

University of Stuttgart

Institute of Parallel and Distributed Systems¹

Institute of Systems Theory and Automatic Control²

Optimal Routing and Scheduling of Complementary Flows in Converged Networks

Jonathan Falk¹, Frank Dürr¹, Steffen Linsenmayer², Stefan Wildhagen², Ben Carabelli¹, Kurt Rothermel¹

The age of the cyber-physical machine.

More distributed systems interfacing with the physical world

- Manipulate the physical world via computers
- “Smart” {city, factory, home}
- Industry 4.0
- Autonomous Driving
- IEEE Time-sensitive Networking (TSN) Workgroup

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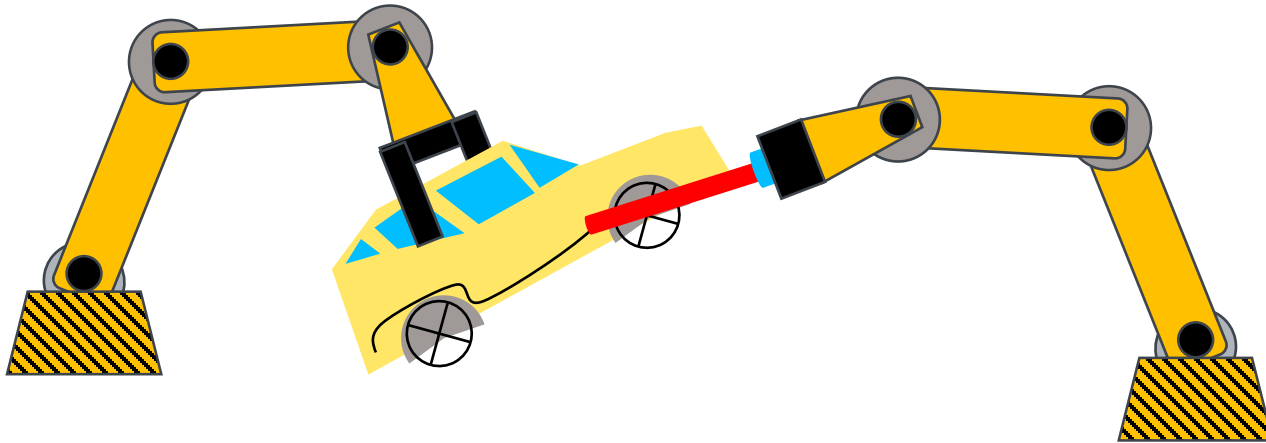


requires real-time communication

But! There's a catch.

Ubiquitous quality requirements

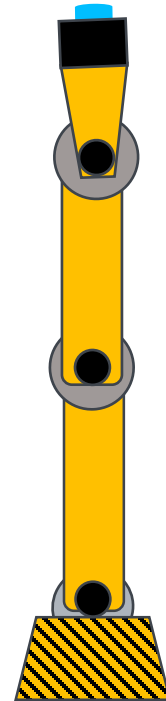
- message delivery with bounded delay & jitter
- introduced by “coupling” with the physical world
- lack of quality potentially disastrous
- often implemented with time-triggered paradigm with static schedule



But! There's a catch.

Applications can benefit from dynamic communication

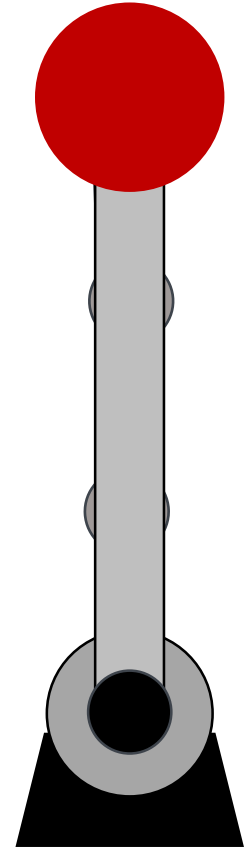
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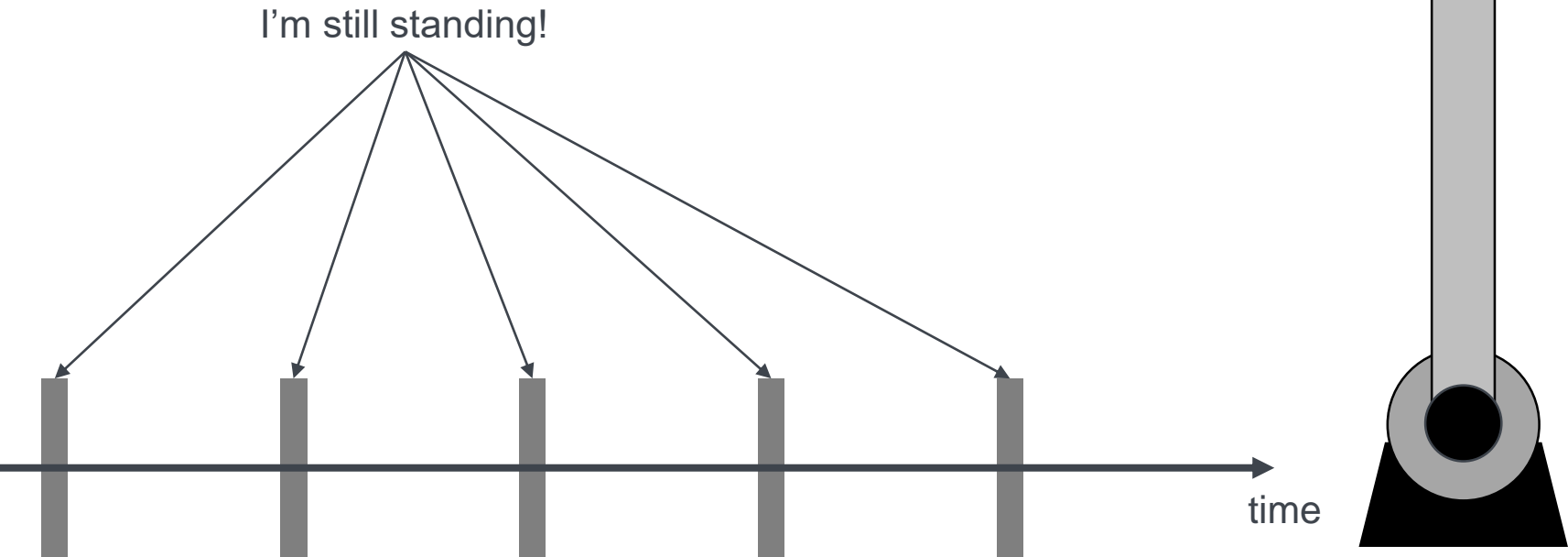
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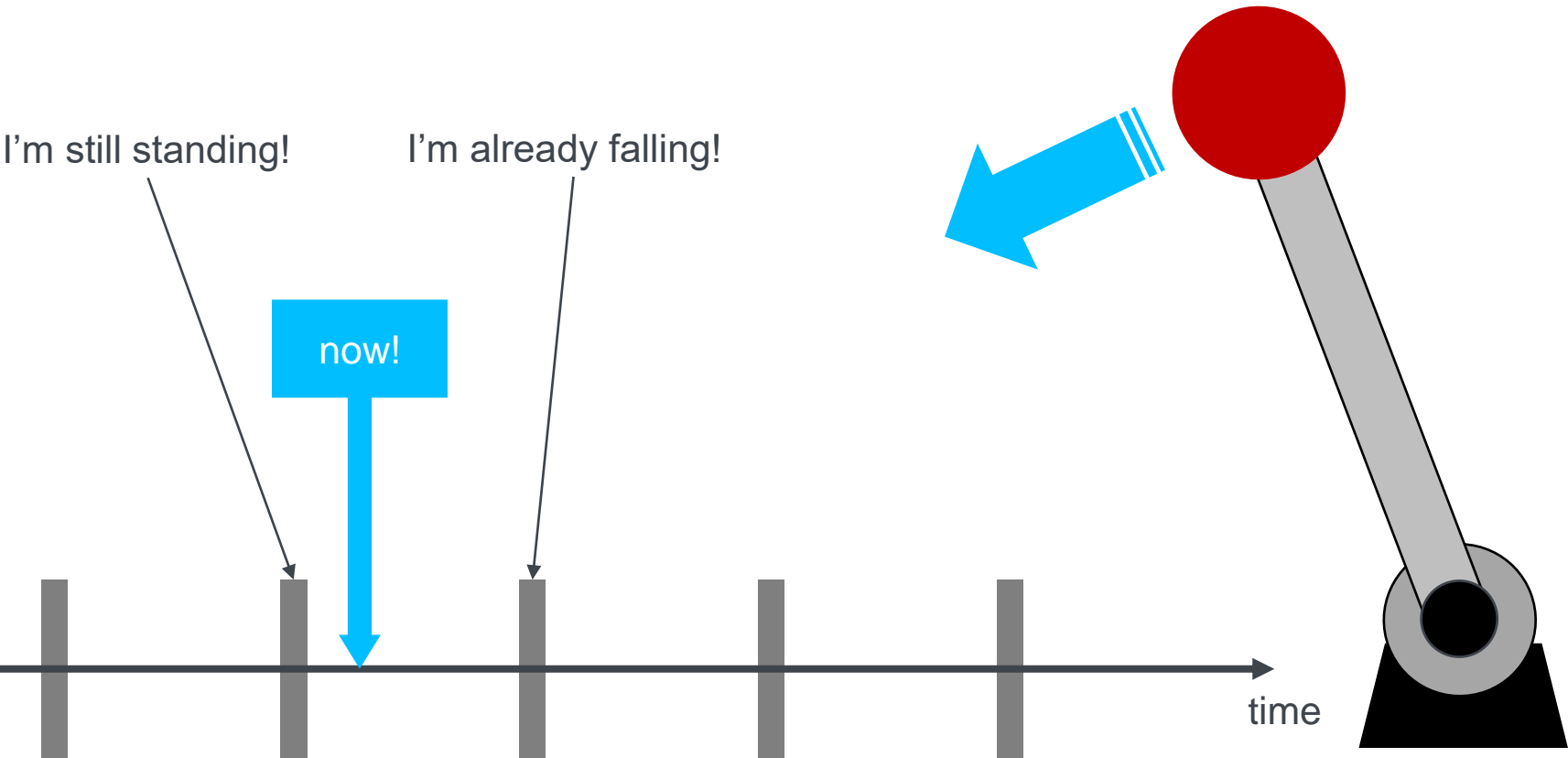
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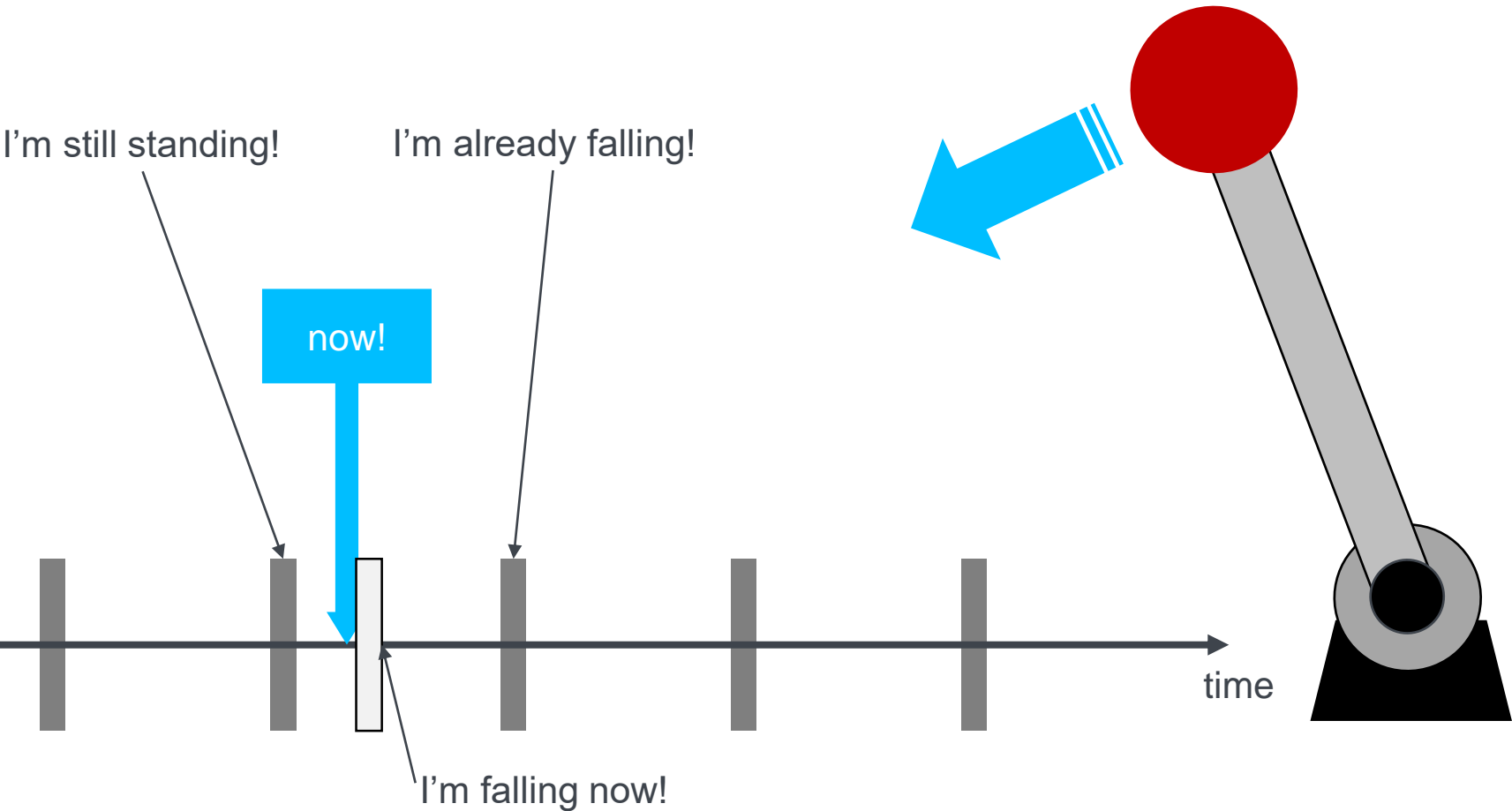
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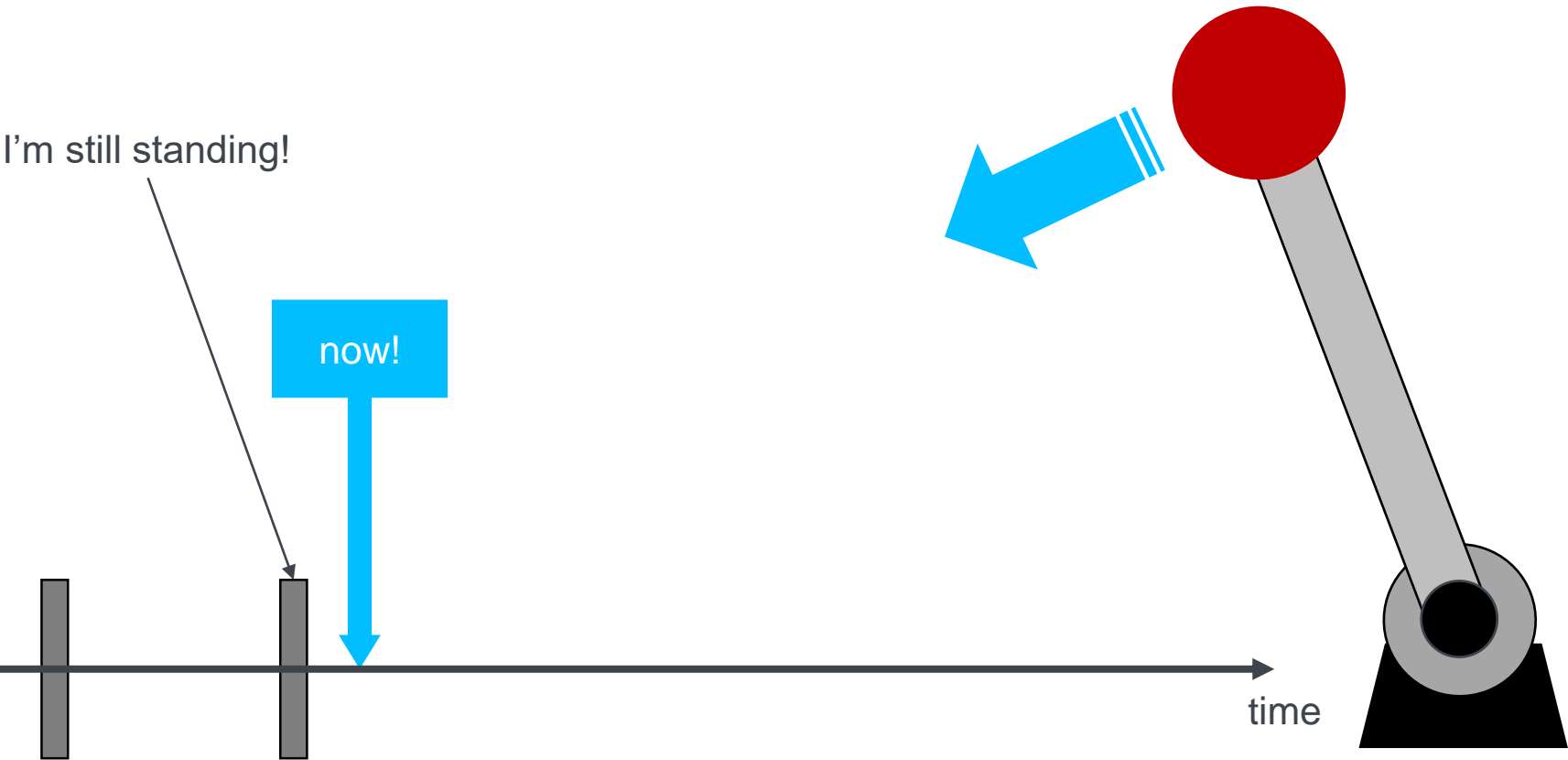
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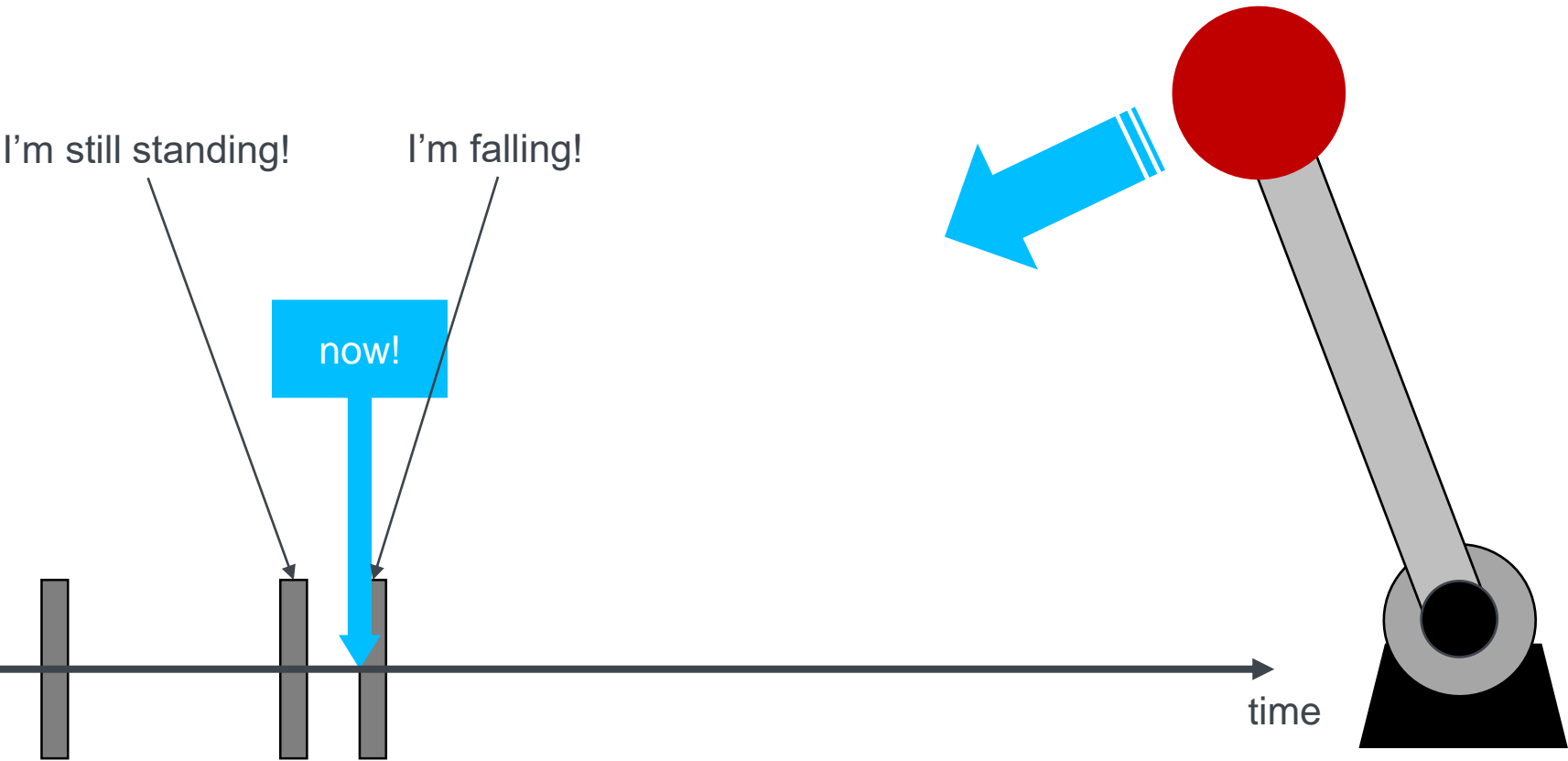
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Messages can have different "importance"



