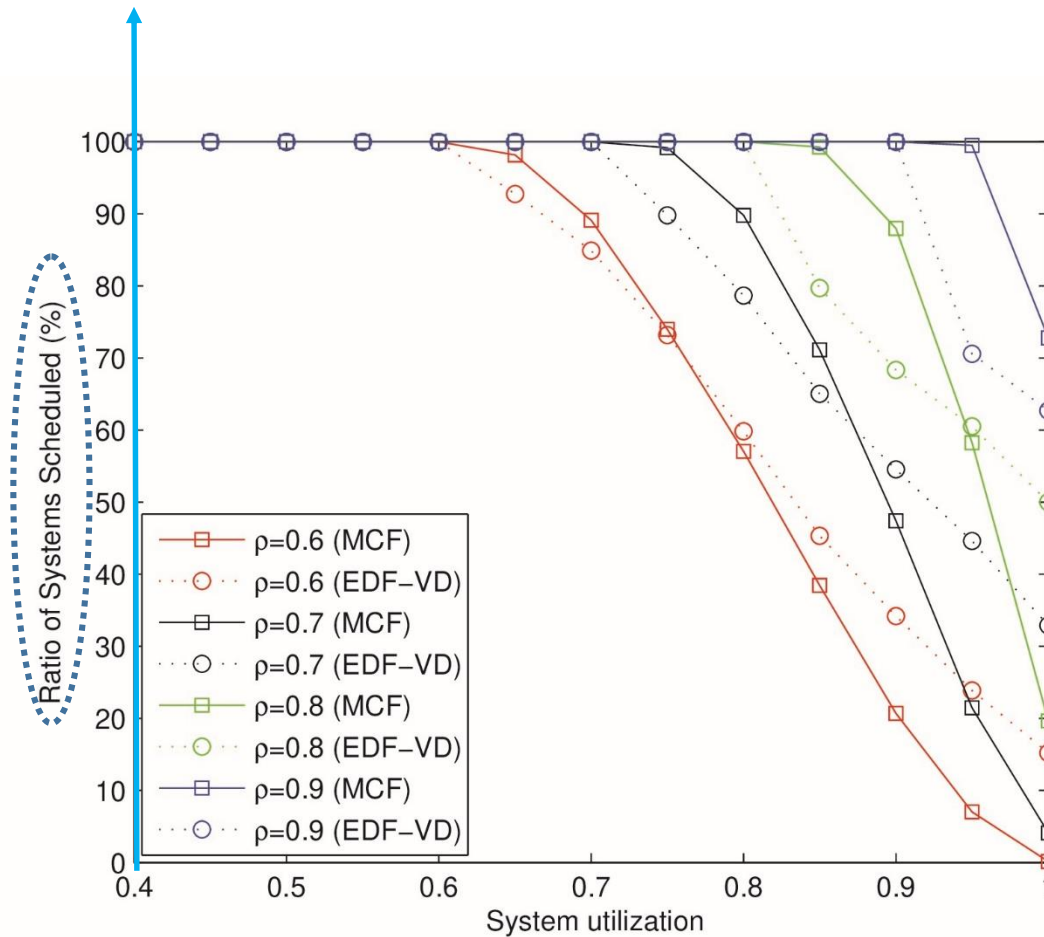
Simulation (EDF-VD vs MCF)