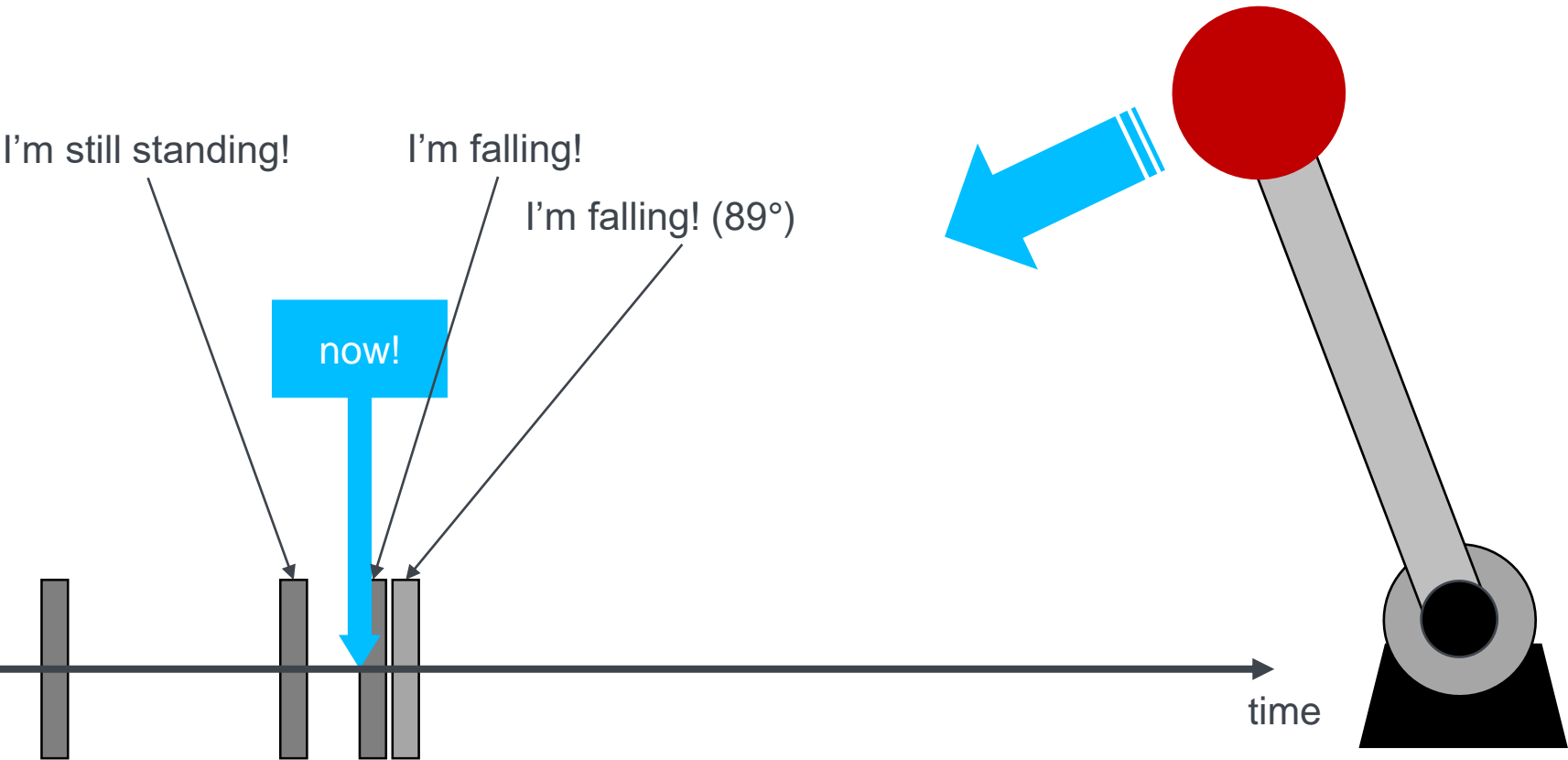
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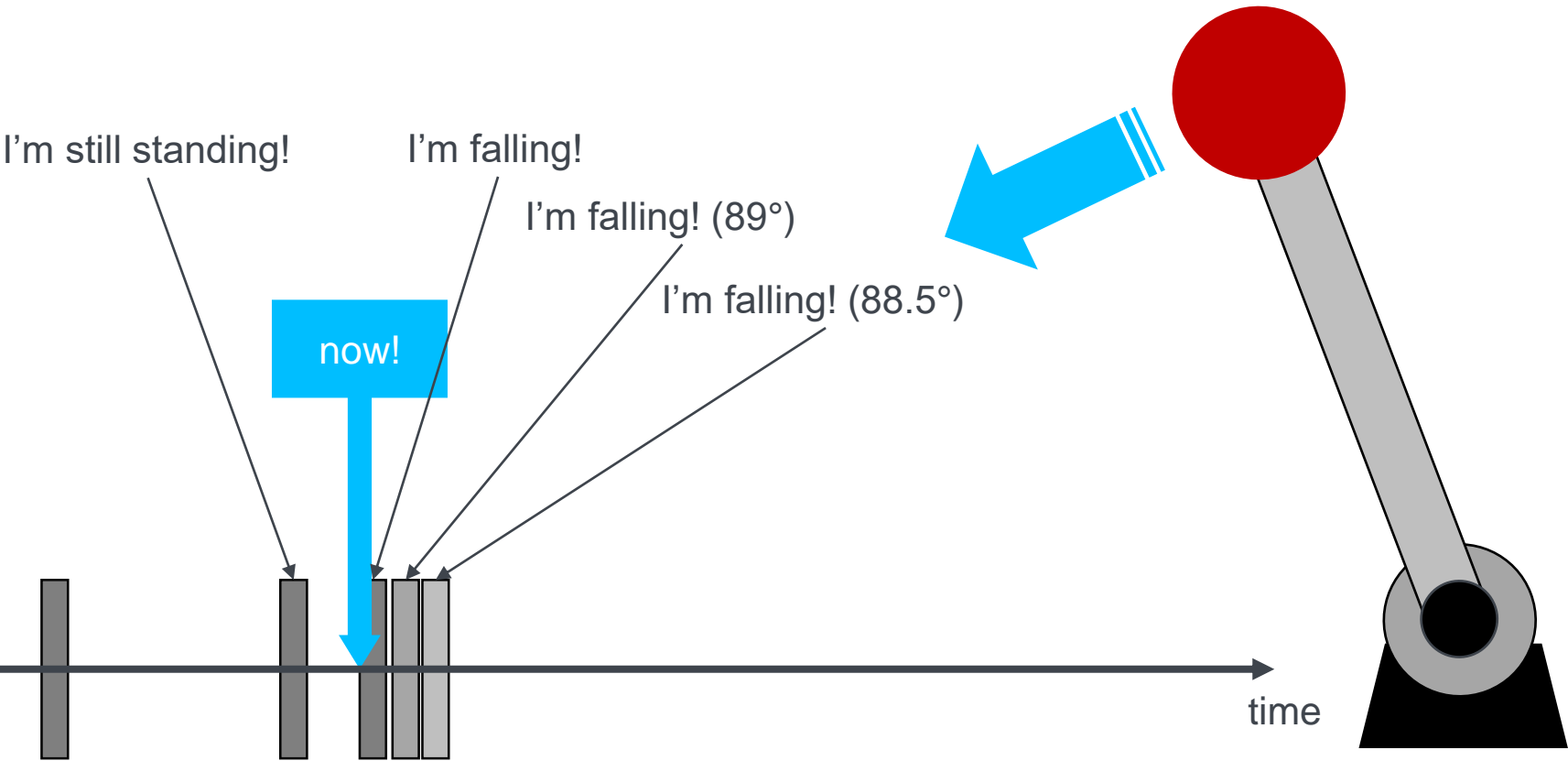
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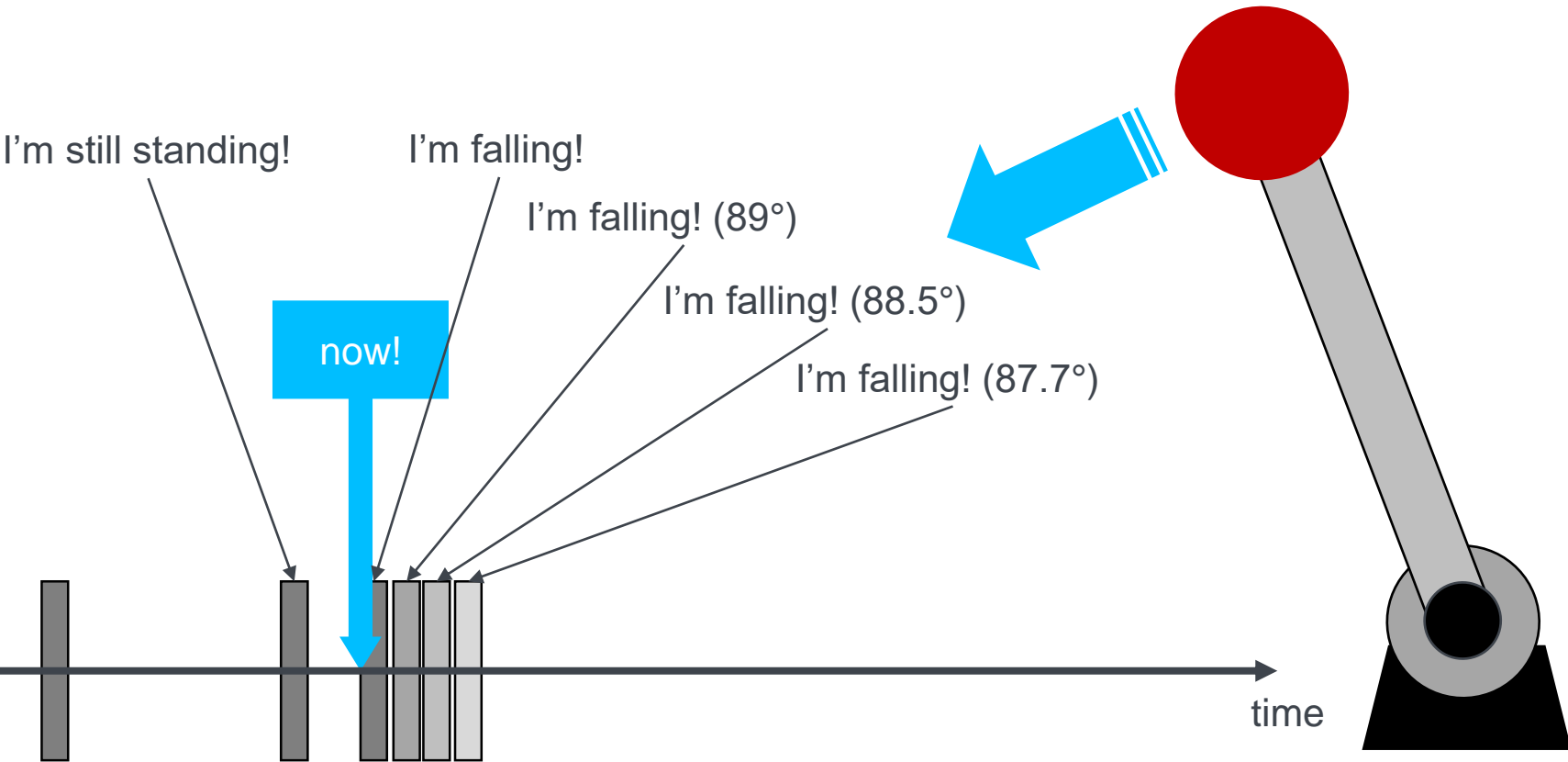
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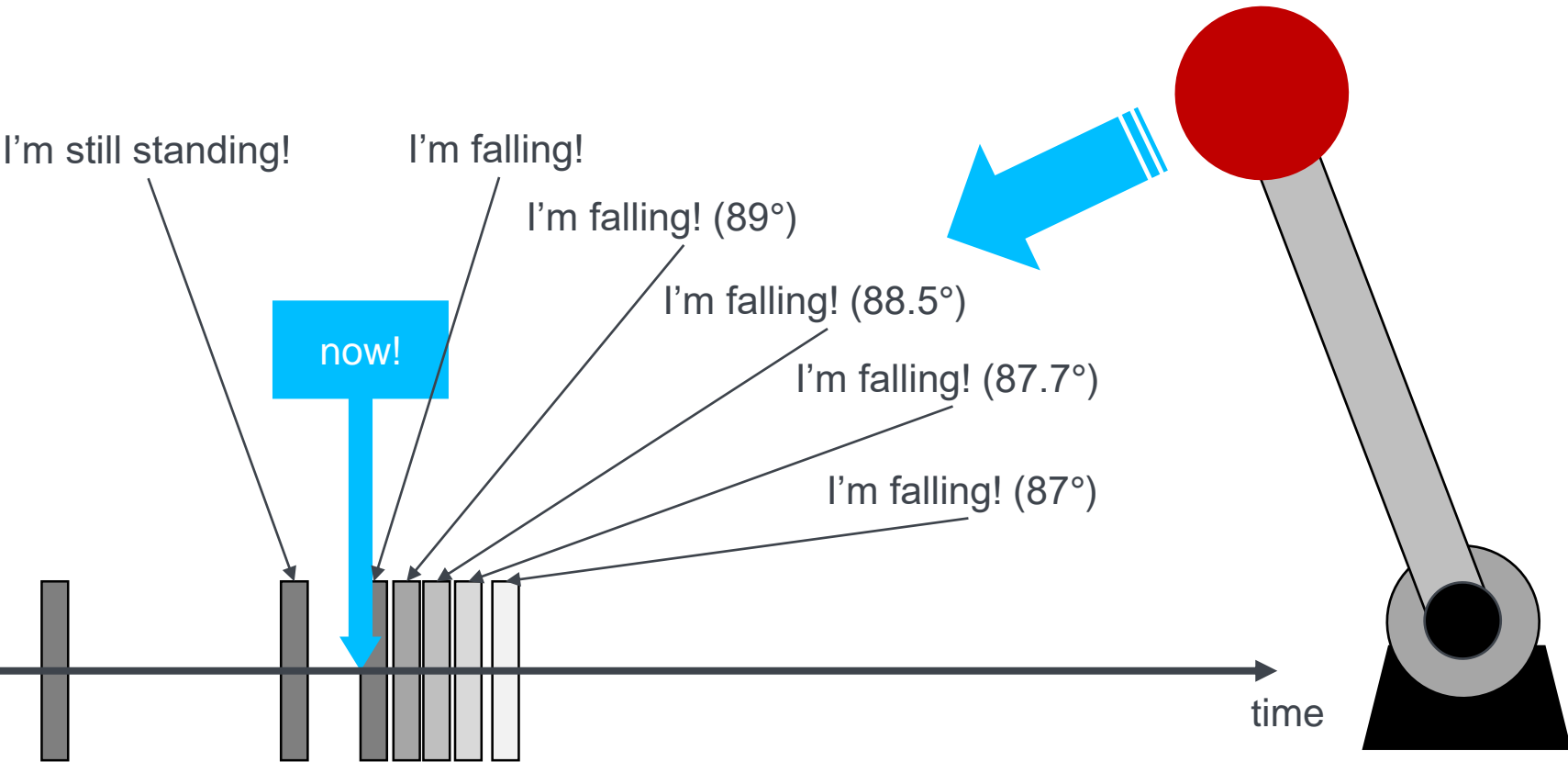
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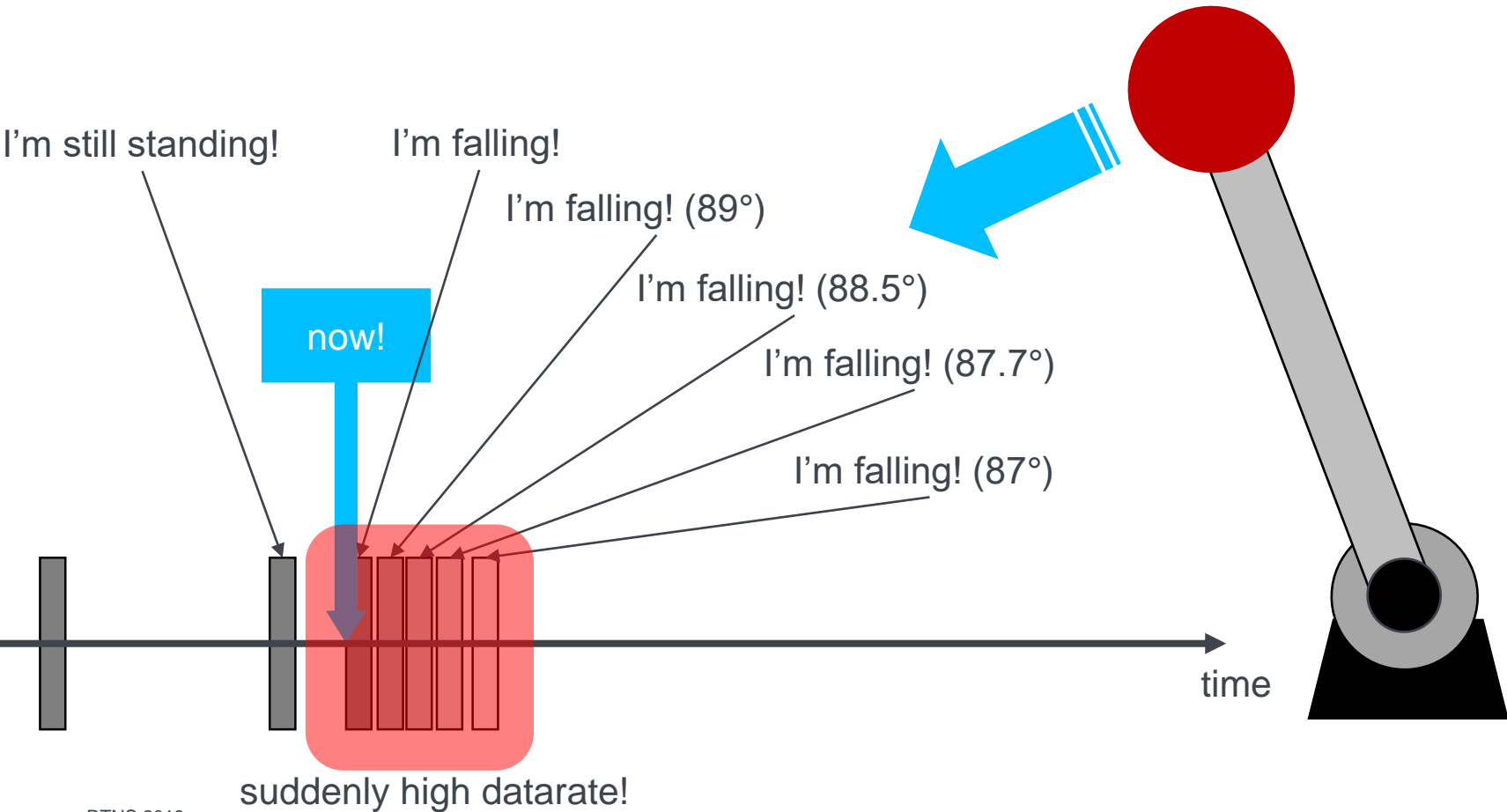
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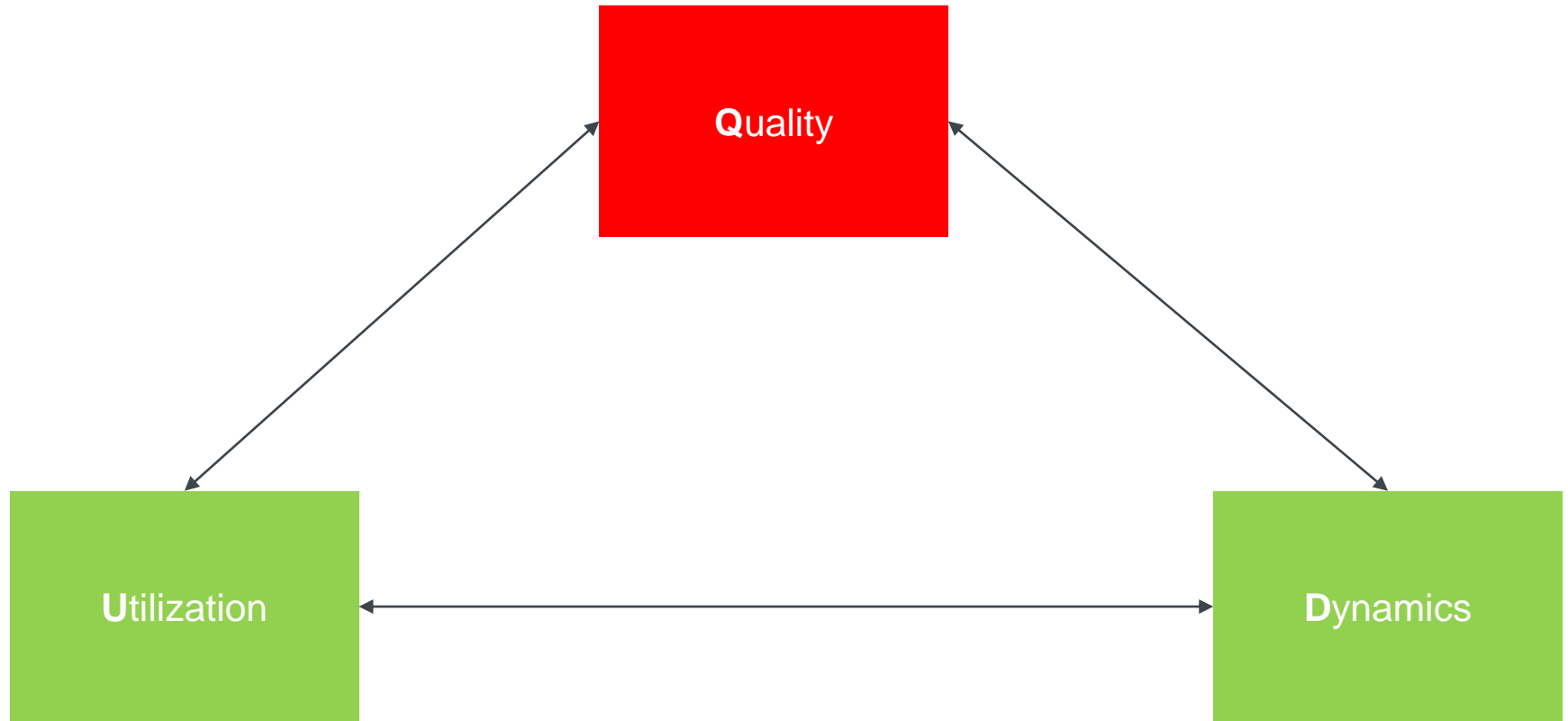
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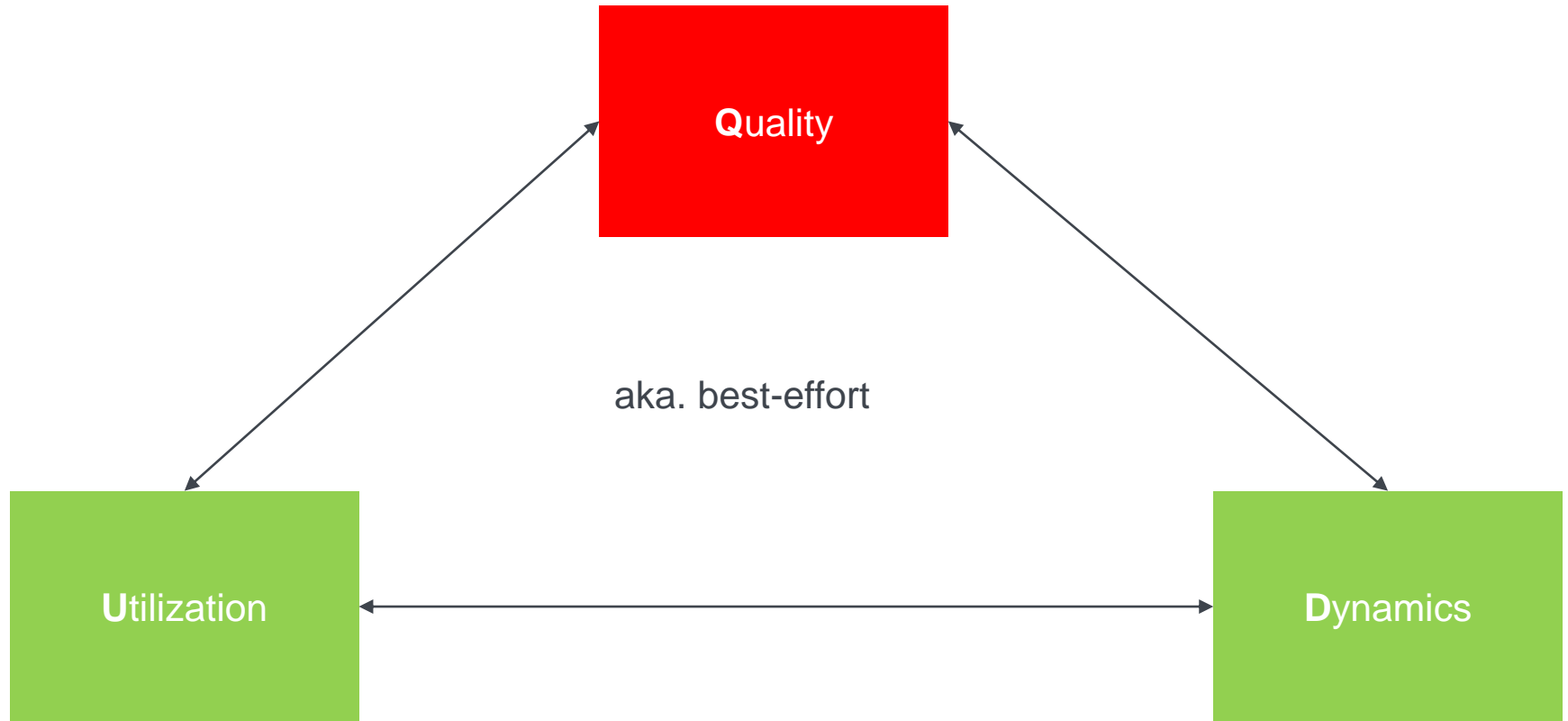
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Conflicts for real-time communication in shared networks



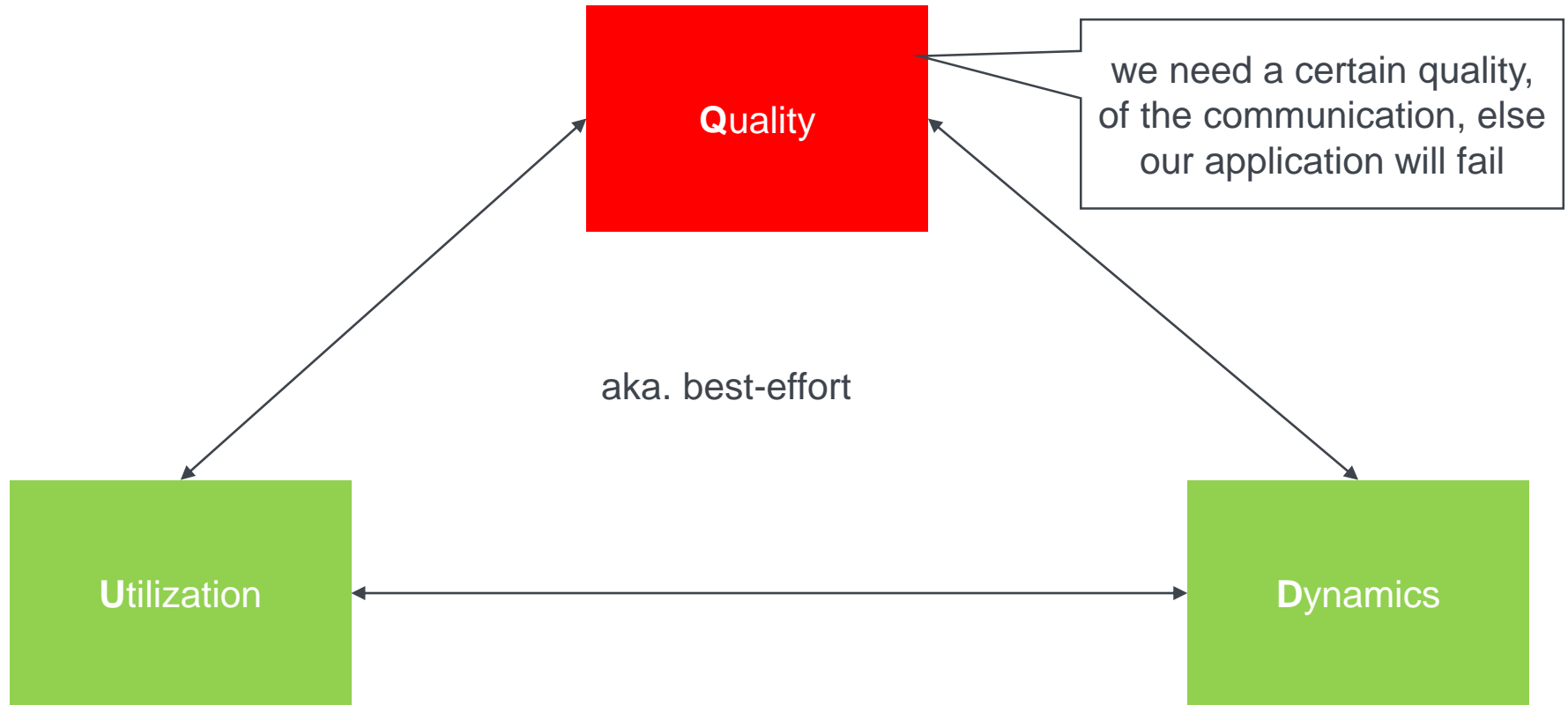
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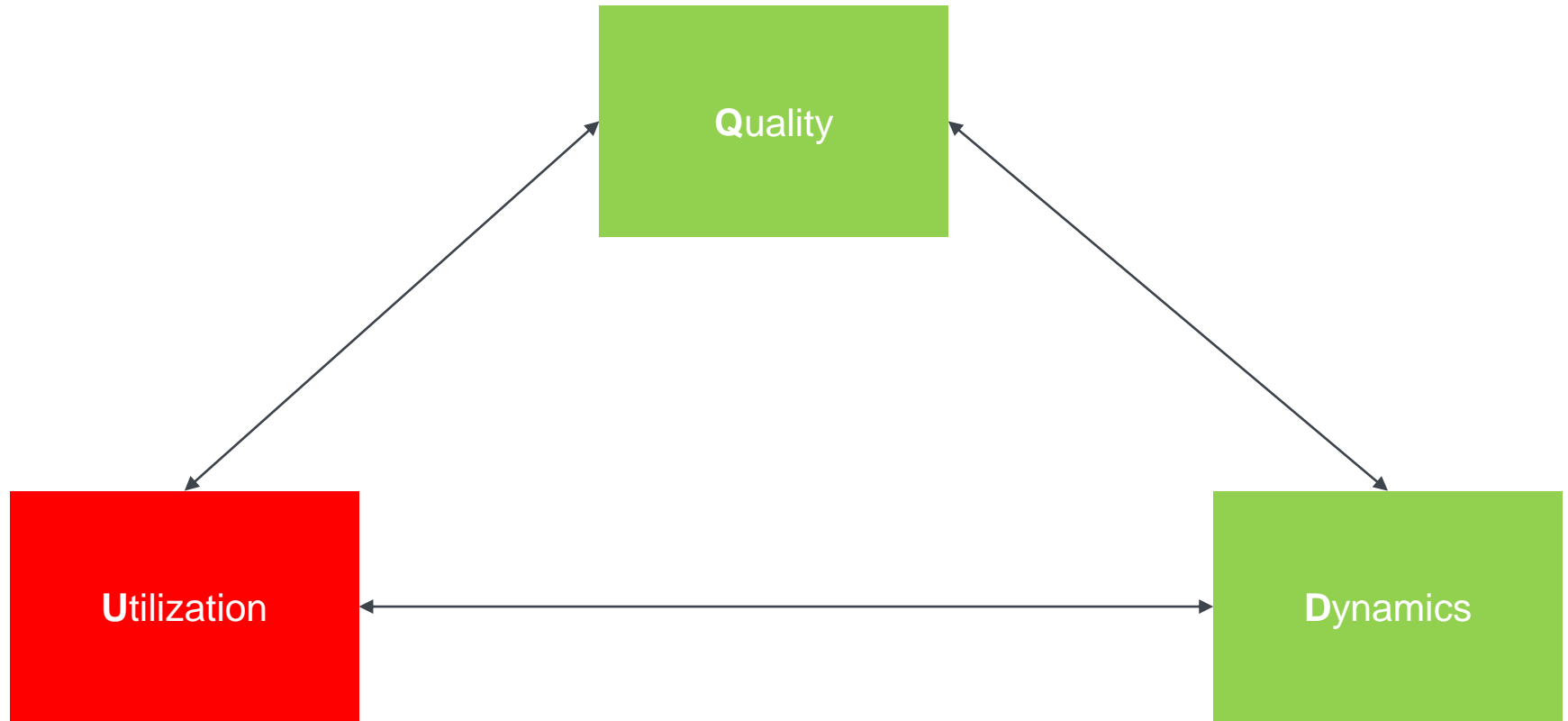
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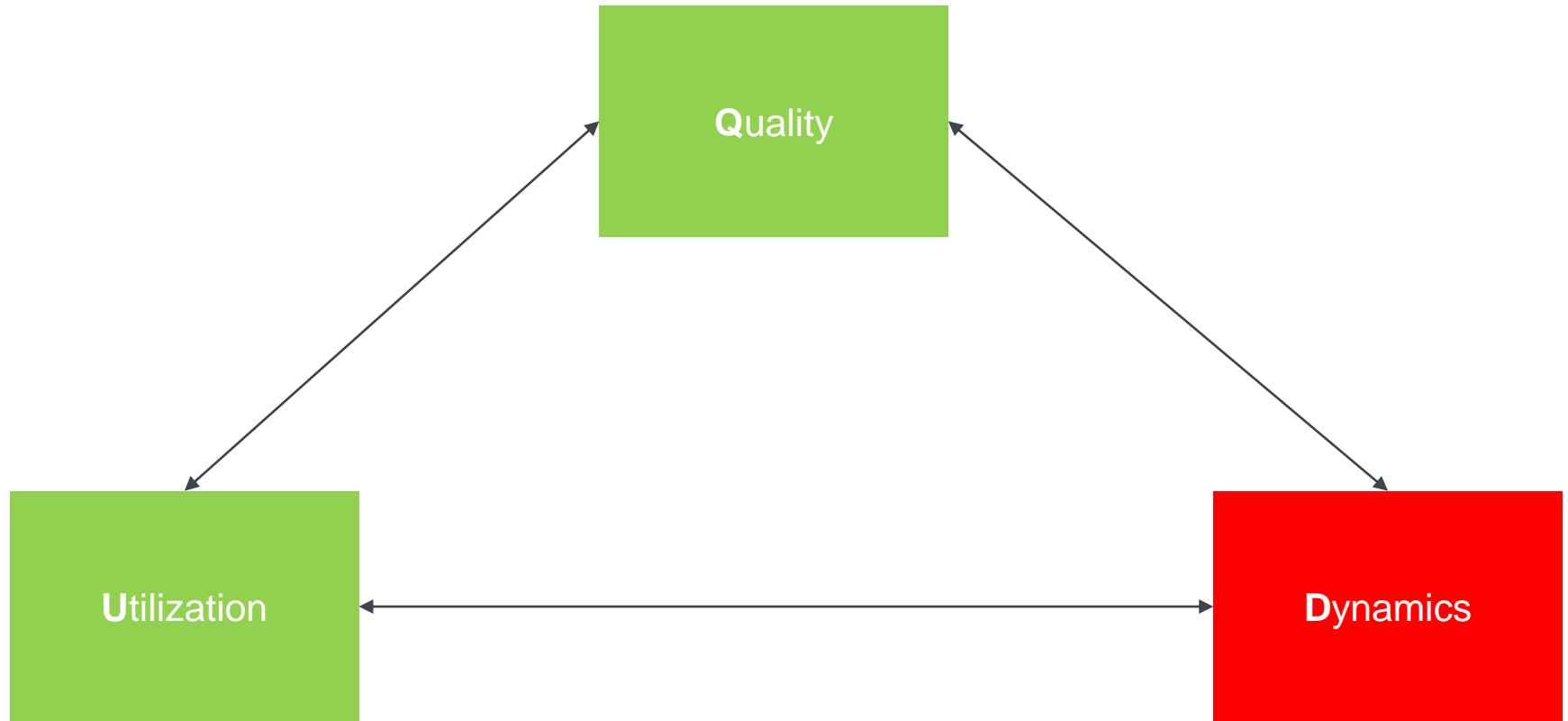
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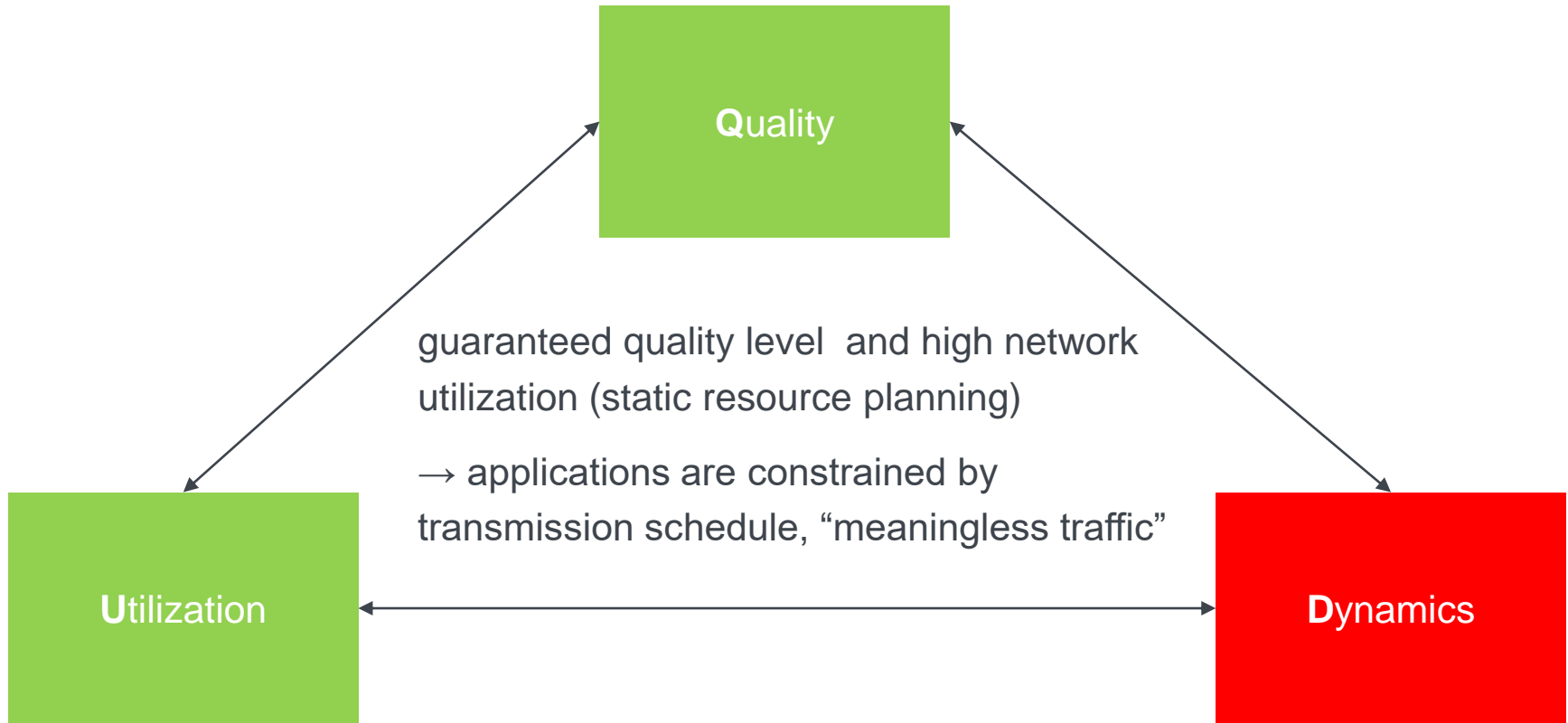
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Conflicts for real-time communication in shared networks



Contributions

Complemental flows

- guarantee (minimal) communication quality
 - allow (some) dynamics to improve application performance
 - account for “utility” of messages for the application via traffic metric
-
- How to route and schedule supplemental flows?

Complemental flows

Quality

- Application:
 - periodic transmissions
 - certain level of application performance is guaranteed (e.g., stability of control-system)
- Network:
 - well-specified traffic (when, how much data)
 - delivery with bounded delay

deterministic traffic part



Complemental flows

Dynamics

opportunistic traffic part

- Application:
 - transmit, “when it makes sense”, e.g., unforeseen external disturbance
 - improve application performance beyond minimum
 - traffic metric
- Network:
 - dynamic traffic load
 - relaxed (or no) guarantees



Complemental flows

Applications?

- Control systems:
 - Linsenmayer, S., B. W. Carabelli, F. Dürr, J. Falk, F. Allgöwer, and K. Rothermel..
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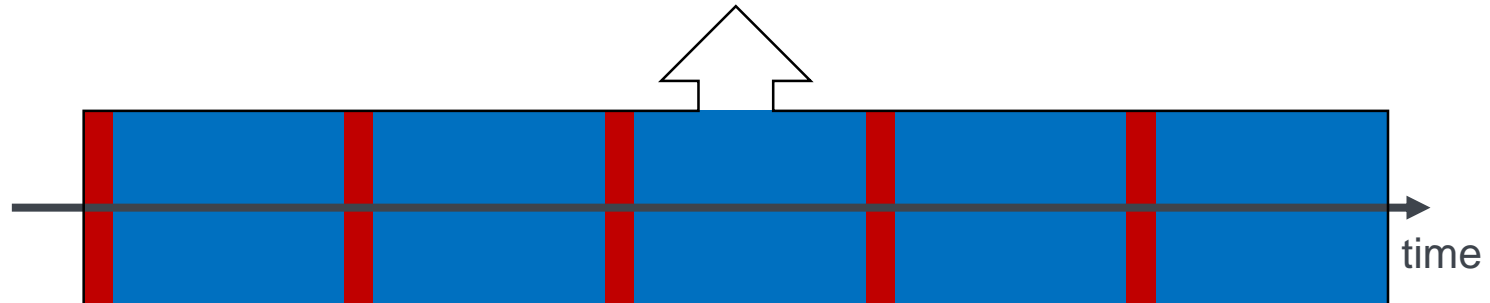


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deterministic and opportunistic messages are temporally and semantically interrelated!



Complemental flows

opportunistic traffic part

deterministic traffic part

Traffic
Engineering?

Complemental flows?

opportunistic traffic part

best effort /
shaped traffic

deterministic traffic part

time-triggered traffic

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Craciunas, et. al, "Scheduling Real-Time Communication in IEEE 802.1Qbv Time Sensitive Networks.", RTNS '16

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relation between time-triggered and non-time-triggered traffic?