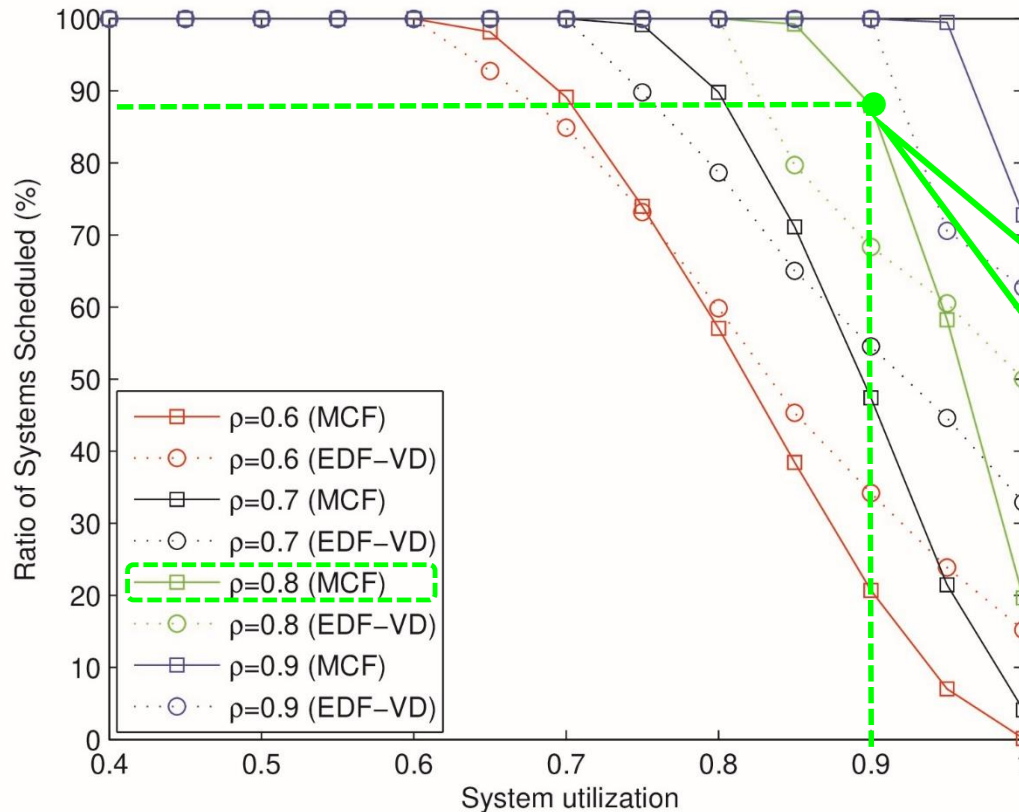
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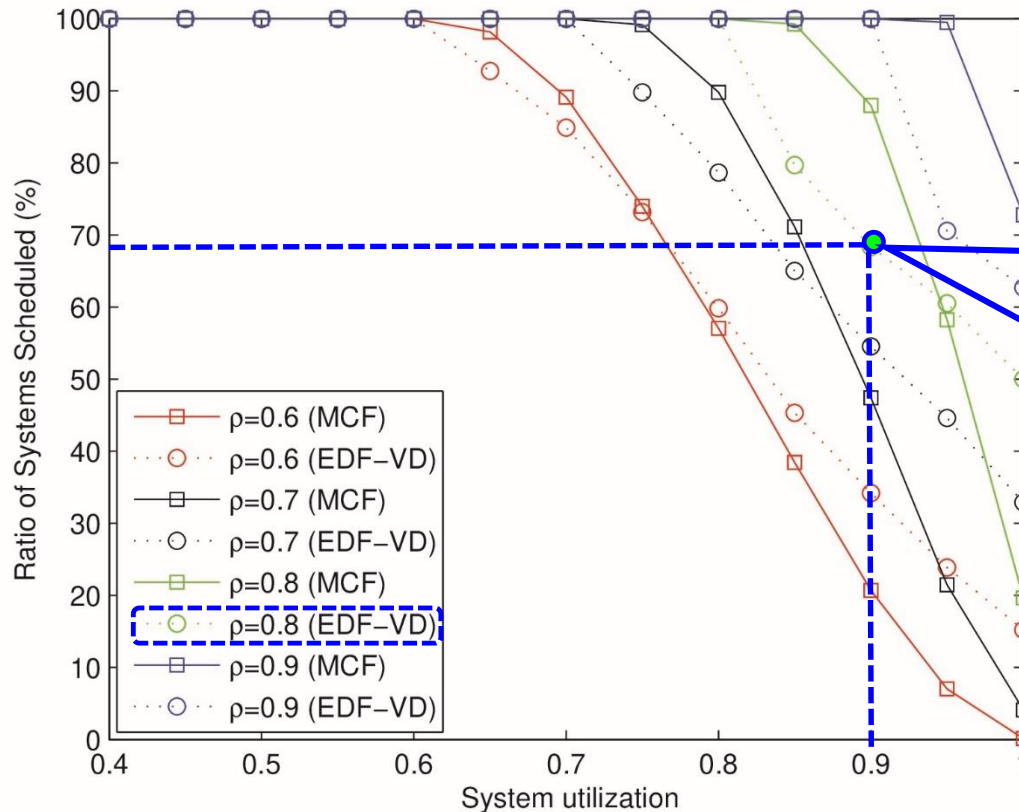