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Traffic Engineering

Problem

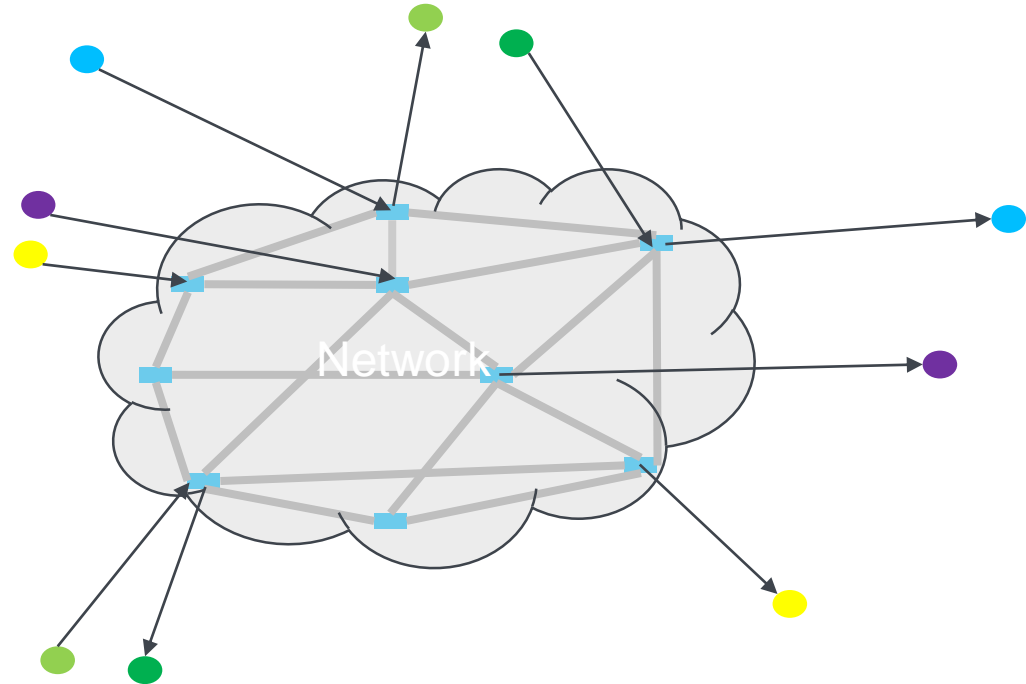
Input:

- Network Topology (graph)
- Set of flows (including requirements and specifications for **deterministic** and **opportunistic** traffic part)

Output:

Optimal traffic configuration:

- route (connected sequence of edges from source to destination of flow)
- schedule (i.e., *phase* of deterministic transmissions)
- optimal with respect to expected opportunistic traffic



Traffic Engineering

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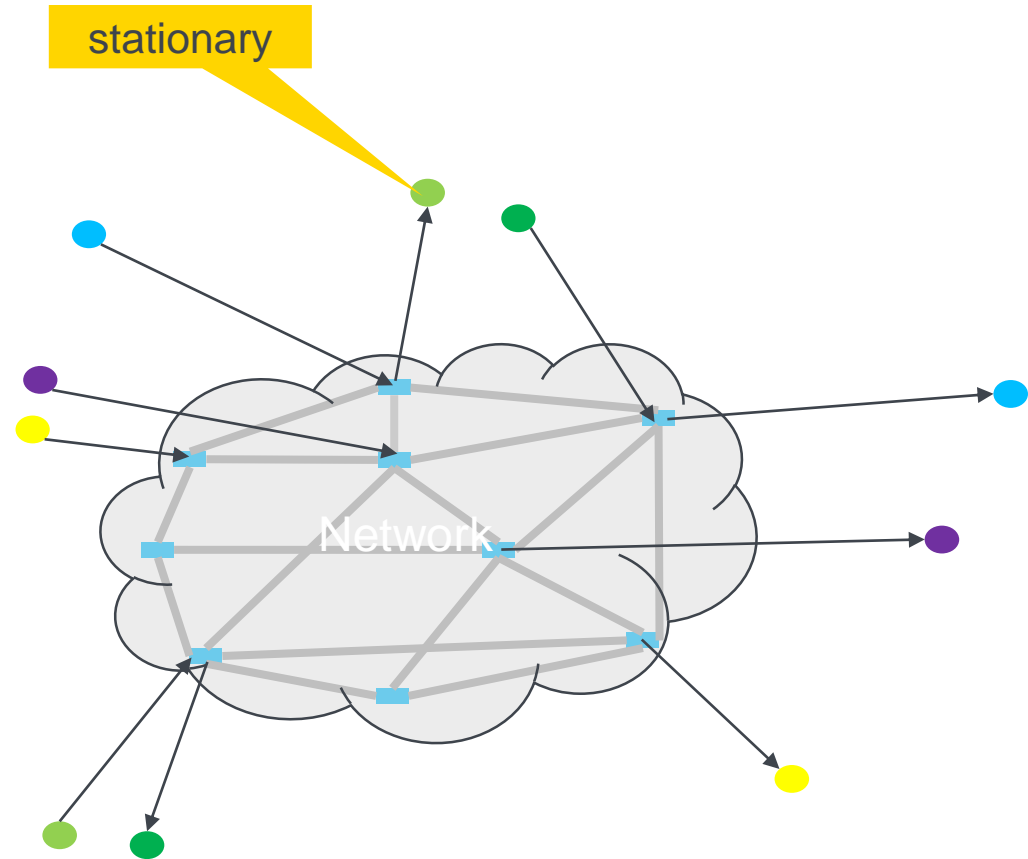
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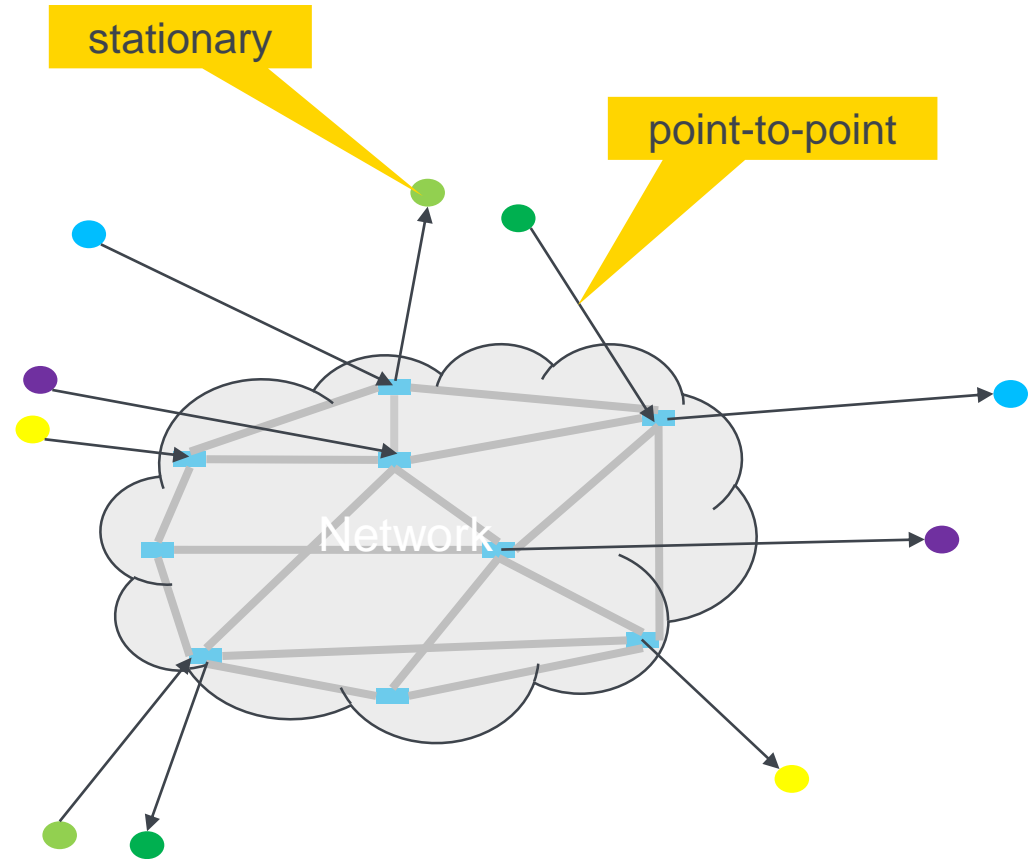
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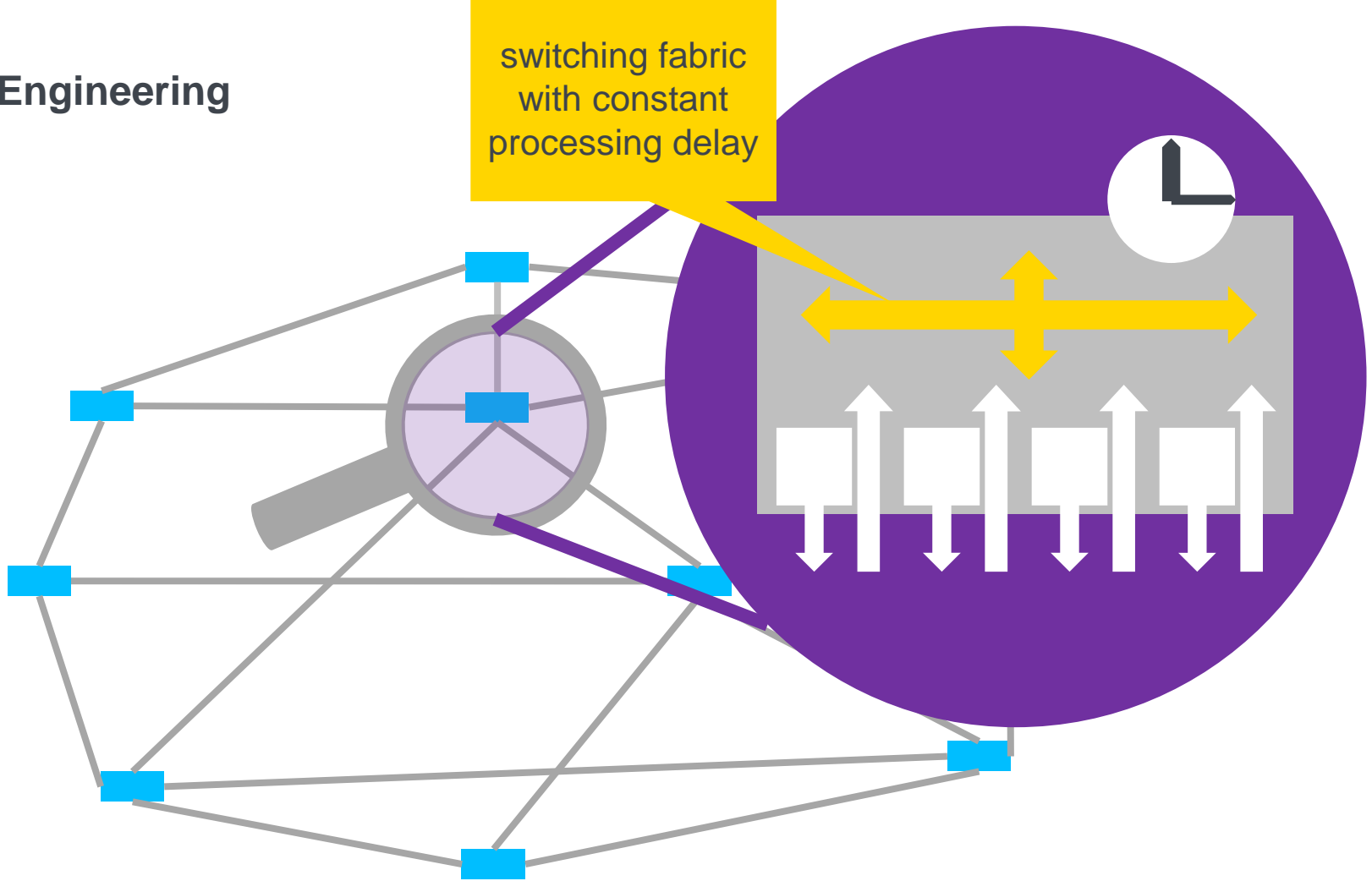
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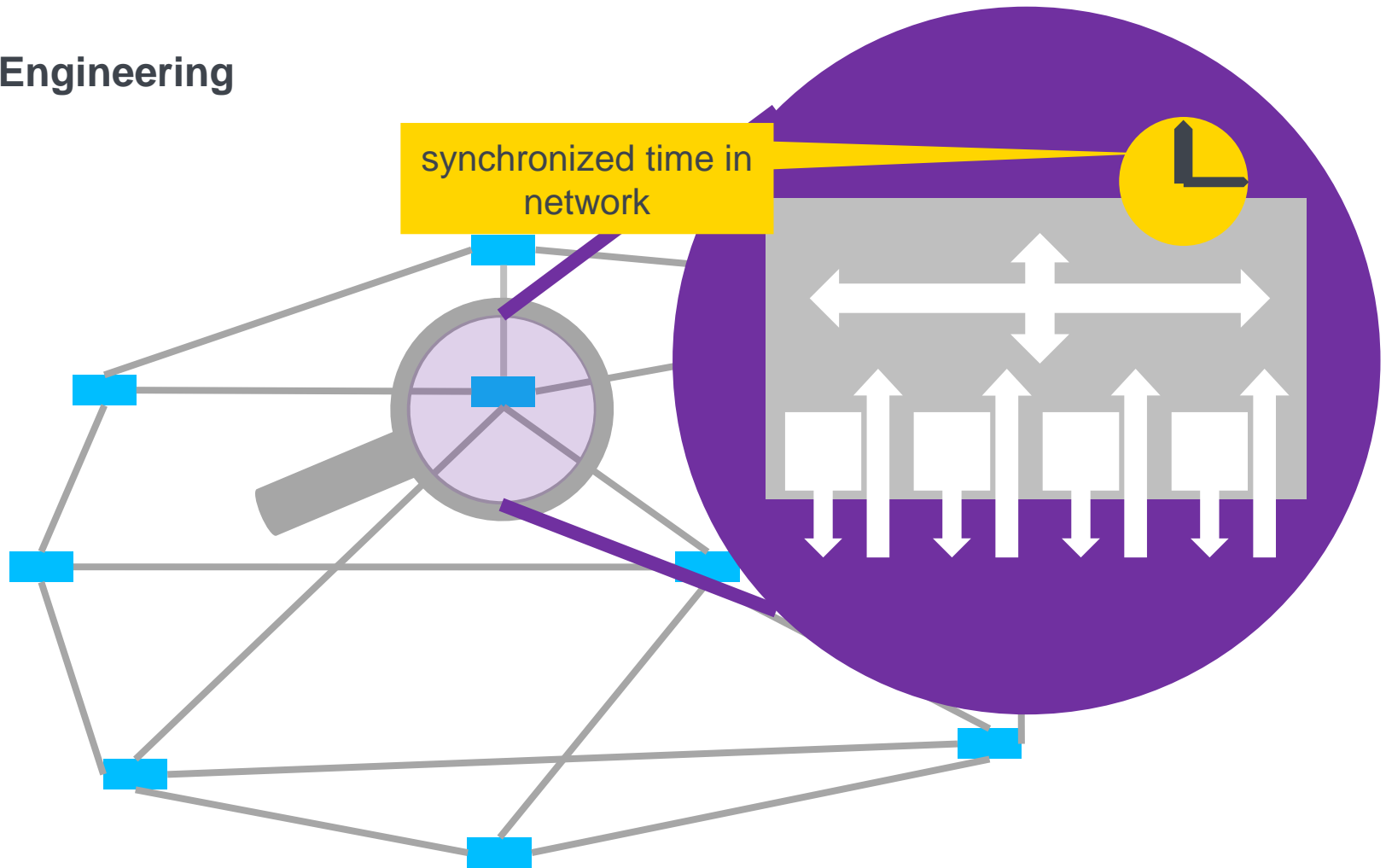
Traffic Engineering

Switch



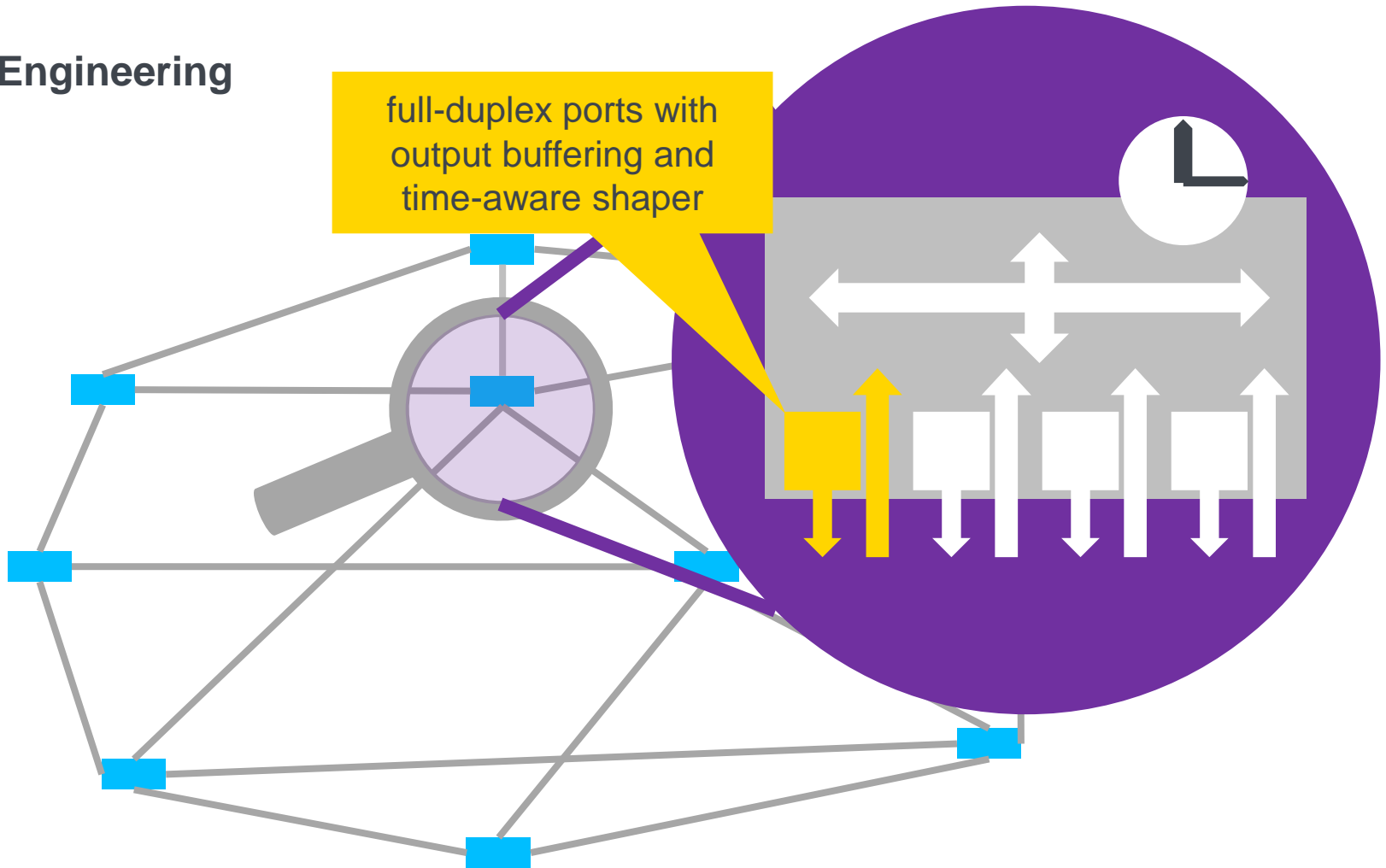
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Switch



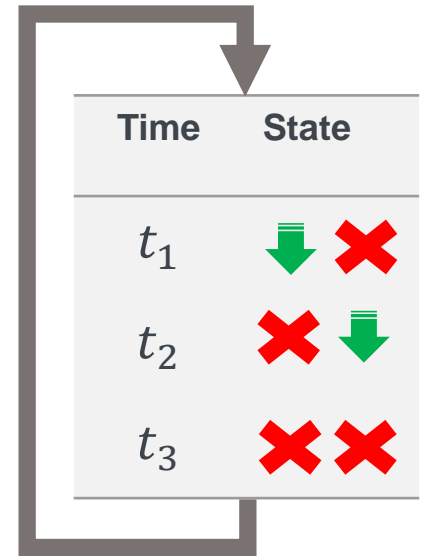
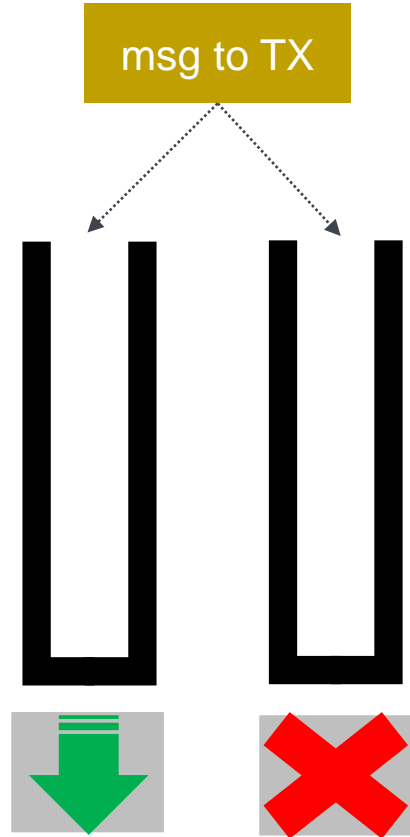
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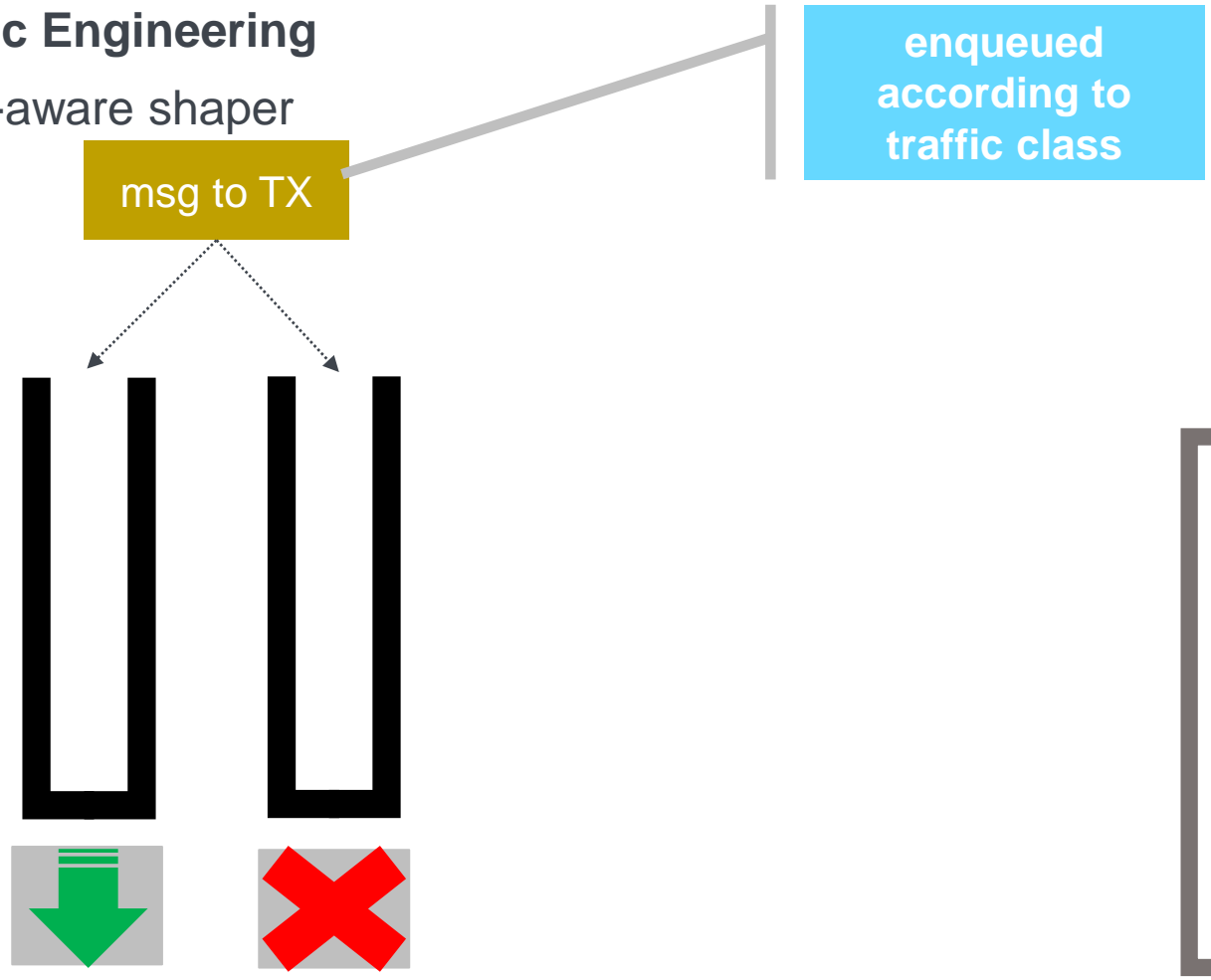
Traffic Engineering

Time-aware shaper



Traffic Engineering

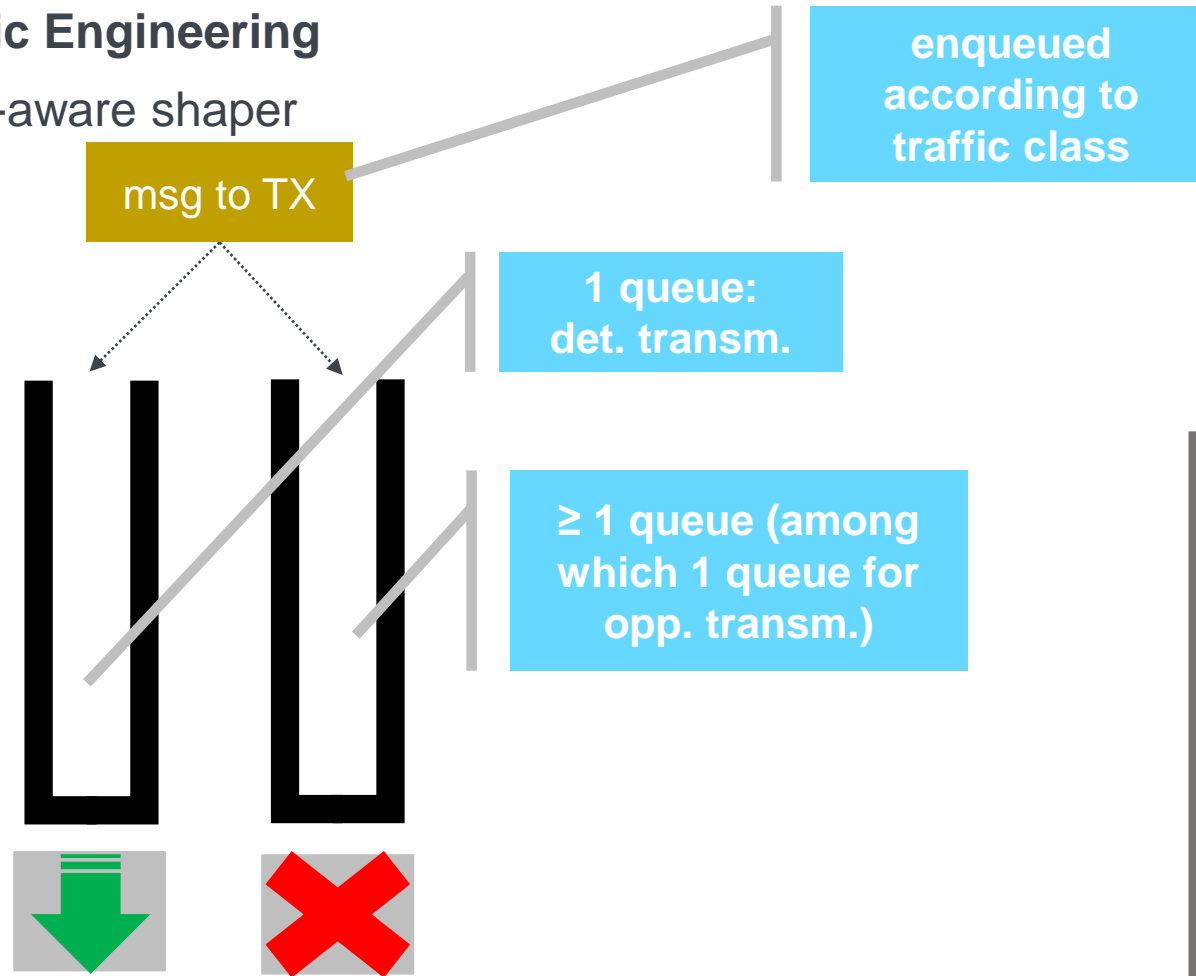
Time-aware shaper



Time	State
t_1	↓ ×
t_2	× ↓
t_3	× ×

Traffic Engineering

Time-aware shaper

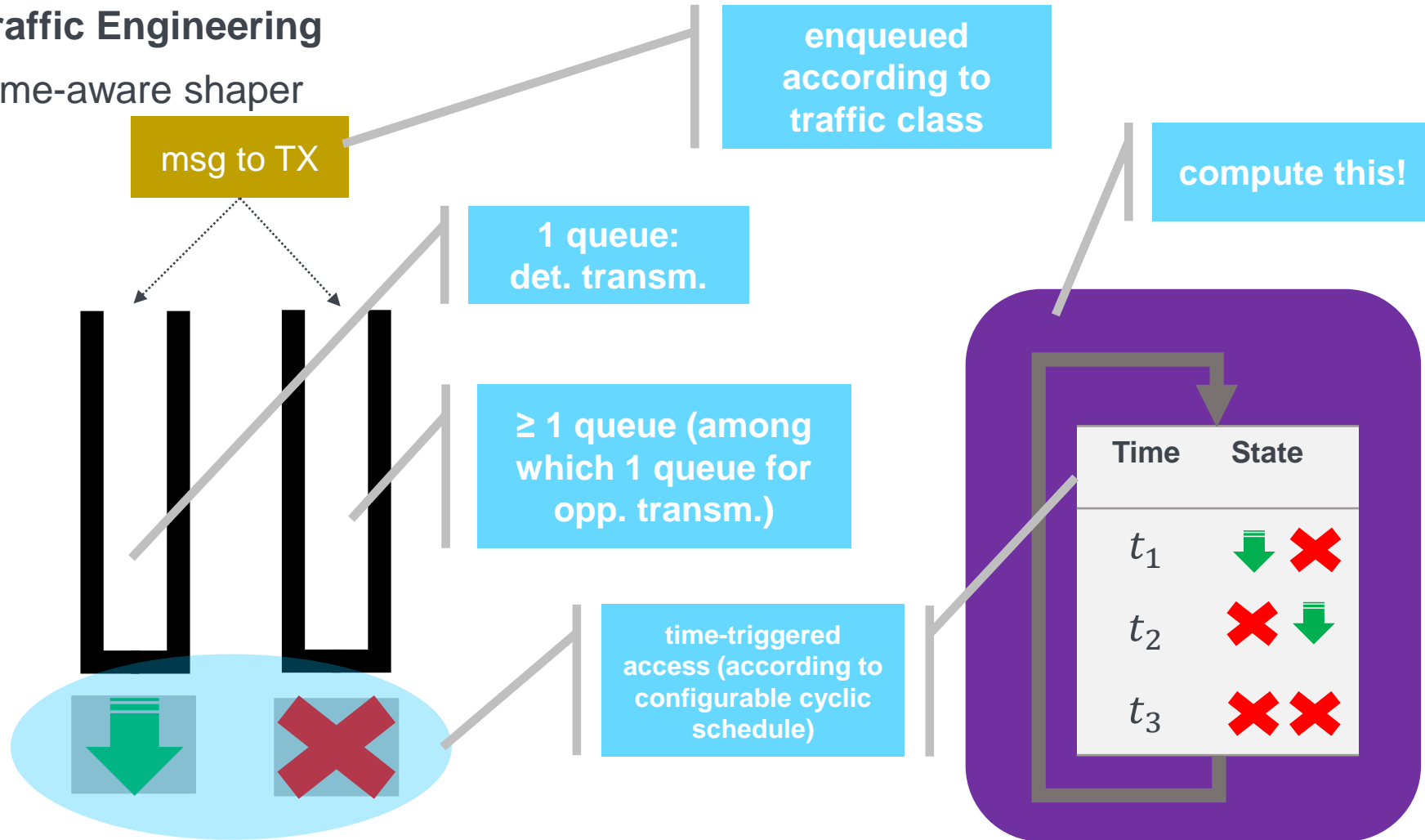


A timeline diagram showing a sequence of states over time. A grey arrow points down to a table with two columns: "Time" and "State". The table has three rows labeled t_1 , t_2 , and t_3 . The "State" column contains a green arrow pointing down and a red 'X' for t_1 , a red 'X' and a green arrow pointing down for t_2 , and two red 'X's for t_3 .

Time	State
t_1	↓ (green) X (red)
t_2	X (red) ↓ (green)
t_3	X (red) X (red)

Traffic Engineering

Time-aware shaper



Traffic Engineering

Traffic metric for opportunistic traffic

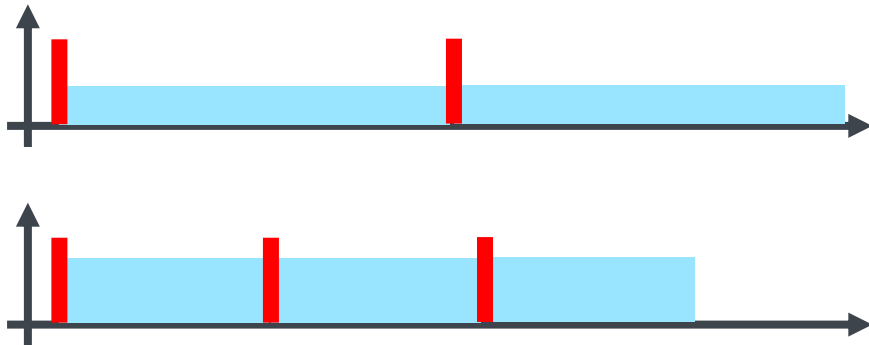
- relates application performance to opportunistic messages
- offline traffic-engineering, i.e., traffic metric is required a-priori
 - estimation
 - measurement
 - analysis
- additive

- different temporal granularity

Traffic Engineering

Traffic metric for opportunistic traffic
time-independent

- e.g., average bandwidth of opportunistic messages
- “scalar” value

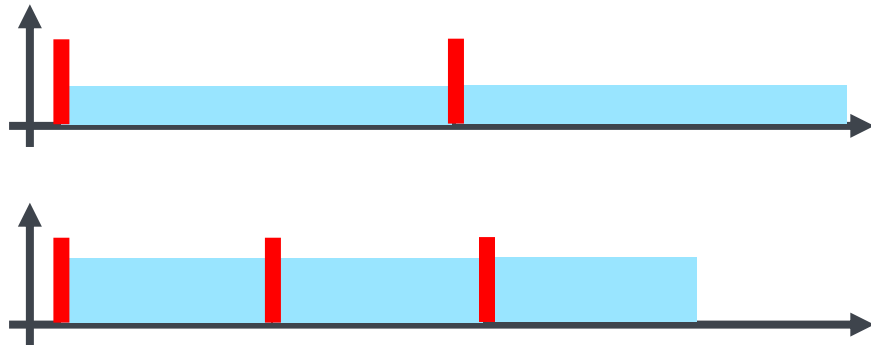


Traffic Engineering

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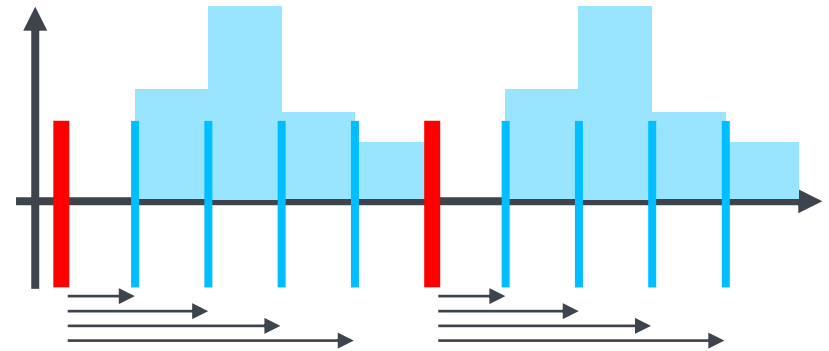
time-independent

- e.g., average bandwidth of opportunistic messages
- “scalar” value



time-dependent

- e.g., average probability of transmission (expected traffic load)
- deterministic messages are “renewal” points



Traffic Engineering

Two approaches: mixed integer linear programming

Edge-granularity routing and time-independent traffic metric:

- MILP decides for each individual edge whether it is part of the route
- min-max to reduce globally highest value of the accumulated traffic metric (i.e., aiming for more even traffic distribution)

➤ freedom in routing

➤ deterministic transmissions impose constraints on **feasibility**

➤ opportunistic transmissions influence **optimality**

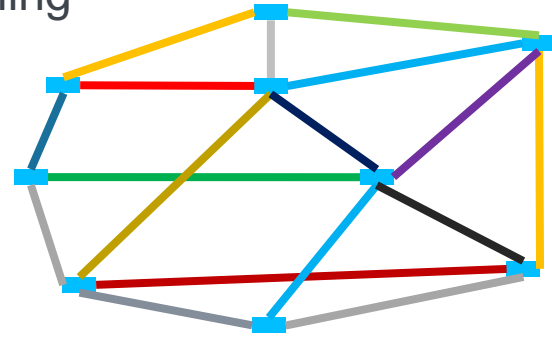
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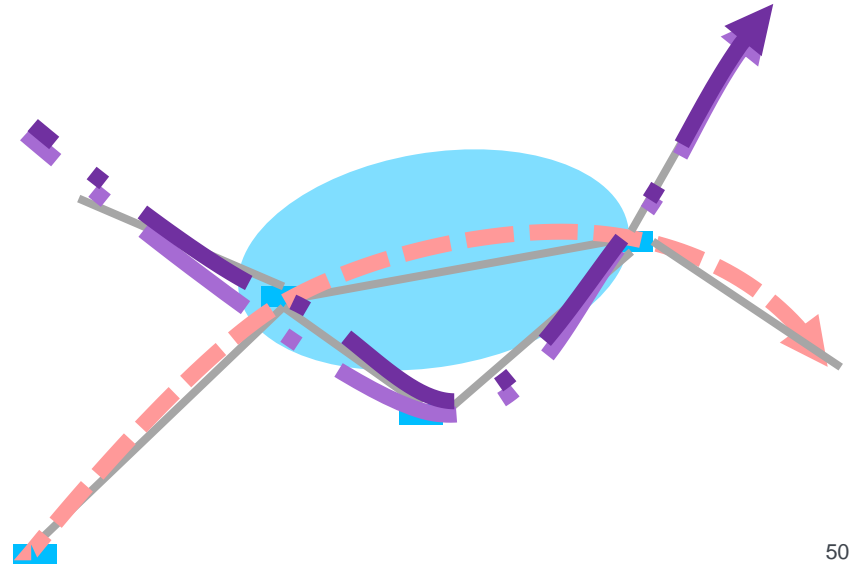
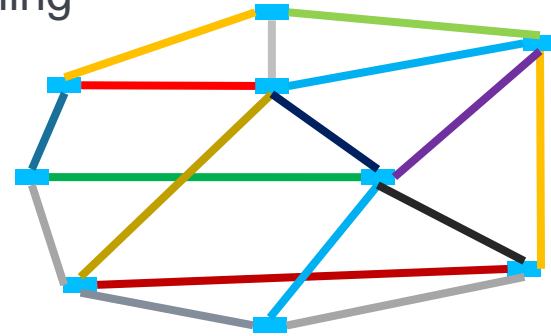
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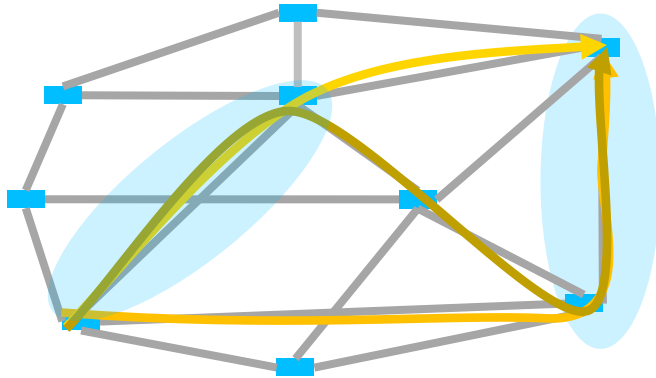
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- MILP chooses pre-computed path as route for each flow
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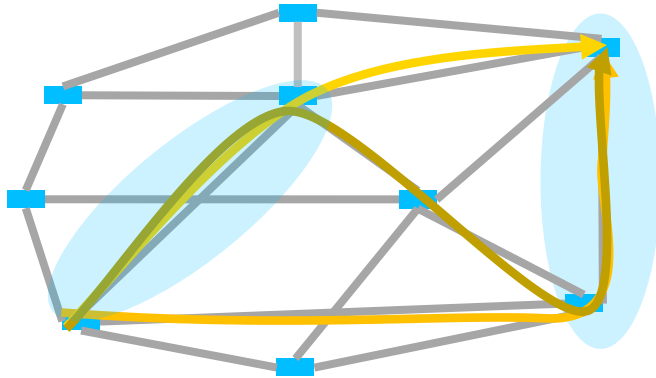
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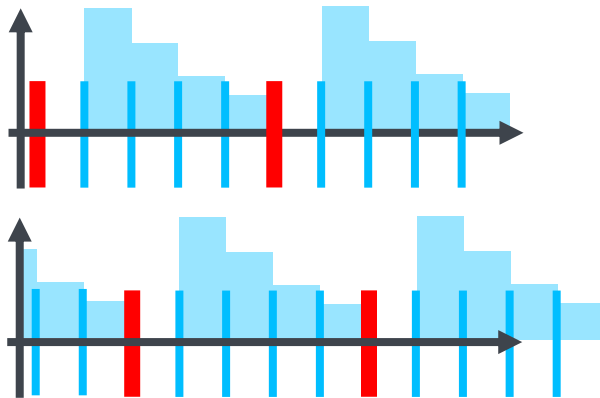
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Traffic Engineering

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- possibly more freedom in routing
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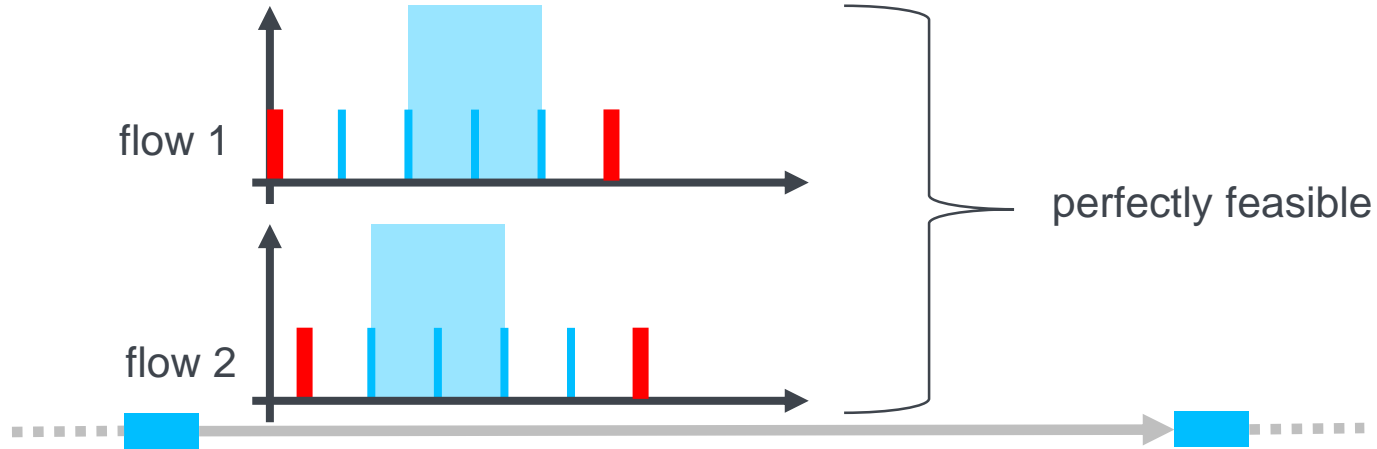
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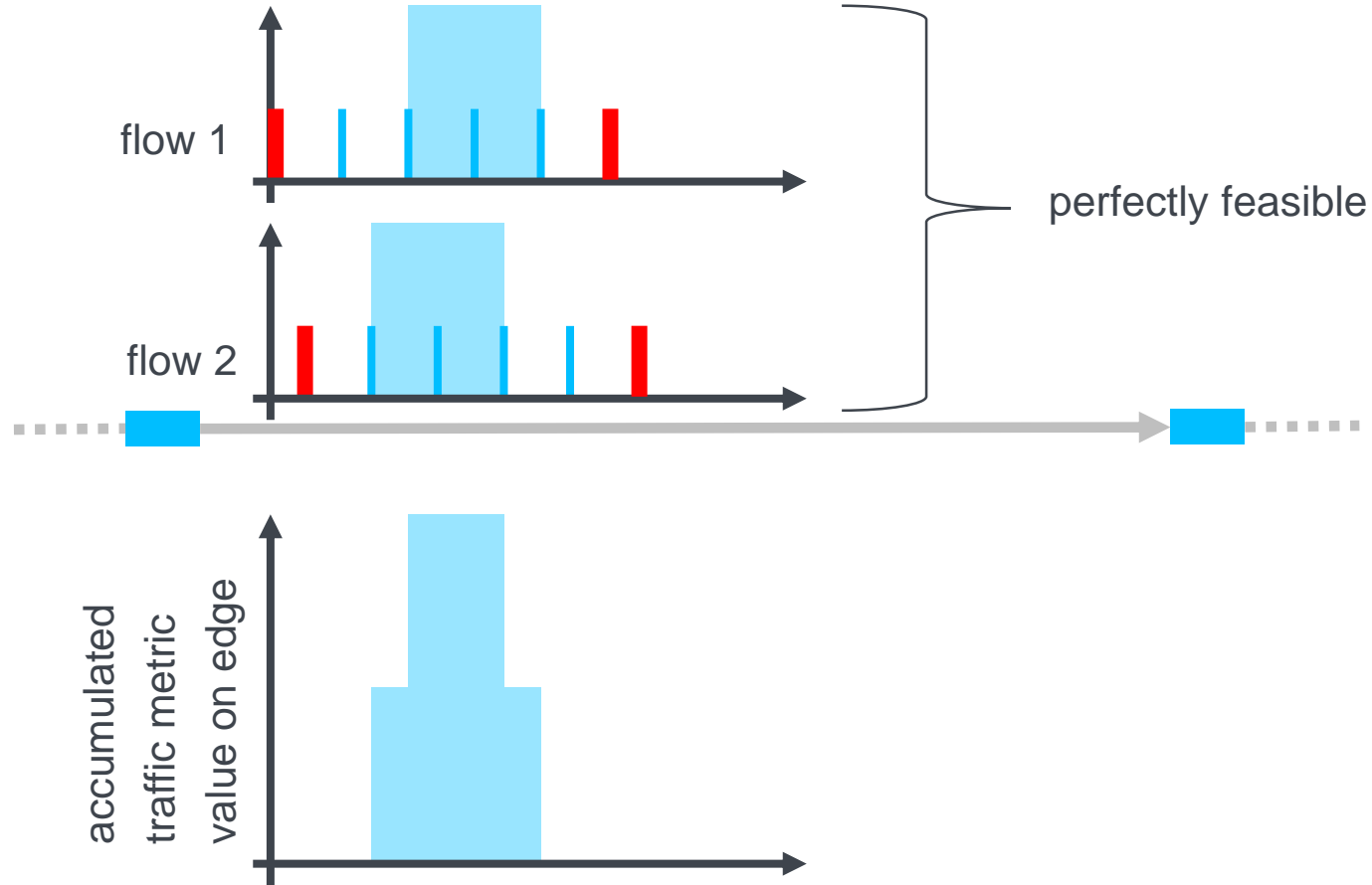
MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Min-max objective