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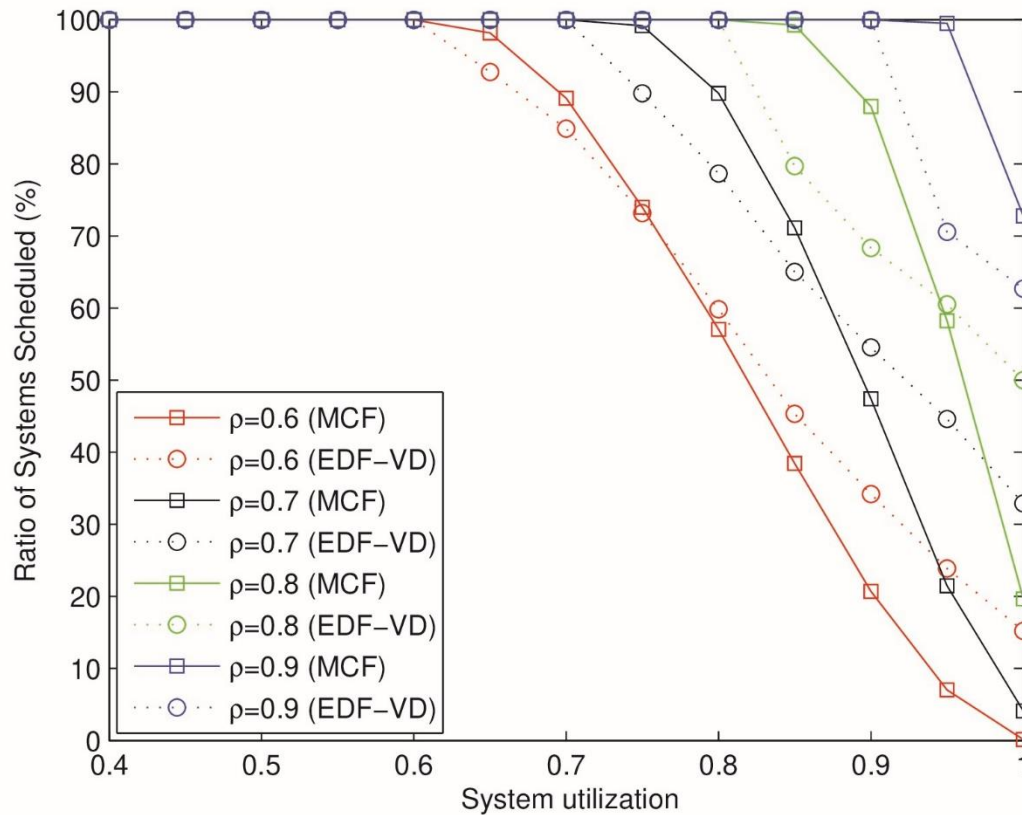
If $\rho = 0.8$ and system utilization is 0.9, MCF can schedule 88% of the randomly generated tasks.

Simulation (EDF-VD vs MCF)



If $\rho = 0.8$ and system utilization is 0.9, EDF-VD can schedule 68% of the randomly generated tasks.

Simulation (EDF-VD vs MCF)



- ❑ Energy-aware scheduling of MC tasks is challenging
- ❑ This work
 - Developed an integrated model combining precise scheduling of LO-criticality tasks on an energy-conserving platform.
 - Proposed schedulability tests under the EDF-VD and MCF scheduling framework.
 - Derived the speedup bound for EDF-VD and the approximation ratio for EDF-VD and MCF.

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❑ Future Goal

- Considering multiprocessor platform and parallel task model.
- Experimental evaluation on a real platform.

Thank You