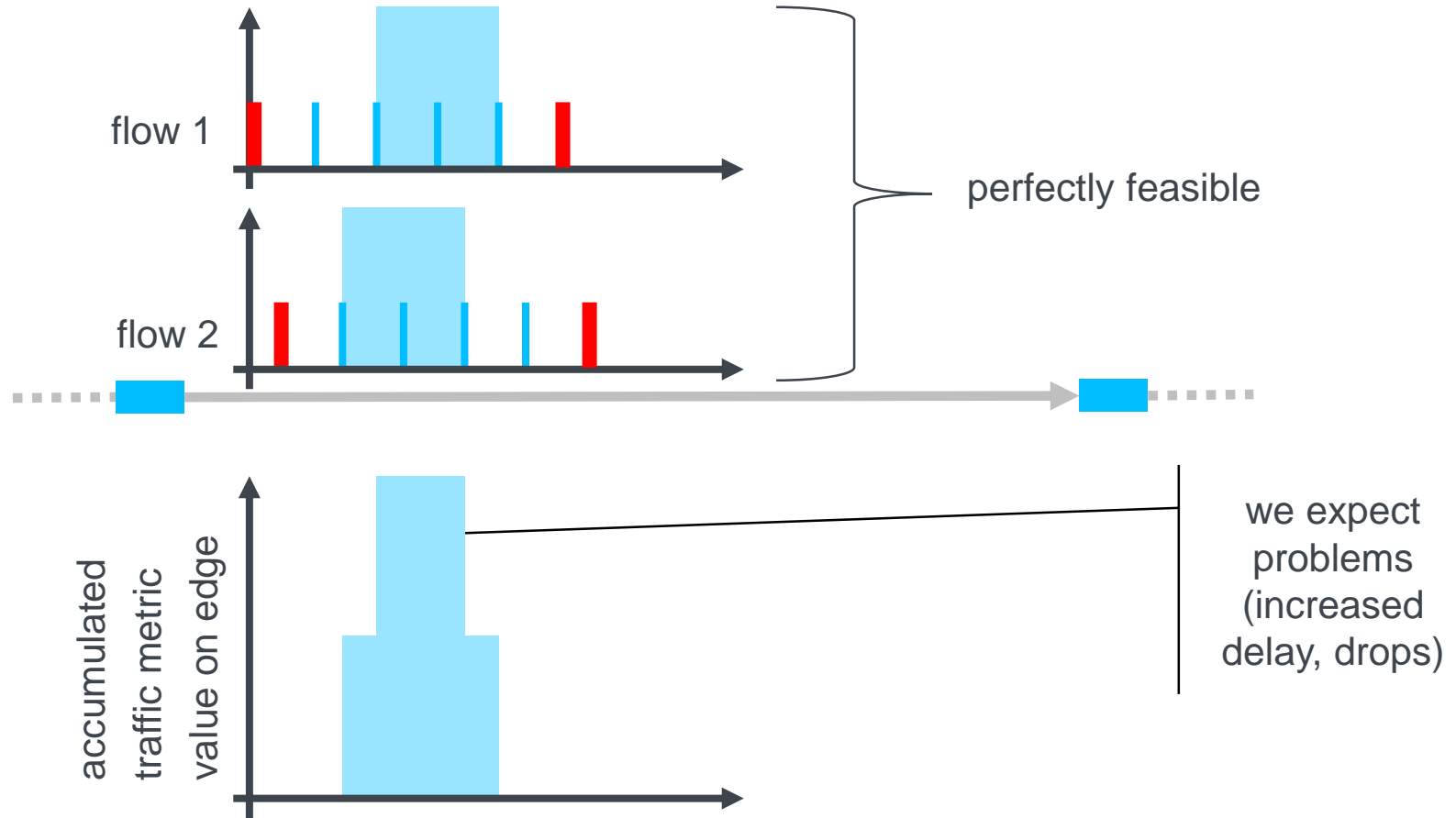
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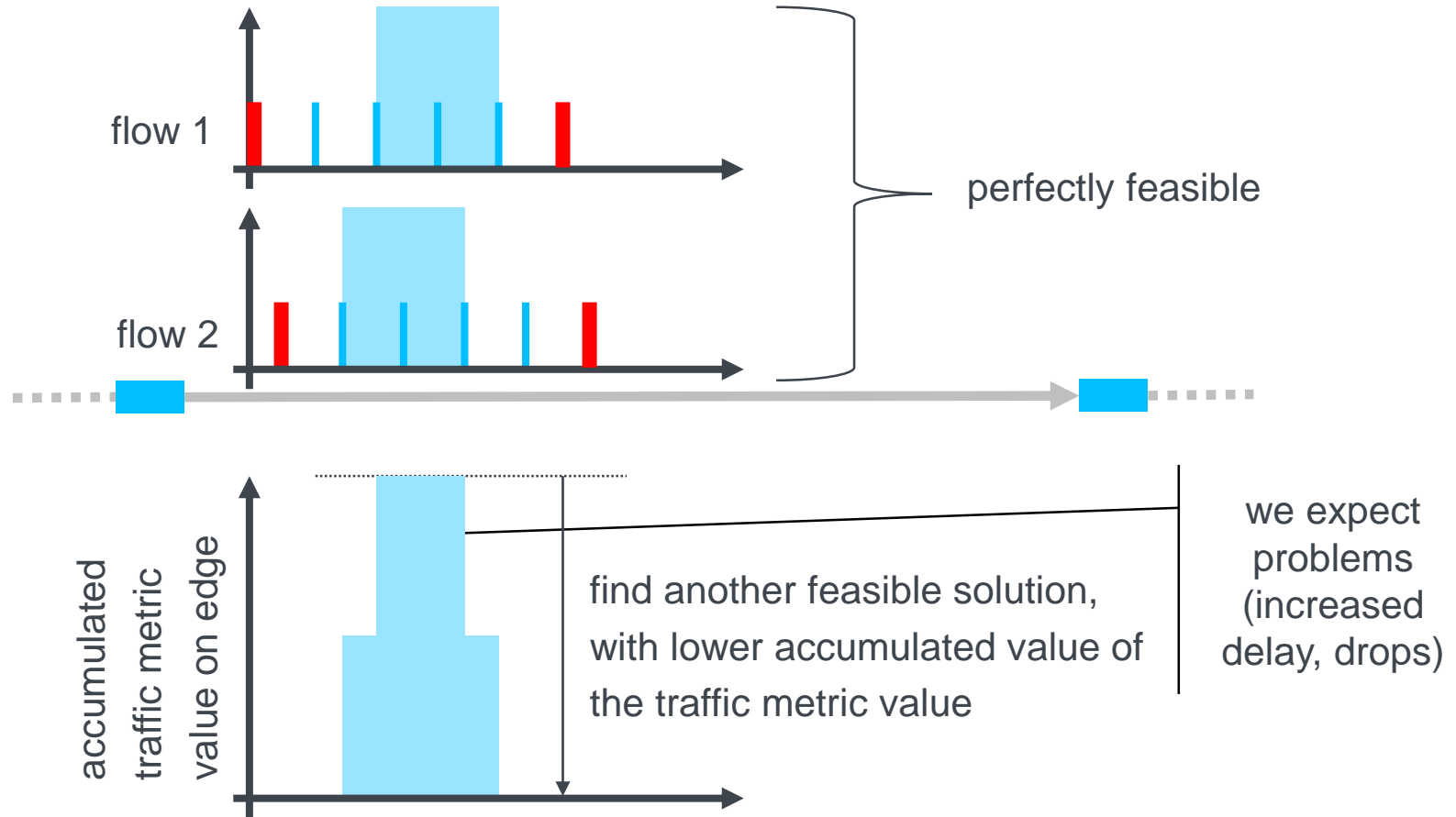
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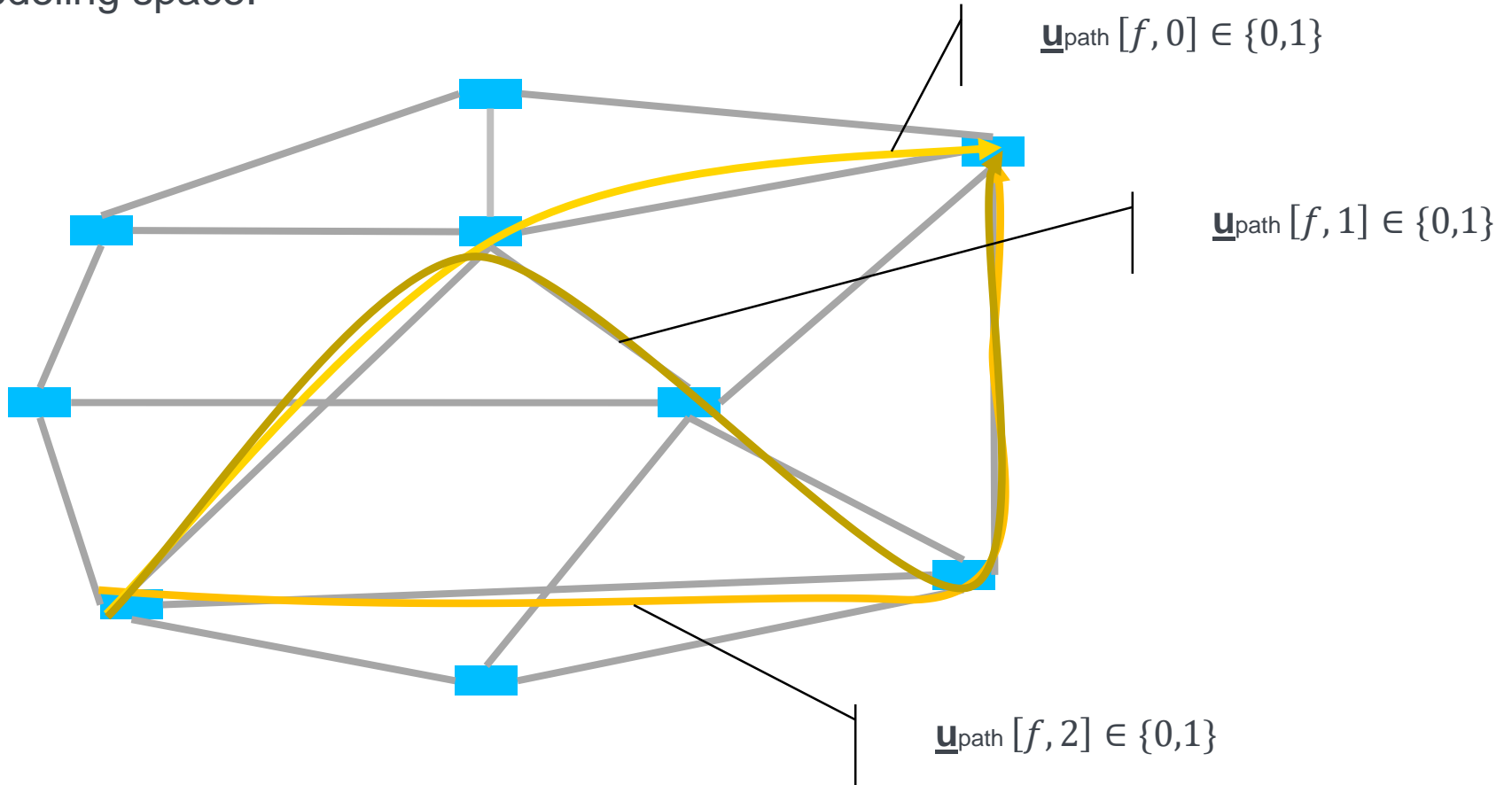
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MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Modeling space.

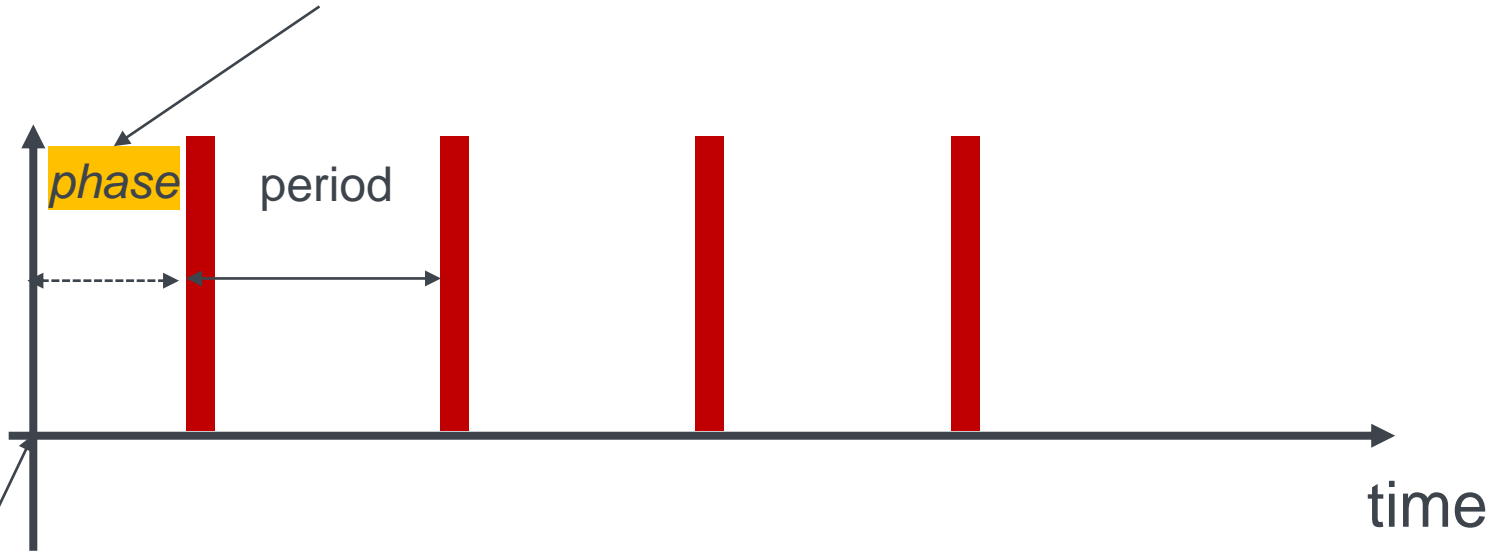


MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Modeling time.

scheduling variable (per edge, per flow),

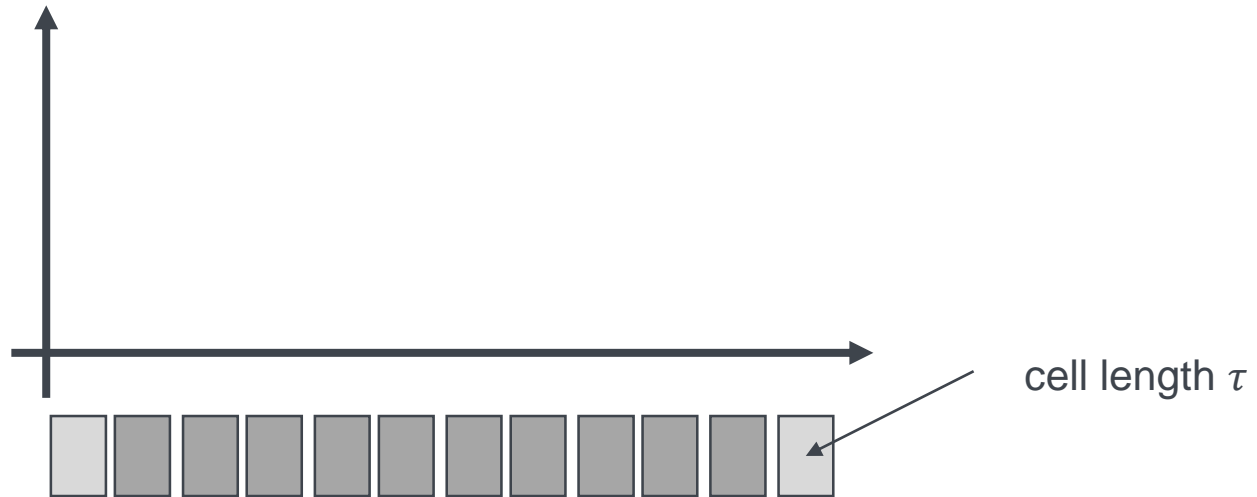
derivation of schedules from phase



global time = 0

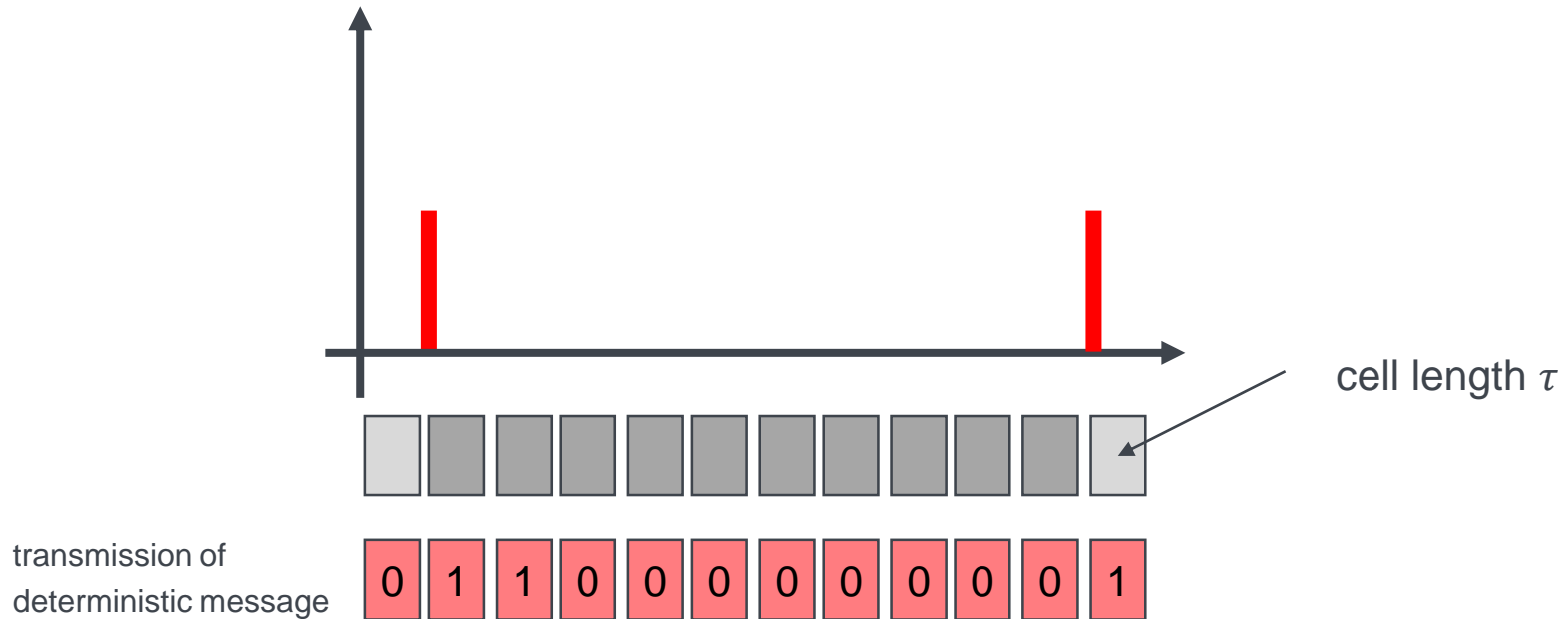
MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Discrete time.



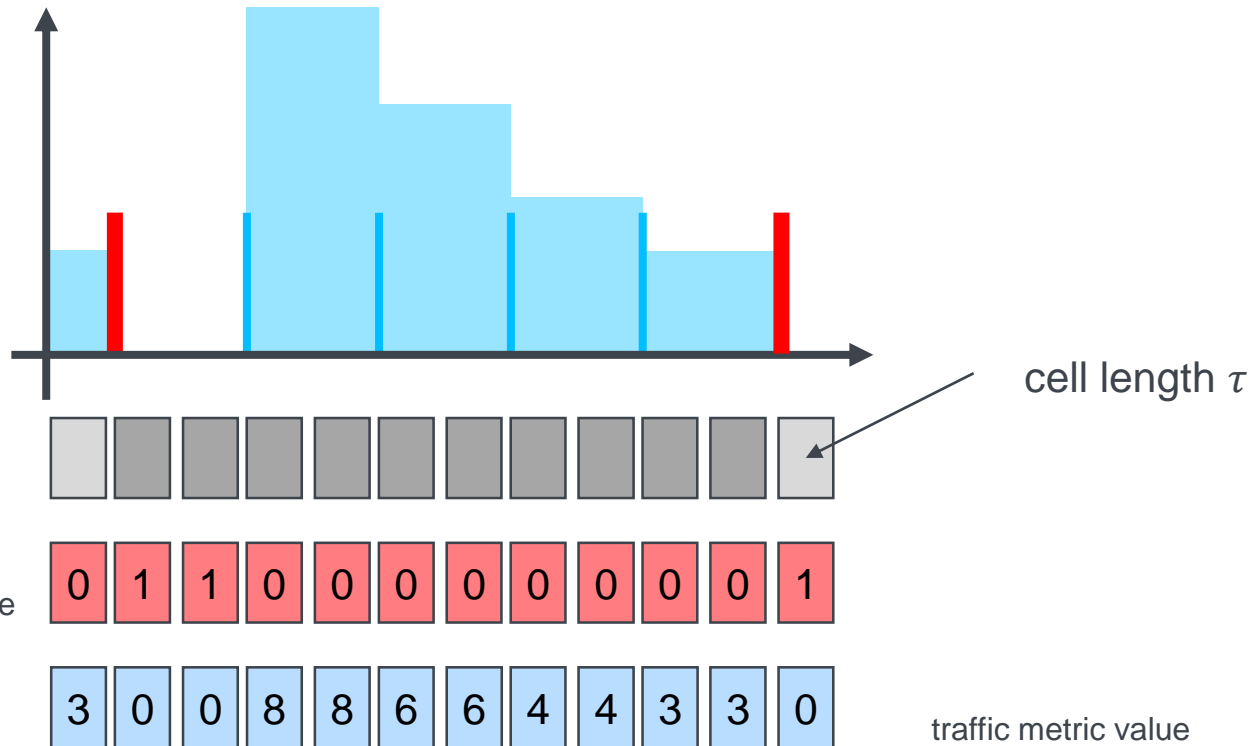
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Discrete time.



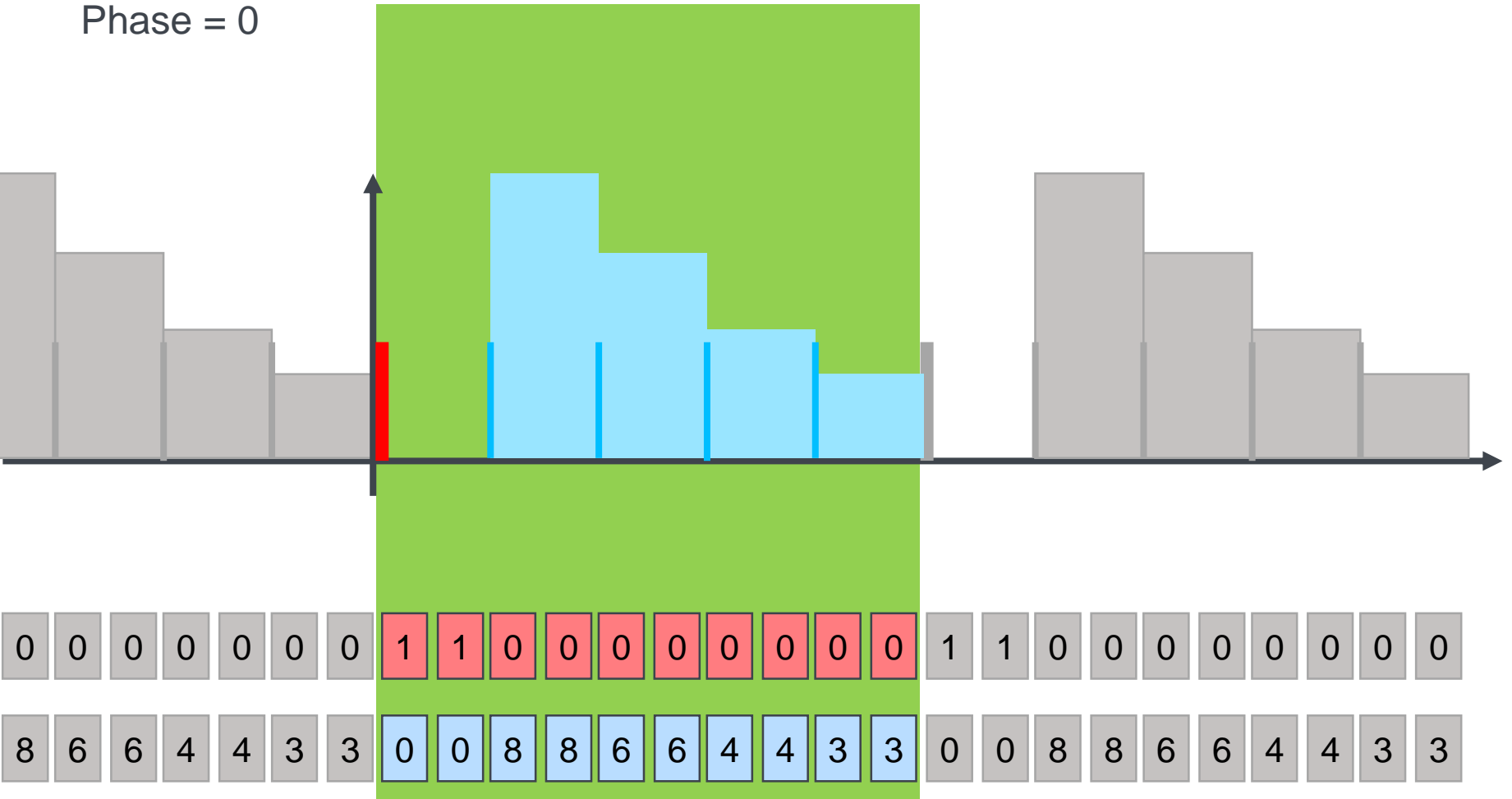
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Discrete time.



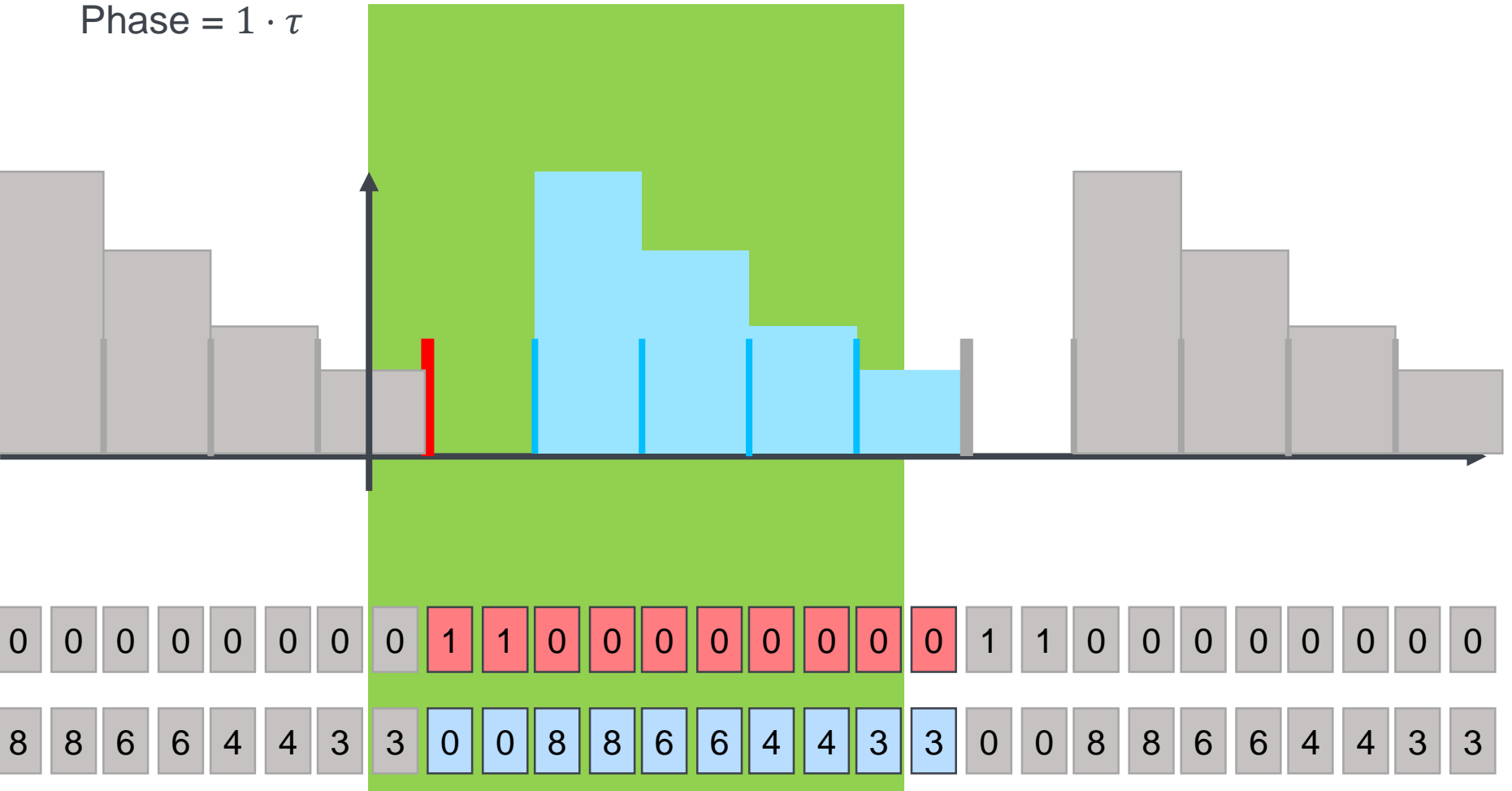
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Phase = 0



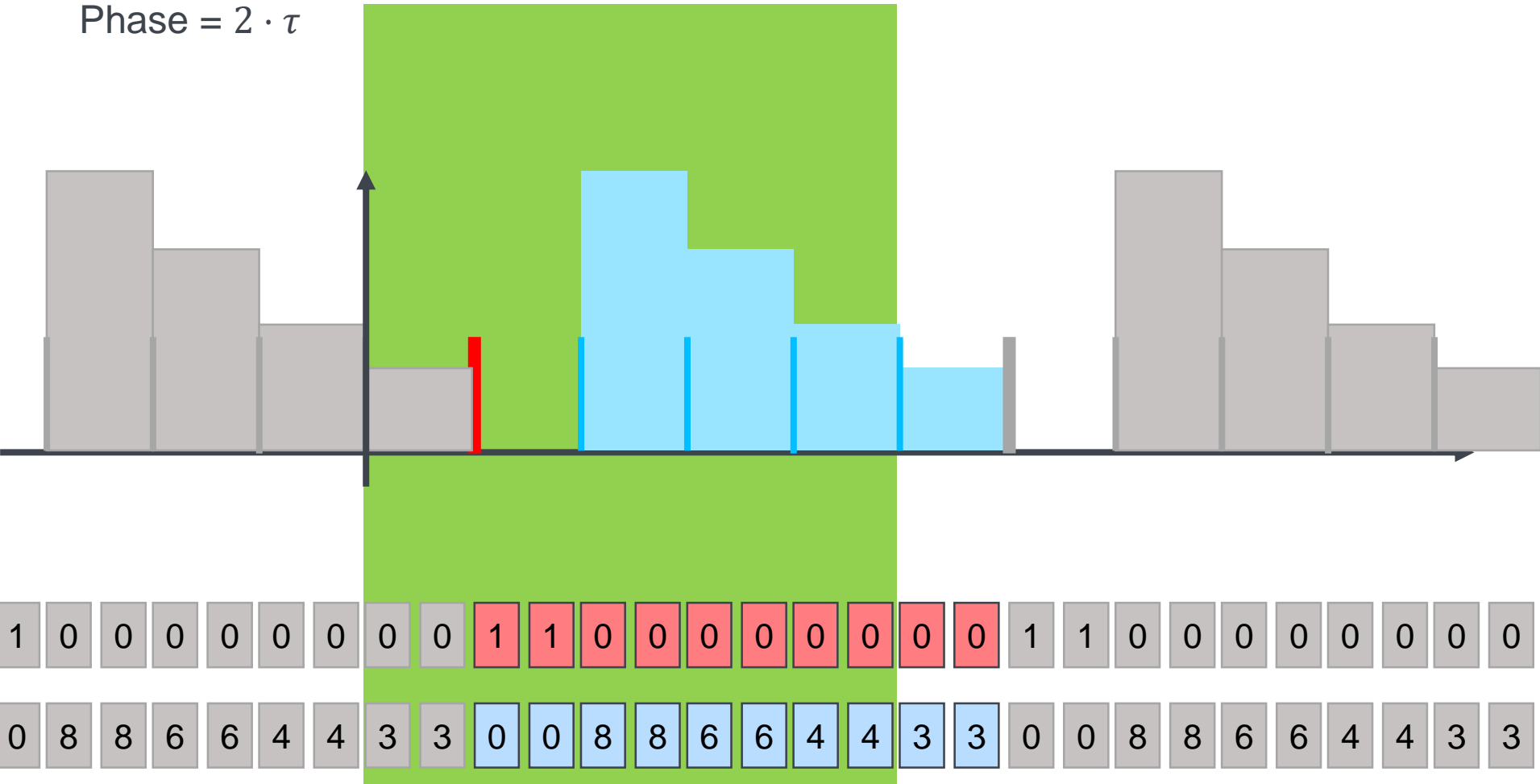
MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Phase = $1 \cdot \tau$



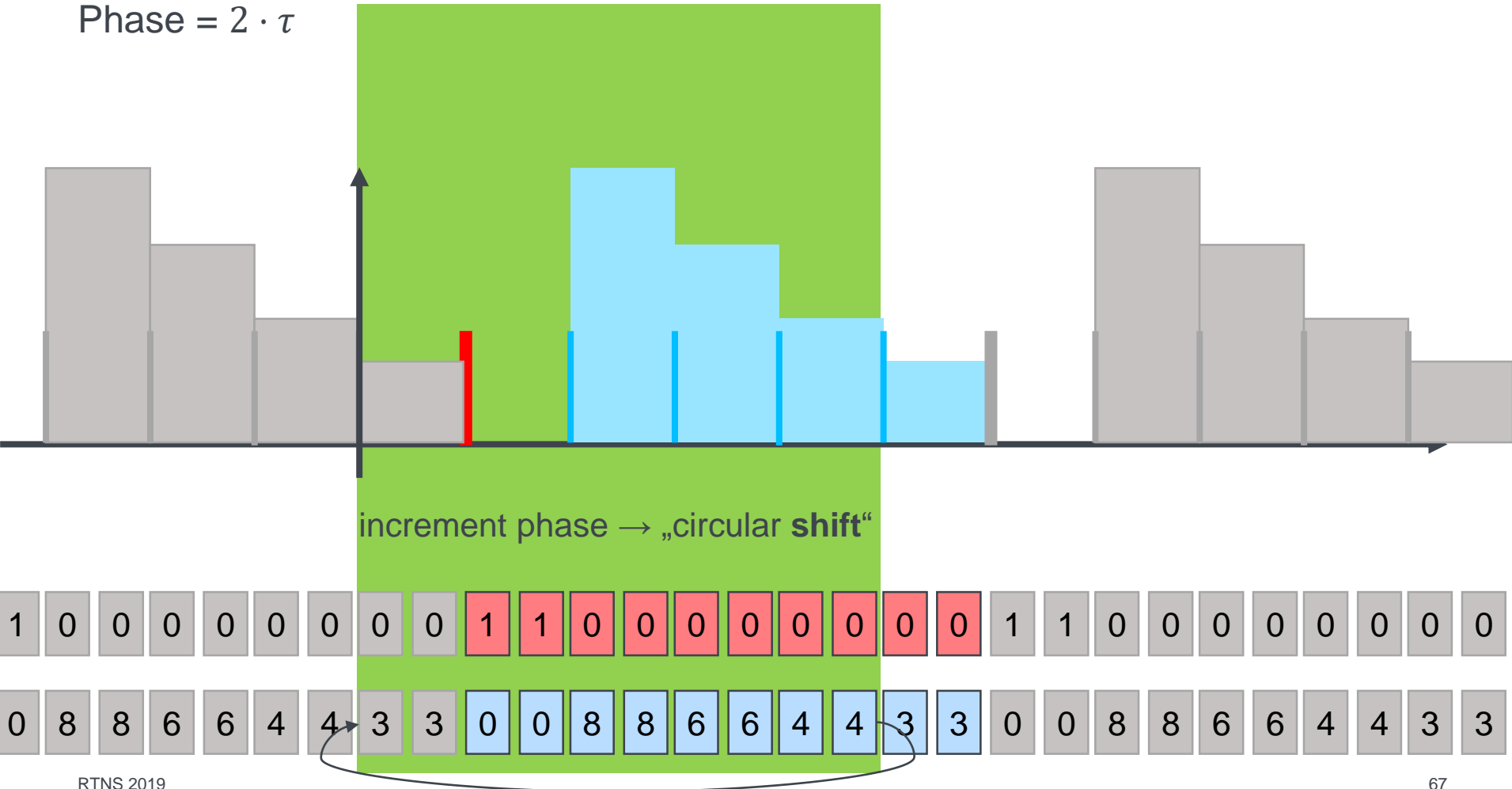
MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Phase = $2 \cdot \tau$



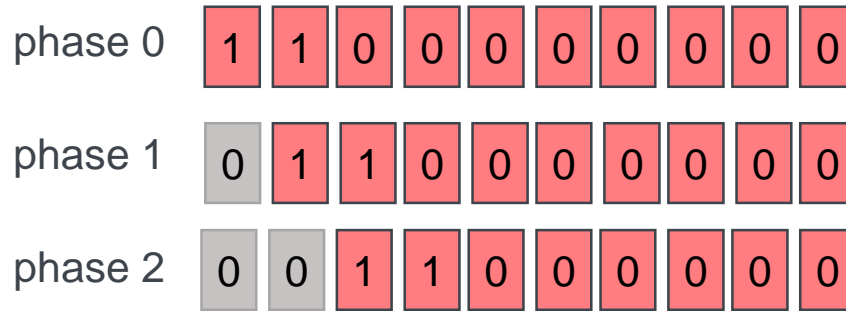
MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Phase = $2 \cdot \tau$



MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Combining the scheduling variable and the cell arrays to model temporal properties.

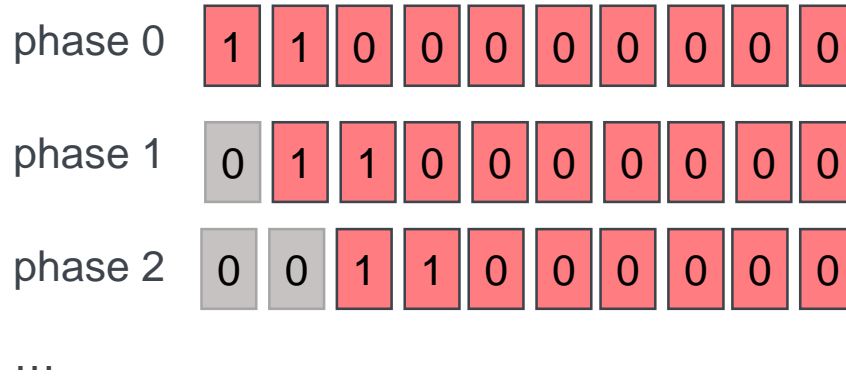


cell matrix

$$\begin{bmatrix} 1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{bmatrix}$$

MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Combining the scheduling variable and the cell arrays to model temporal properties.



cell matrix

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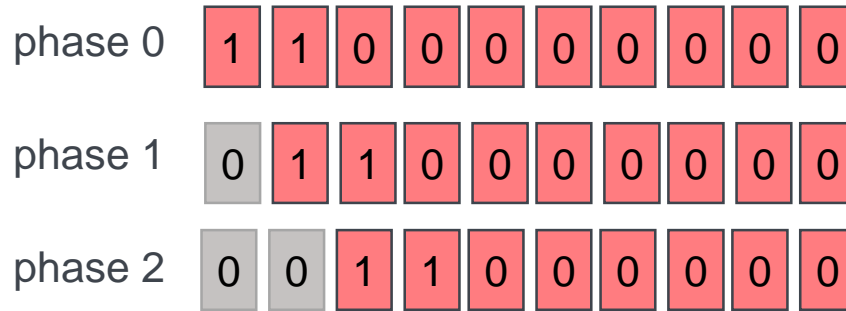
1 in i'th position

↓

$$[0 \ \dots \ 0 \ 1 \ 0 \ \dots \ 0] \cdot \begin{bmatrix} 1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{bmatrix} = \text{i'th row}$$

MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Combining the scheduling variable and the cell arrays to model temporal properties.



cell matrix

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...

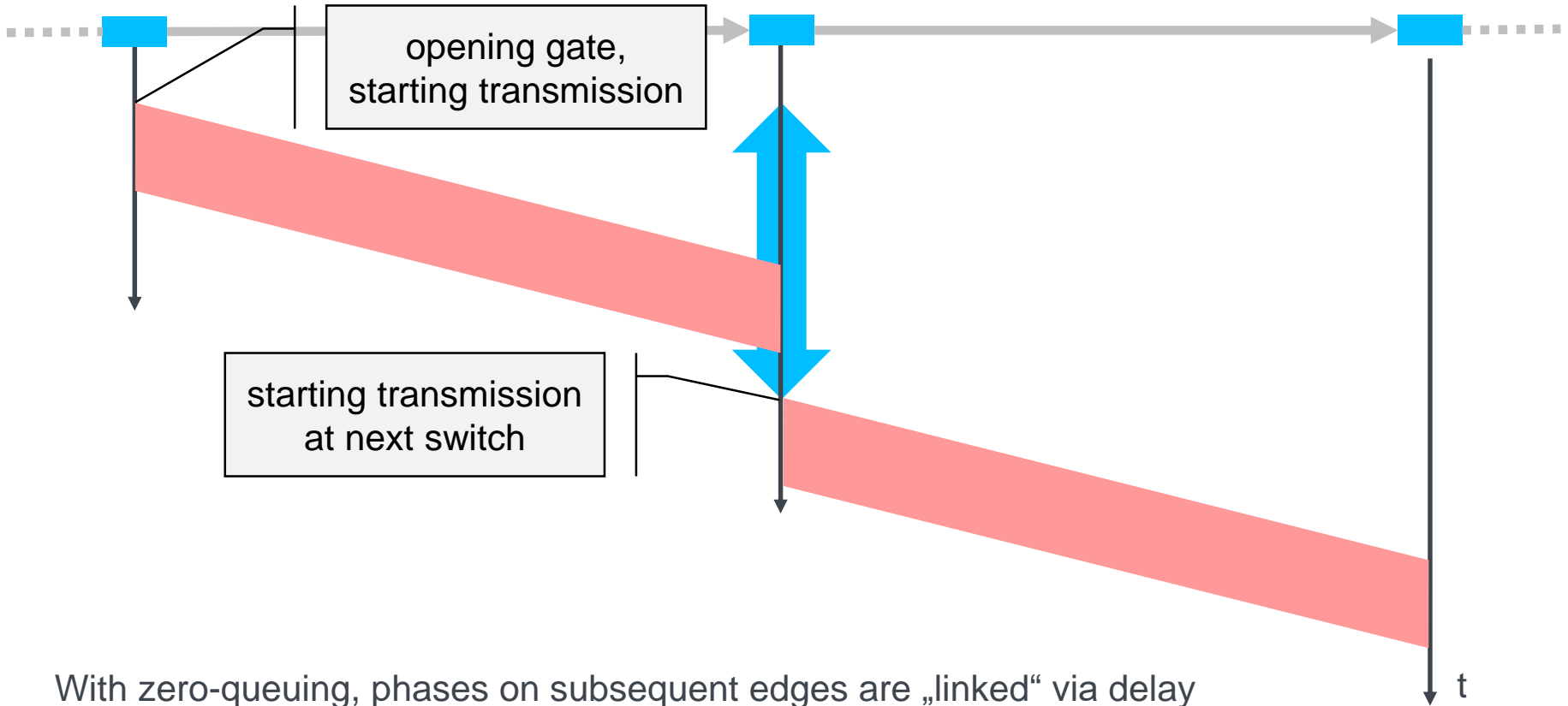
MILP scheduling variables

1 in i'th position

$$[0 \dots 0 \ 1 \ 0 \dots 0] \cdot \begin{bmatrix} 1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{bmatrix} = \text{i'th row}$$

MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

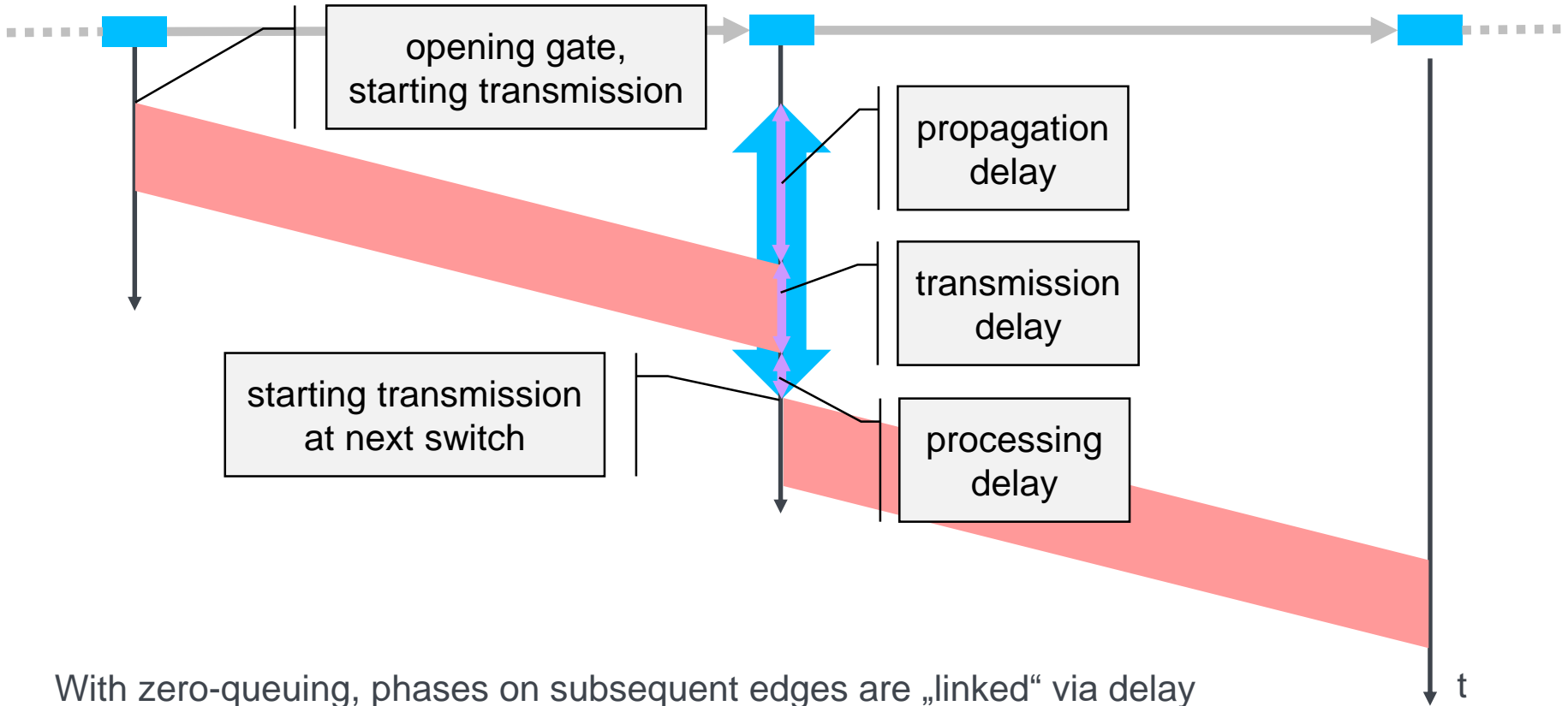
Intraflow scheduling and zero-queuing



With zero-queuing, phases on subsequent edges are „linked“ via delay

MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

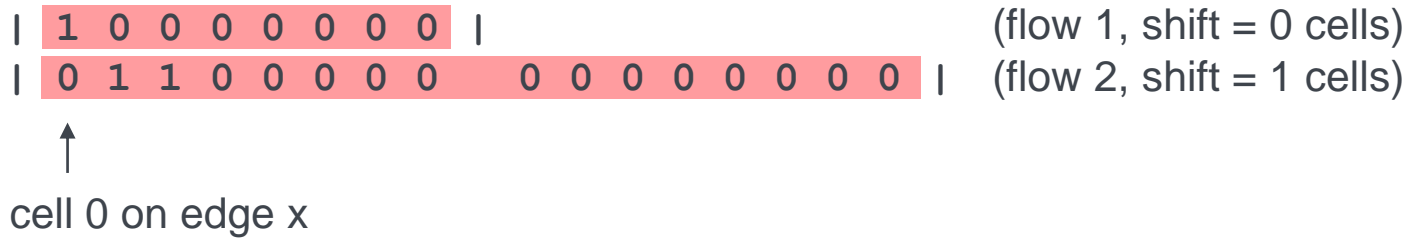
Intraflow scheduling and zero-queuing



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MILP: Path-Granularity Routing and Time-Dependent Traffic Metric

Exemplary constraints: Interflow scheduling and temporal exclusion



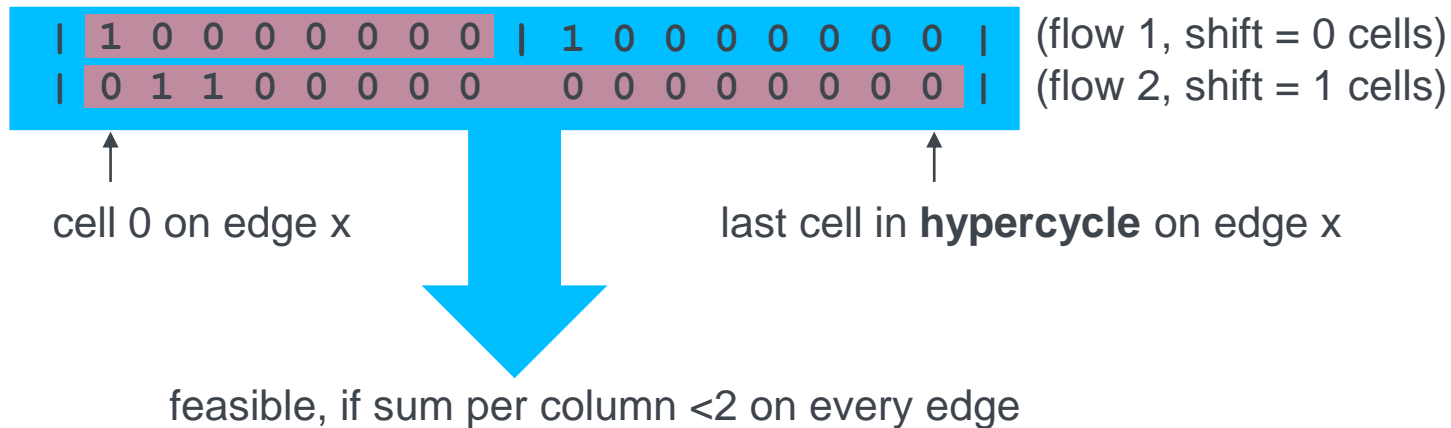
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Exemplary constraints: Interflow scheduling and temporal exclusion



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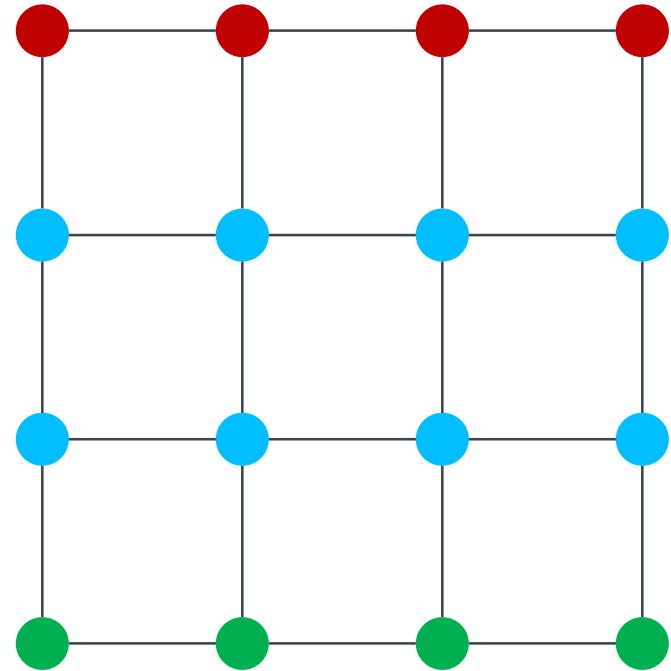
Exemplary constraints: Interflow scheduling and temporal exclusion



Evaluation

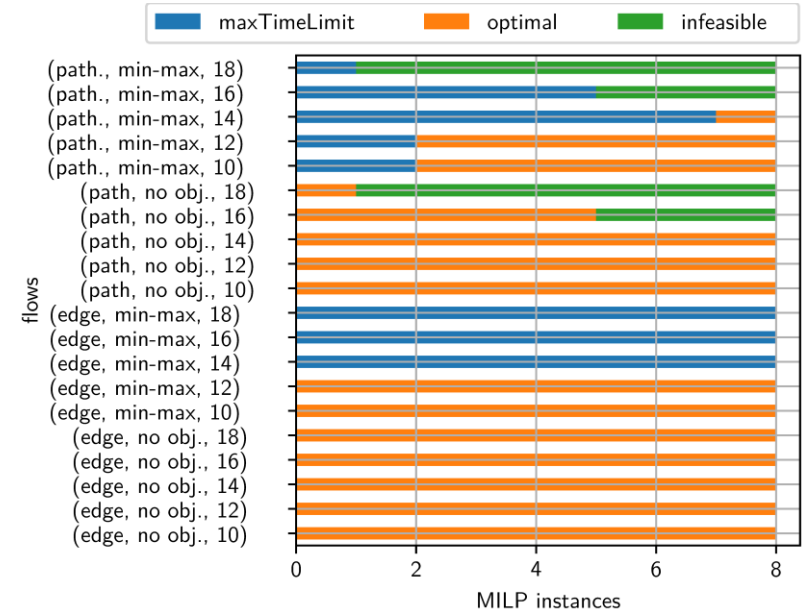
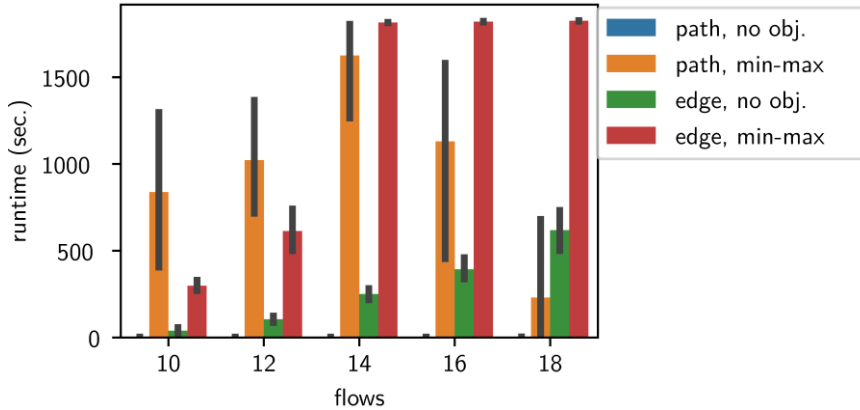
4-way comparison

- edge-gran., min-max
 - edge-gran., no obj.
 - path-gran., min-max
 - path-gran., no obj.
-
- time limit: 30 min
 - container, pyomo + gurobi 8.1.0
 - 4x Intel Xeon E7-4850, 2.1 GHz, 1 TB RAM, Linux 4.19.4



Evaluation

Varying number of flows

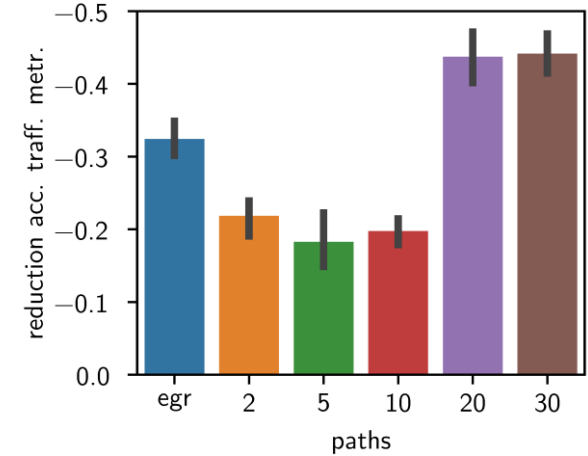
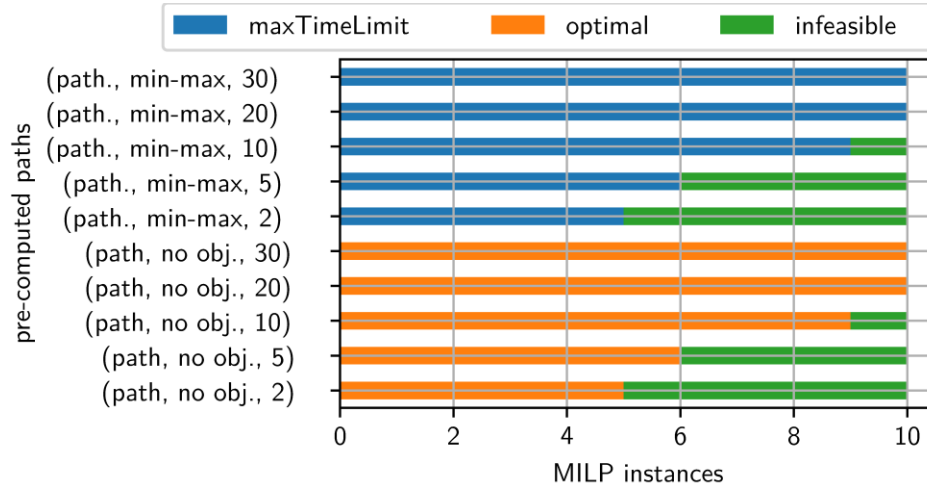


4 precomputed paths for path no obj./min-max

- edge, no obj./min-max yields larger MILP (order of $\sim 10^5$ constraints/variables) compared to path, no obj./min-max (order of $\sim 10^4$ constraints/variables)
- path, min-max reaches runtime limit earlier than edge, min-max (cf. 2 instances at 10 flows)
- infeasibility discovered quickly

Evaluation

Varying number of paths



16 flows

- more paths: increases feasibility and possible improvement, (edge, no obj./min-max always return feasible solution)
- MILP with objective yields improvement over “feasible” schedule

Final remarks

- Complementary flows to improve application performance
- Routing + scheduling of complementary flows

- Different MILP formulations
 - trade-off routing vs. scheduling fidelity

- Open Question
 - Consideration of queuing effects for opportunistic messages?

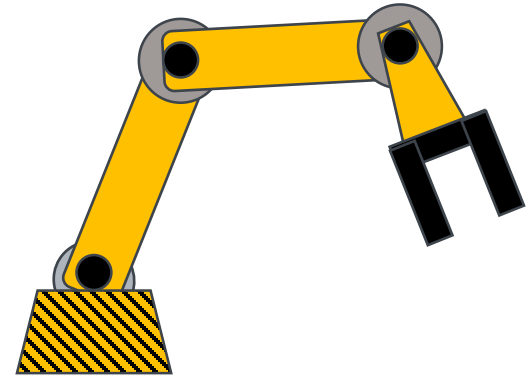
Traffic Engineering

Application

Traffic Engineering

Application

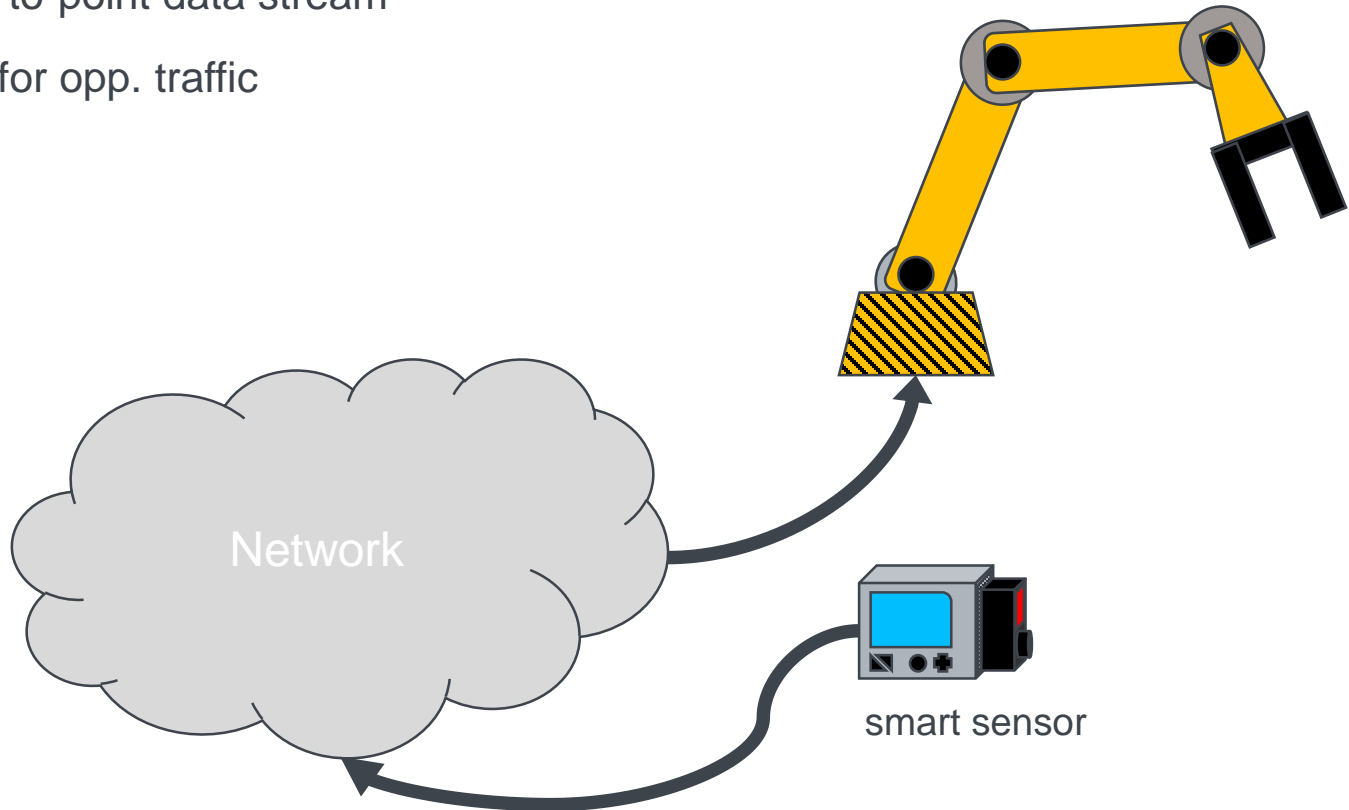
- stationary
- directed, point-to-point data stream
- **traffic metric** for opp. traffic



Traffic Engineering

Application

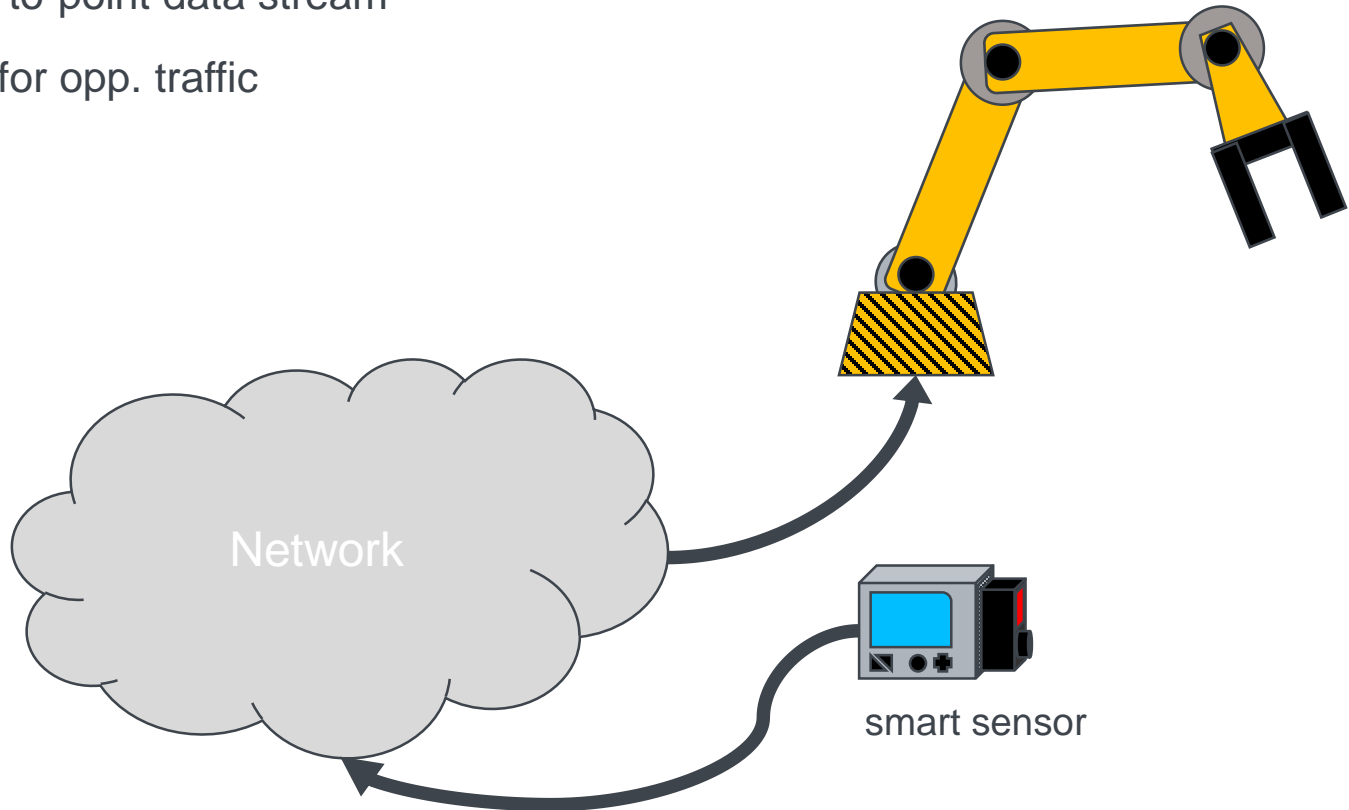
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Traffic Engineering

Application

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Traffic Engineering

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